

Numerical Solutions to Partial Differential Equations

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C ea Lemma — an Abstract Error Estimate Theorem

- 1 Consider the variational problem of the form

$$\begin{cases} \text{Find } u \in \mathbb{V} \text{ such that} \\ a(u, v) = f(v), \quad \forall v \in \mathbb{V}. \end{cases}$$

- 2 Consider the conforming finite element method of the form

$$\begin{cases} \text{Find } u_h \in \mathbb{V}_h \subset \mathbb{V} \text{ such that} \\ a(u_h, v_h) = f(v_h), \quad \forall v_h \in \mathbb{V}_h. \end{cases}$$

- 3 The problem: how to estimate the error $\|u - u_h\|$?
- 4 The method used for FDM is not an ideal framework for FEM.
- 5 The standard approach for the error estimations of a finite element solution is to use an abstract error estimate to reduce the problem to a function approximation problem.



Céa Lemma — an Abstract Error Estimate Theorem

Theorem

Let \mathbb{V} be a Hilbert space, \mathbb{V}_h be a linear subspace of \mathbb{V} . Let the bilinear form $a(\cdot, \cdot)$ and the linear form $f(\cdot)$ satisfy the conditions of the Lax-Milgram lemma (see Theorem 5.1). Let $u \in \mathbb{V}$ be the solution to the variational problem, and $u_h \in \mathbb{V}_h$ satisfy the equation

$$a(u_h, v_h) = f(v_h), \quad \forall v_h \in \mathbb{V}_h.$$

Then, there exist a constant C independent of \mathbb{V}_h , such that

$$\|u - u_h\| \leq C \inf_{v_h \in \mathbb{V}_h} \|u - v_h\|,$$

where $\|\cdot\|$ is the norm of \mathbb{V} .



Proof of the C ea Lemma

① Since u and u_h satisfy the equations, and $\mathbb{V}_h \subset \mathbb{V}$, we have $a(u - u_h, w_h) = a(u, w_h) - a(u_h, w_h) = f(w_h) - f(w_h) = 0, \quad \forall w_h \in \mathbb{V}_h.$

② In particular, taking $w_h = u_h - v_h$ leads to

$$a(u - u_h, u_h - v_h) = 0.$$

③ The \mathbb{V} -ellipticity $\Rightarrow \alpha \|u - u_h\|^2 \leq a(u - u_h, u - u_h).$

④ The boundedness $\Rightarrow a(u - u_h, u - v_h) \leq M \|u - u_h\| \|u - v_h\|.$

⑤ Hence, $\alpha \|u - u_h\|^2 \leq a(u - u_h, u - v_h) \leq M \|u - u_h\| \|u - v_h\|.$

⑥ Take $C = M/\alpha$, we have

$$\|u - u_h\| \leq C \|u - v_h\|, \quad \forall v_h \in \mathbb{V}_h.$$

⑦ The conclusion of the theorem follows. ■



Remarks on the C ea Lemma

- 1 The C ea lemma reduces the error estimation problem of $\|u - u_h\|$ to the optimal approximation problem of $\inf_{v_h \in \mathbb{V}_h} \|u - v_h\|$.
- 2 Error of the finite element solution $\|u - u_h\|$ is of the same order as the optimal approximation error $\inf_{v_h \in \mathbb{V}_h} \|u - v_h\|$.
- 3 Suppose the \mathbb{V}_h -interpolation function $\Pi_h u$ of u is well defined in the finite element function space \mathbb{V}_h , then,
$$\|u - u_h\| \leq C \inf_{v_h \in \mathbb{V}_h} \|u - v_h\| \leq C \|u - \Pi_h u\|.$$
- 4 Therefore, the error estimation problem of $\|u - u_h\|$ can be further reduced to the error estimation problem for the \mathbb{V}_h -interpolation error $\|u - \Pi_h u\|$.



For Symmetric $a(\cdot, \cdot)$, u_h Is a Orthogonal Projection of u on \mathbb{V}_h

- 1 If the \mathbb{V} -elliptic bounded bilinear form $a(\cdot, \cdot)$ is symmetric, then, $a(\cdot, \cdot)$ defines an inner product on \mathbb{V} , with the induced norm equivalent to the \mathbb{V} -norm.
- 2 Denote $\mathbf{P}_h : \mathbb{V} \rightarrow \mathbb{V}_h$ as the orthogonal projection operator induced by the inner product $a(\cdot, \cdot)$. Then,

$$a(u - \mathbf{P}_h u, v_h) = 0, \quad \forall v_h \in \mathbb{V}_h.$$

- 3 Therefore, the finite element solution $u_h = \mathbf{P}_h u$, *i.e.* it is the orthogonal projection of u on \mathbb{V}_h with respect to the inner product $a(\cdot, \cdot)$.



