Homework 11

- 1. Examine the behavior of the trajectories in the phase plane for the following systems of equations:
 - (a). $\dot{y}_1 = y_2, \dot{y}_2 = \pm a^2(1 y_1^2)y_2 y_1$ (Van der Pol's equation);
 - (b). $\dot{y}_1 = y_2, \dot{y}_2 = (\sin y_2) y_1$ (Show that this system has an infinite number of limit cycles which are alternately stable and unstable).
- 2. Show that the Jacobian

$$J(t) = \frac{\partial [\mathbf{p}(t), \mathbf{q}(t)]}{\partial [\mathbf{p}(0), \mathbf{q}(0)]}$$

satisfies J(t) = 1 for all t if **p** and **q** satisfy the Hamiltonian system

$$\frac{dq_j}{dt} = \frac{\partial H}{\partial p_j}$$
$$\frac{dp_j}{dt} = -\frac{\partial H}{\partial q_j}$$

3. (a). Prove that when r < 1 the only critical point of the Lorenz model

$$\frac{dx}{dt} = -3(x-y)$$
$$\frac{dy}{dt} = -xz + rx - y$$
$$\frac{dz}{dt} = xy - z$$

is at x = y = z = 0 and it is stable. Show also that when r > 1 the origin becomes an unstable critical point. What happens when r = 1?

(b). Show that when r > 1 there are critical points at $x = y = \pm \sqrt{r-1}$, z = r-1. Prove that these critical points are stable if 1 < r < 21 and unstable if r > 21.