微分拓扑, 2022 年春季

作业 1

上交时间及方式: 2022.03.18

- 1. Let $X \subset \mathbb{R}^N$, $Y \subset \mathbb{R}^M$ and $Z \subset \mathbb{R}^L$ be arbitrary subsets in certain Euclidean spaces, and let $f: X \to Y$ and $g: Y \to Z$ be smooth maps. Show that the composite $g \circ f: X \to Z$ is smooth, and if f and g are diffeomorphisms, so is $g \circ f$.
- 2. The graph of a map $f: X \to Y$ is the subset of $X \times Y$ defined by

$$graph(f) = \{(x, f(x)) : x \in X\}.$$

Define $F: X \to \operatorname{graph}(f)$ by F(x) = (x, F(x)). Show that if f is smooth, then F is a diffeomorphism.; thus $\operatorname{graph}(f)$ is a manifold if X is.

3. (a) An extremely useful function $f : \mathbb{R}^1 \to \mathbb{R}^1$ is

$$f(x) = \begin{cases} e^{-1/x^2} & x > 0\\ 0 & x \le 0 \end{cases}$$

Prove that f is smooth.

(b) Show that g(x) = f(x-a)f(b-x) is a smooth function, positive on (a, b) and zero elsewhere. (Here a < b.) Then

$$h(x) = \frac{\int_{-\infty}^{x} g(t)}{\int_{-\infty}^{\infty} g(t)}$$

is a smooth function satisfying h(x) = 0 for x < a, h(x) = 1 for x > b, and 0 < h(x) < 1 for $x \in (a, b)$.

- (c) Now construct a smooth function on \mathbb{R}^k that equals 1 on the ball of radius *a* zero outside the ball of radio *b*, and is strictly between 0 and 1 at intermediate points. (Here 0 < a < b.)
- 4. If U is an open subset of the manifold X, check that

$$T_x(U) = T_x(X)$$
 for $x \in U$.

- 5. (a) Let $f: X \to X \times X$ be the mapping f(x) = (x, x). Check that $df_x(v) = (v, v)$.
 - (b) Let $\Delta = \{(x, x) : x \in X\}$ be the diagonal of $X \times X$, show that its tangent space $T_{(x,x)}(\Delta)$ is the diagonal of $T_x(X) \times T_x(X)$.
- 6. (a) Suppose that $f: X \to Y$ is a smooth map, and let $F: X \to Y$ be F(x) = (x, f(x)). Show that $dF_x(v) = (v, df_x(v))$.
 - (b) Prove that the tangent space to graph(f) at the point (x, f(x)) is the graph of $df_x : T_x(X) \to T_{f(x)}(Y)$.
- 7. (a) Let x_1, \dots, x_N be the standard coordinate functions on \mathbb{R}^N , and let X be a k-dimensional submanifold of \mathbb{R}^N . Prove that every point $x \in X$ has a neighborhood on which the restrictions of some k-coordinate functions x_{i_1}, \dots, x_{i_k} form a local coordinate system.
 - (b) For simplicity, assume that x_1, \dots, x_k form a local coordinate system on a neighborhood V of x in X. Show that there are smooth functions g_{k+1}, \dots, g_N on an open set U in \mathbb{R}^K such that V may be taken to be the set

$$\left\{\left(a_1,\cdots,a_k,g_{k+1}(a),\cdots,g_N(a)\right)\in\mathbb{R}^N:a=\left(a_1\cdots,a_k\right)\in U\right\}$$

- 8. If X is compact and Y is connected, show that every submersion $f: X \to Y$ is surjective. Show that there exist no submersions of compact manifolds into Euclidean spaces.
- 9. Verify that the tangent space to O(n) at the identity matrix I is the vector space of skew symmetric $n \times n$ matrices that is, A satisfying $A^t = -A$.

10. Show that the set of $m \times n$ matrices of rank r is a submanifold of \mathbb{R}^{mn} of codimension (m-r)(n-r). (Hint: Suppose, for simplicity, that an $m \times n$ matrix A has the form $A = \begin{pmatrix} B_{r \times r} & C \\ D & E \end{pmatrix}$, where the $r \times r$ matrix B is nonsingular. Postmultiply by the non singular matrix $\begin{pmatrix} I & -B^{-1}C \\ 0 & I \end{pmatrix}$ to prove that rank(A) = r if and only if $E - DB^{-1}C = 0$.)