C ea Lemma for Symmetric $a(\cdot, \cdot)$

Corollary

Under the conditions of the C ea Lemma, if the bilinear form $a(\cdot, \cdot)$ is in addition symmetric, then, the solution u_h is the orthogonal projection, which is induced by the inner product $a(\cdot, \cdot)$, of the solution u on the subspace \mathbb{V}_h , meaning $u_h = \mathbf{P}_h u$.

Furthermore, we have

$$a(u - u_h, u - u_h) = \inf_{v_h \in \mathbb{V}_h} a(u - v_h, u - v_h).$$

The proof follows the same lines as the proof of the C ea lemma. The only difference here is that $\alpha = M = 1$.



C ea Lemma in the Form of Orthogonal Projection Error Estimate

Denote $\tilde{P}_h : \mathbb{V} \rightarrow \mathbb{V}_h$ as the orthogonal projection operator induced by the inner product $(\cdot, \cdot)_{\mathbb{V}}$ of \mathbb{V} , then,

$$\|u - \tilde{P}_h u\| = \|(I - \tilde{P}_h)u\| = \inf_{v_h \in \mathbb{V}_h} \|u - v_h\|.$$

Therefore, as a corollary of the C ea lemma, we have

Corollary

Let \mathbb{V} be a Hilbert space, and \mathbb{V}_h be a linear subspace of \mathbb{V} . Let $a(\cdot, \cdot)$ be a symmetric bilinear form on \mathbb{V} satisfying the conditions of the Lax-Milgram lemma. Let P_h and \tilde{P}_h be the orthogonal projection operators from \mathbb{V} to \mathbb{V}_h induced by the inner products $a(\cdot, \cdot)$ and $(\cdot, \cdot)_{\mathbb{V}}$ respectively. Then, we have

$$\|I - \tilde{P}_h\| \leq \|I - P_h\| \leq \frac{M}{\alpha} \|I - \tilde{P}_h\|.$$



1-D Example on Linear Interpolation Error Estimation for \mathbb{H}^2 Functions

- 1 $\hat{\Omega} = (0, 1)$, $\Omega = (b, b + h)$, $h > 0$.
- 2 $F : \hat{x} \in [0, 1] \rightarrow [b, b + h]$, $F(\hat{x}) = h\hat{x} + b$: an invertible affine mapping from $\overline{\hat{\Omega}}$ to $\overline{\Omega}$.
- 3 $\hat{\Pi} : \mathbb{C}([0, 1]) \rightarrow \mathbb{P}_1([0, 1])$: the interpolation operator with $\hat{\Pi}\hat{v}(0) = \hat{v}(0)$, $\hat{\Pi}\hat{v}(1) = \hat{v}(1)$.
- 4 $\Pi : \mathbb{C}([b, b + h]) \rightarrow \mathbb{P}_1([b, b + h])$: the interpolation operator with $\Pi v(b) = v(b)$, $\Pi v(b + h) = v(b + h)$.



1-D Example on Linear Interpolation Error Estimation for \mathbb{H}^2 Functions

⑤ Let $u \in \mathbb{H}^2(\Omega)$, denote $\hat{u}(\hat{x}) = u \circ F(\hat{x}) = u(h\hat{x} + b)$, then, it can be shown $\hat{u} \in \mathbb{H}^2(\hat{\Omega})$, thus, $\hat{u} \in \mathbb{C}([0, 1])$.

⑥ $\hat{\Pi}$ is $\mathbb{P}_1([0, 1])$ **invariant**: $\hat{\Pi}\hat{w} = \hat{w}$, $\forall \hat{w} \in \mathbb{P}_1([0, 1])$, thus,

$$\|(I - \hat{\Pi})\hat{u}\|_{0,\hat{\Omega}} = \|(I - \hat{\Pi})(\hat{u} + \hat{w})\|_{0,\hat{\Omega}} \leq \|I - \hat{\Pi}\| \|\hat{u} + \hat{w}\|_{2,\hat{\Omega}},$$

where $\|I - \hat{\Pi}\|$ is the norm of $I - \hat{\Pi} : \mathbb{H}^2(\hat{\Omega}) \rightarrow \mathbb{L}^2(\hat{\Omega})$.

★ This shows that $I - \hat{\Pi} \in \mathcal{L}(\mathbb{H}^2(0, 1)/\mathbb{P}_1([0, 1]); \mathbb{L}^2(0, 1))$, and

$$(1) \quad \|\hat{u} - \hat{\Pi}\hat{u}\|_{0,\hat{\Omega}} \leq \|I - \hat{\Pi}\| \inf_{\hat{w} \in \mathbb{P}_1(\hat{\Omega})} \|\hat{u} + \hat{w}\|_{2,\hat{\Omega}},$$

where $\inf_{\hat{w} \in \mathbb{P}_1(\hat{\Omega})} \|\hat{u} + \hat{w}\|_{2,\hat{\Omega}}$ is the norm of \hat{u} in the quotient space $\mathbb{H}^2(0, 1)/\mathbb{P}_1([0, 1])$.



1-D Example on Linear Interpolation Error Estimation for \mathbb{H}^2 Functions

★ It can be shown that, \exists const. $C(\hat{\Omega}) > 0$ s.t.

$$(2) \quad |\hat{u}|_{2,\hat{\Omega}} \leq \inf_{\hat{w} \in \mathbb{P}_1(\hat{\Omega})} \|\hat{u} + \hat{w}\|_{2,\hat{\Omega}} \leq C(\hat{\Omega})|\hat{u}|_{2,\hat{\Omega}}.$$

★ It follows from the chain rule that $\hat{u}''(\hat{x}) = h^2 u''(x)$.

★ By a change of the integral variable, and $dx = h d\hat{x}$, we obtain

$$(3) \quad \hat{u} \in \mathbb{H}^2(\hat{\Omega}), \text{ and } |\hat{u}|_{2,\hat{\Omega}}^2 = h^3 |u|_{2,\Omega}^2;$$

$$(4) \quad \|u - \Pi u\|_{0,\Omega}^2 = h \|\hat{u} - \hat{\Pi} \hat{u}\|_{0,\hat{\Omega}}^2.$$



1-D Example on Linear Interpolation Error Estimation for \mathbb{H}^2 Functions

- The conclusion (1) says that the \mathbb{L}^2 norm of the error of a \mathbb{P}_1 invariant interpolation can be bounded by the quotient norm of the function in $\mathbb{H}^2(0, 1)/\mathbb{P}_1([0, 1])$.
- The conclusion (2) says that the semi norm $|\cdot|_{2,(0,1)}$ is an equivalent norm of the quotient space $\mathbb{H}^2(0, 1)/\mathbb{P}_1([0, 1])$.
- The conclusions (3) and (4) present the relations between the semi-norms of Sobolev spaces defined on affine-equivalent open sets.



1-D Example on Linear Interpolation Error Estimation for \mathbb{H}^2 Functions

★ The combination of (4) and (1) yields

$$\|u - \Pi u\|_{0,\Omega} \leq h^{\frac{1}{2}} \|I - \hat{\Pi}\| \inf_{\hat{w} \in \mathbb{P}_1(\hat{\Omega})} \|\hat{u} + \hat{w}\|_{2,\hat{\Omega}}$$

★ This together with (2) and (3) lead to the expected interpolation error estimate:

$$\|u - \Pi u\|_{0,\Omega} \leq \|I - \hat{\Pi}\| C(\hat{\Omega}) |u|_{2,\Omega} h^2, \quad \forall u \in \mathbb{H}^2(\Omega).$$



A Framework for Interpolation Error Estimation of Affine Equivalent FEs

- 1 The polynomial quotient spaces of a Sobolev space and their equivalent quotient norms ((2) in the example);
- 2 The relations between the semi-norms of Sobolev spaces defined on affine-equivalent open sets ((3), (4) in the example);
- 3 The abstract error estimates for the polynomial invariant operators ((1) in the example);
- 4 To estimate the constants appeared in the relations of the Sobolev semi-norms by means of the geometric parameters of the corresponding affine-equivalent open sets.



A Framework for Interpolation Error Estimation of Affine Equivalent FEs

- the change of integral variable will introduce the Jacobi determinant $\det \left(\frac{\partial F(\hat{x})}{\partial \hat{x}} \right)$;
- in high dimensions, the Jacobi determinant represents the ratio of the volumes $|\Omega|/|\hat{\Omega}|$;
- the chain rule for the m th derivative will produce h^m .
- h actually represents the ratio of the lengths in the directions of corresponding directional derivatives of the regions $\Omega = F(\hat{\Omega})$ and $\hat{\Omega}$.

The related technique is often referred to as the scaling technique.



Polynomial Quotient Spaces

- ① The quotient space $\mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega)$, in which a function \dot{v} is the equivalent class of $v \in \mathbb{W}^{k+1,p}(\Omega)$ in the sense that

$$\dot{v} = \{w \in \mathbb{W}^{k+1,p}(\Omega) : (w - v) \in \mathbb{P}_k(\Omega)\}.$$

- ② The quotient norm of a function \dot{v} is defined by

$$\dot{v} \in \mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega) \rightarrow \|\dot{v}\|_{k+1,p,\Omega} := \inf_{w \in \mathbb{P}_k(\Omega)} \|v+w\|_{k+1,p,\Omega}.$$



Polynomial Quotient Spaces

- ③ The quotient space $\mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega)$ is a Banach space.
- ④ $\dot{v} \in \mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega) \rightarrow |\dot{v}|_{k+1,p,\Omega} = |v|_{k+1,p,\Omega}$ is a semi-norm of the quotient space $\mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega)$, and obviously $|\dot{v}|_{k+1,p,\Omega} \leq \|\dot{v}\|_{k+1,p,\Omega}$.
- ⑤ In fact, $|\dot{v}|_{k+1,p,\Omega} = |v|_{k+1,p,\Omega}$ is an equivalent norm of the quotient space $\mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega)$.



The Semi-norm $|\dot{v}|_{k+1,p,\Omega}$ Is an equivalent Norm of $\mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega)$

Theorem

There exists a constant $C(\Omega)$ such that

$$\|\dot{v}\|_{k+1,p,\Omega} \leq C(\Omega) |\dot{v}|_{k+1,p,\Omega}, \quad \forall \dot{v} \in \mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega).$$

Proof:

- ① Let $\{p_i\}_{i=1}^N$ be a basis of $\mathbb{P}_k(\Omega)$, and let f_i , $i = 1, \dots, N$, be the corresponding dual basis, meaning $f_i(p_j) = \delta_{ij}$.
- ② For any $w \in \mathbb{P}_k(\Omega)$, $f_i(w) = 0$, $i = 1, \dots, N \iff w = 0$.
- ③ Extend f_i , $i = 1, \dots, N$, to a set of bounded linear functionals defined on $\mathbb{W}^{k+1,p}(\Omega)$.



The Semi-norm $|v|_{k+1,p,\Omega}$ Is an equivalent Norm of $\mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega)$

- ④ We claim that there exists a constant $C(\Omega)$ such that $\|v\|_{k+1,p,\Omega} \leq C(\Omega)(|v|_{k+1,p,\Omega} + \sum_{i=1}^N |f_i(v)|)$, $\forall v \in \mathbb{W}^{k+1,p}(\Omega)$.
- ⑤ For $v \in \mathbb{W}^{k+1,p}(\Omega)$, define $\tilde{w} = -\sum_{j=1}^N f_j(v)p_j$, then, $f_i(v + \tilde{w}) = 0$, $i = 1, \dots, N$, consequently, $\inf_{w \in \mathbb{P}_k(\Omega)} \|v + w\|_{k+1,p,\Omega} \leq \|v + \tilde{w}\|_{k+1,p,\Omega} \leq C(\Omega)|v|_{k+1,p,\Omega}$.

What remains to show is ④. Suppose ④ doesn't hold.

- ⑥ Then, there exists a sequence $\{v_j\}_{j=1}^\infty$ in $\mathbb{W}^{k+1,p}(\Omega)$ such that $\|v_j\|_{k+1,p,\Omega} = 1$, $\forall j \geq 1$ and $\lim_{j \rightarrow \infty} (|v_j|_{k+1,p,\Omega} + \sum_{i=1}^N |f_i(v_j)|) = 0$.
- ⑦ $\mathbb{W}^{k+1,p}(\Omega) \xrightarrow{c} \mathbb{W}^{k,p}(\Omega)$, $1 \leq p < \infty$; $\mathbb{W}^{k+1,\infty}(\Omega) \xrightarrow{c} \mathbb{C}^k(\bar{\Omega})$.

The Semi-norm $|v|_{k+1,p,\Omega}$ Is an equivalent Norm of $\mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega)$

- ⑧ So, there exist a subsequence of $\{v_j\}_{j=1}^{\infty}$, denoted again as $\{v_j\}_{j=1}^{\infty}$, and a function $v \in \mathbb{W}^{k,p}(\Omega)$, such that

$$\lim_{j \rightarrow \infty} \|v_j - v\|_{k,p,\Omega} = 0.$$

- ⑨ ⑥ and ⑧ imply $\{v_j\}_{j=1}^{\infty}$ is a Cauchy sequence in $\mathbb{W}^{k+1,p}(\Omega)$.

- ⑩ Therefore, v in ⑧ is actually a function in $\mathbb{W}^{k+1,p}(\Omega)$.

- ⑪ Thus, it follows from ⑥ that

$$|\partial^\alpha v|_{0,p,\Omega} = \lim_{j \rightarrow \infty} |\partial^\alpha v_j|_{0,p,\Omega} = 0, \quad \forall \alpha, \quad |\alpha| = k + 1,$$



The Semi-norm $|v|_{k+1,p,\Omega}$ Is an equivalent Norm of $\mathbb{W}^{k+1,p}(\Omega)/\mathbb{P}_k(\Omega)$

⑫ By Theorem 5.2, ⑪ implies $v \in \mathbb{P}_k(\Omega)$.

⑬ On the other hand, it follows from ⑥ that

$$f_i(v) = \lim_{j \rightarrow \infty} f_i(v_j) = 0, \quad i = 1, \dots, N,$$

⑭ Therefore, by ②, we have $v = 0$.

⑮ On the other hand, since v_j converges to v in $\mathbb{W}^{k+1,p}(\Omega)$, by ⑥, we have $\|v\|_{k+1,p,\Omega} = \lim_{j \rightarrow \infty} \|v_j\|_{k+1,p,\Omega} = 1$.

⑯ The contradiction of ⑭ and ⑮ completes the proof. ■



Relations of Semi-norms on Open Sets Related by $F(\hat{x}) = h\hat{x} + b \in \mathbb{R}^n$

- ① Let $F : \hat{x} \in \mathbb{R}^n \rightarrow F(\hat{x}) = h\hat{x} + b \in \mathbb{R}^n$, and $\Omega = F(\hat{\Omega})$,
 $\Rightarrow \text{diam}(\Omega)/\text{diam}(\hat{\Omega}) = h$ and $\|\frac{\partial F(\hat{x})}{\partial \hat{x}}\| = h$.
- ② Then, $\partial^\alpha v(x) = h^{-|\alpha|} \partial^\alpha \hat{v}(\hat{x})$, and $dx = |\det(B)| d\hat{x} = h^n d\hat{x}$,
 (where $B = \frac{\partial F(\hat{x})}{\partial \hat{x}} = h I_{n \times n}$).

- ③ Therefore, by a change of integral variable, we have

$$|v|_{m,p,\Omega} = \|B^{-1}\|^m |\det(B)|^{1/p} |\hat{v}|_{m,p,\hat{\Omega}} = h^{-m+n/p} |\hat{v}|_{m,p,\hat{\Omega}}.$$

- ④ $|v|_{m,p,\Omega} / |\hat{v}|_{m,p,\hat{\Omega}} \propto \|B^{-1}\|^m |\det(B)|^{1/p} = h^{-m+n/p}$.



Affine Equivalent Open Sets Related by $F(\hat{x}) = B\hat{x} + b \in \mathbb{R}^n$

Let $\Omega = F(\hat{\Omega})$ be an affine equivalent open set in \mathbb{R}^n with

$$F : \hat{x} \in \mathbb{R}^n \rightarrow F(\hat{x}) = B\hat{x} + b \in \mathbb{R}^n,$$

For $v \in \mathbb{W}^{m,p}(\Omega)$ and $\hat{v}(\hat{x}) = v(F(\hat{x}))$, the Sobolev semi-norms $|v|_{m,p,\Omega}$ and $|\hat{v}|_{m,p,\hat{\Omega}}$ have a similar relation for general B , *i.e.*

$$|v|_{m,p,\Omega} / |\hat{v}|_{m,p,\hat{\Omega}} \propto \|B^{-1}\|^m |\det(B)|^{1/p} \propto h^{-m+n/p},$$

provided $F(\hat{x})$ satisfies certain regularity conditions.



Relations of Semi-norms on Open Sets Related by $F(\hat{x}) = B\hat{x} + b$

Theorem

Let Ω and $\hat{\Omega}$ be two affine equivalent open sets in \mathbb{R}^n . Let $v \in \mathbb{W}^{m,p}(\Omega)$ for some $p \in [1, \infty]$ and nonnegative integer m . Then, $\hat{v} = v \circ F \in \mathbb{W}^{m,p}(\hat{\Omega})$, and there exists a constant $C = C(m, n)$ such that

$$|\hat{v}|_{m,p,\hat{\Omega}} \leq C \|B\|^m |\det(B)|^{-1/p} |v|_{m,p,\Omega},$$

where B is the matrix in the affine mapping F , $\|\cdot\|$ represents the operator norms induced from the Euclidian norm of \mathbb{R}^n . Similarly, we also have

$$|v|_{m,p,\Omega} \leq C \|B^{-1}\|^m |\det(B)|^{1/p} |\hat{v}|_{m,p,\hat{\Omega}}.$$



Proof of $|\hat{v}|_{m,p,\hat{\Omega}} \leq C(n, m) \|B\|^m |\det(B)|^{-1/p} |v|_{m,p,\Omega}$

① Let $\xi_i = (\xi_{i1}, \dots, \xi_{in})^T \in \mathbb{R}^n$, $i = 1, \dots, m$, be unit vectors, $D = (\partial_1, \dots, \partial_n)$, $D^m \hat{v}(\hat{x})(\xi_1, \dots, \xi_m) = (\prod_{i=1}^m D \cdot \xi_i) \hat{v}(\hat{x})$.

② Assume $v \in \mathbb{C}^m(\bar{\Omega})$, therefore, $\hat{v} \in \mathbb{C}^m(\bar{\hat{\Omega}})$ also. We have

$$|\partial^\alpha \hat{v}(\hat{x})| \leq \|D^m \hat{v}(\hat{x})\| := \sup_{\substack{\|\xi_i\|=1 \\ 1 \leq i \leq m}} |D^m \hat{v}(\hat{x})(\xi_1, \dots, \xi_m)|, \quad \forall |\alpha| = m.$$

③ Let $C_1(m, n)$ be the cardinal number of α , then

$$|\hat{v}|_{m,p,\hat{\Omega}} = \left(\int_{\hat{\Omega}} \sum_{|\alpha|=m} |\partial^\alpha \hat{v}(\hat{x})|^p d\hat{x} \right)^{1/p} \leq C_1(m, n) \left(\int_{\hat{\Omega}} \|D^m \hat{v}(\hat{x})\|^p d\hat{x} \right)^{1/p}.$$



Proof of $|\hat{v}|_{m,p,\hat{\Omega}} \leq C(n, m) \|B\|^m |\det(B)|^{-1/p} |v|_{m,p,\Omega}$

- ④ On the other hand, by the chain rule of differentiations for composition of functions,

$$(D \cdot \xi) \hat{v}(\hat{x}) = D(v \circ F(\hat{x})) \xi = Dv(x) \frac{\partial F(\hat{x})}{\partial \hat{x}} \xi = (D \cdot B\xi)v(x).$$

- ⑤ Therefore, $(\prod_{i=1}^m D \cdot \xi_i) \hat{v}(\hat{x}) = (\prod_{i=1}^m D \cdot B\xi_i) v(x)$, i.e.

$$D^m \hat{v}(\hat{x})(\xi_1, \dots, \xi_m) = D^m v(x)(B\xi_1, \dots, B\xi_m).$$

- ⑥ Consequently, $\|D^m \hat{v}(\hat{x})\| \leq \|B\|^m \|D^m v(x)\|$.

- ⑦ Thus, by a change of integral variable, we obtain

$$\int_{\hat{\Omega}} \|D^m \hat{v}(\hat{x})\|^p d\hat{x} \leq \|B\|^{mp} |\det(B^{-1})| \int_{\Omega} \|D^m v(x)\|^p dx.$$

Proof of $|\hat{v}|_{m,p,\hat{\Omega}} \leq C(n,m) \|B\|^m |\det(B)|^{-1/p} |v|_{m,p,\Omega}$

⑧ For any given $\eta_i \in \mathbb{R}^n$ with $\|\eta_i\| = 1$, $1 \leq i \leq m$, we have

$$D^m v(x)(\eta_1, \dots, \eta_m) = \left[\prod_{i=1}^m \sum_{j=1}^n \eta_{ij} \partial_j \right] v(x) = \sum_{j_1, \dots, j_m=1}^n \left[\prod_{i=1}^m \eta_{ij_i} \partial_{j_i} \right] v(x).$$

⑨ Since, $|\eta_{ij}| \leq 1$, $1 \leq i \leq m$, $1 \leq j \leq n$, we are lead to

$$\|D^m v(x)\| \leq n^m \max_{|\alpha|=m} |\partial^\alpha v(x)| \leq n^m \left(\sum_{|\alpha|=m} |\partial^\alpha v(x)|^p \right)^{1/p}.$$



Proof of $|\hat{v}|_{m,p,\hat{\Omega}} \leq C(n,m) \|B\|^m |\det(B)|^{-1/p} |v|_{m,p,\Omega}$

- ⑩ By ③, ⑦ and ⑨, the inequality hold for $v \in \mathbb{C}^m(\bar{\Omega})$.
- ⑪ For $1 \leq p < \infty$, $\mathbb{C}^m(\bar{\Omega})$ is dense in $\mathbb{W}^{m,p}(\Omega)$, so the inequality also holds for all $v \in \mathbb{W}^{m,p}(\Omega)$.
- ⑫ If $p = \infty$, since the inequality holds uniformly for $1 \leq q < \infty$, and for the bounded domain Ω

$$\|w\|_{0,\infty,\Omega} = \lim_{q \rightarrow \infty} \|w\|_{0,q,\Omega}, \quad \forall w \in \mathbb{L}^\infty(\Omega),$$

therefore, the inequality holds also for $v \in \mathbb{W}^{m,\infty}(\Omega)$. ■



Bound $\|B\|$ and $\|B^{-1}\|$ by the Interior and Exterior Diameters

- ① Denote the exterior and interior diameters of a region Ω as

$$\begin{cases} h_{\Omega} := \text{diam}(\Omega), \\ \rho_{\Omega} := \sup \{ \text{diam}(S) : S \subset \Omega \text{ is a } n\text{-dimensional ball} \}. \end{cases}$$

Theorem

Let Ω and $\hat{\Omega}$ be two affine-equivalent open sets in \mathbb{R}^n , let $F(\hat{x}) = B\hat{x} + b$ be the invertible affine mapping, and $\Omega = F(\hat{\Omega})$.

Then,

$$\|B\| \leq \frac{h}{\hat{\rho}}, \quad \text{and} \quad \|B^{-1}\| \leq \frac{\hat{h}}{\rho},$$

where $h = h_{\Omega}$, $\hat{h} = h_{\hat{\Omega}}$, $\rho = \rho_{\Omega}$, $\hat{\rho} = \rho_{\hat{\Omega}}$.



Proof of $\|B\| \leq \frac{h}{\hat{\rho}}$ and the Geometric Meaning of $\det(B)$

- ① By the definition of $\|B\|$, we have

$$\|B\| = \frac{1}{\hat{\rho}} \sup_{\|\xi\|=\hat{\rho}} \|B\xi\|.$$

- ② Let the vectors $\hat{x}, \hat{y} \in \overline{\hat{\Omega}}$ be such that $\|\hat{y} - \hat{x}\| = \hat{\rho}$, then, we have $x = F(\hat{x}) \in \bar{\Omega}$, $y = F(\hat{y}) \in \bar{\Omega}$.

- ③ Therefore, $\|B(\hat{y} - \hat{x})\| = \|F(\hat{y}) - F(\hat{x})\| \leq h \Rightarrow \|B\| \leq \frac{h}{\hat{\rho}}$. ■

The determinant $\det(B)$ also has an obvious geometric meaning:

$$|\det(B)| = \frac{\text{meas}(\Omega)}{\text{meas}(\hat{\Omega})} \quad \text{and} \quad |\det(B^{-1})| = \frac{\text{meas}(\hat{\Omega})}{\text{meas}(\Omega)}.$$



习题 7: 1, 3, 4

Thank You!

