

# Event-B Course

## 1. Introduction

Jean-Raymond Abrial

September-October-November 2011

- To show that **software** (and systems) can be **correct by construction**
- Insights about **modeling** and **formal reasoning** using **Event-B**
- To show that this can be **made practical** with the **Rodin Platform**

- To illustrate this approach with many **examples**:
  - a small sequential program
  - controlling cars on a bridge
  - a mechanical press controller
  - a file transfer protocol

- More examples:
  - a mobile phone routing algorithm
  - more sequential programs
  - some hardware developments
  - an access control system
  - . . .

- Writing a **requirement document** (more **explanations** later)
- **Modeling** versus **programming** (more **explanations** later)
- **Abstraction** and **refinement** (more **explanations** later)

- Some **mathematical techniques** used for reasoning
- The practice of **proving** as a means to **construct programs**
- The usage of the **Rodin Platform**

**Lectures:** Monday (10:10 to 12:00) and Wednesday (13:00 to 14:50)

**Practices:** Tuesday (18:40 to 20:30)

**17 lectures:**

September: 5, 7, 14, 19, 21, 26, 28

October: 10, 12, 17, 19, 24, 26, 31

November: 2, 7, 9

**9 Practices:**

September: 6, 13, 20, 27

October: 11, 18, 25

November: 1, 8

- 1. **Introduction** (September 5, 7)
- 2. **Cars on a Bridge** (September 14, 19, 21)
- 3. **Mechanical Press** (September 26, 28)
- 4. **File Transfer Protocol** (October 10)
- 5. **Math Refresher** (October 12, 17)
- 6. **Mobile Phone Routing** (October 19)
- 7. **Hardware Development** (October 24, 26)
- 8. **Access Control System** (October 31, November 2)
- 9. **Hypervisor Development** (November 7, 9)



- 1. Writing a Requirement Document (September 6)
- 2. Introducing the Rodin Platform (September 13)
- 3. Developing a small Motor Controller (September 20)
- 4. Practicing Interactive Proofs (September 27, October 11, 18)
- 5. Another Formal Development (October 25)
- 6. Developing a Business Protocol (November 1, 8)

For **lectures**:

- slides
- text

For **practices**:

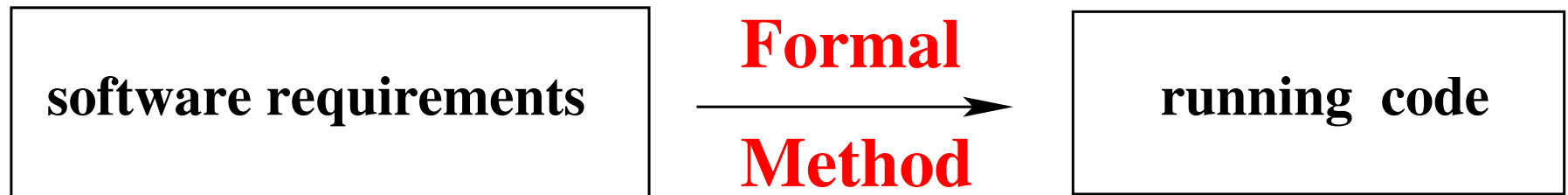
- text of exercises
- corrected exercises (one week later)
- Rodin Platform development files

1. About **formal methods** in general
2. About **requirements**
3. About **modeling**
4. A light introduction to **Event-B**
5. Presentation of a **small example**

1. About **formal methods** in general

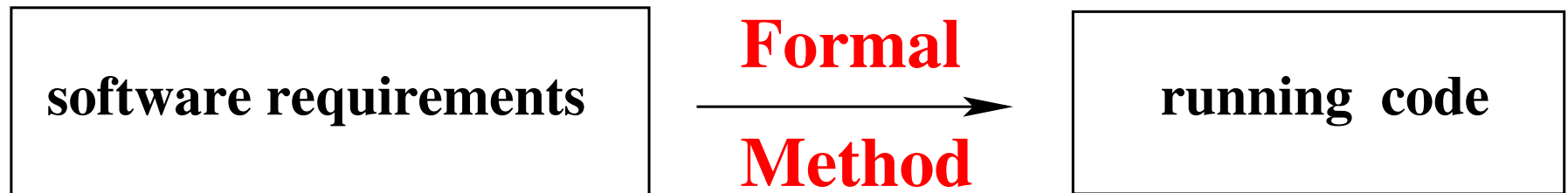
- What are they used for?
- When are they to be used?
- Is UML a formal method?
- Are formal methods needed when doing OO programming?
- What is their definition?

- Helping **people** in doing the following **transformation**:

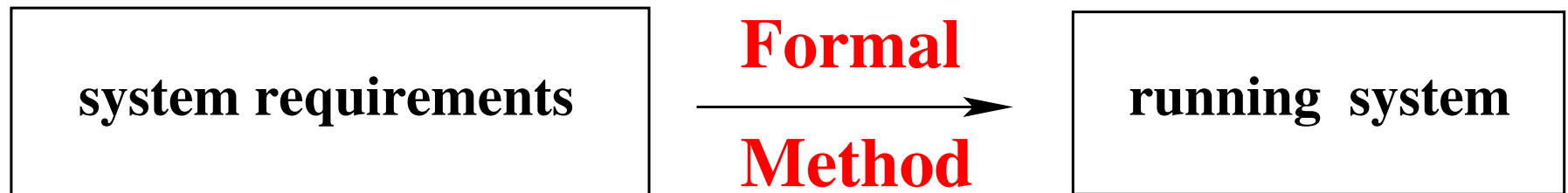


- It does not seem to be different from **ordinary programming**

- Helping **people** in doing the following **transformation**:



- It does not seem to be different from **ordinary programming**
- It can be generalized to:



- Determining whether a **program** has certain wishful **properties**.
- The checked **properties** will become **clearer** in subsequent slides
- Different **kinds** of formal methods (according to this definition)
  - **Type checking**
  - **Abstract interpretation**
  - **Model checking**
  - **Theorem proving**



- The properties to be checked are **properties of program variables**
- Controlling low level **properties of variables**
- A **type** defines:
  - a **set of values** to be assigned to a **variable**
  - the **operations** that can be performed on a **variable**
  - the way a program **variable** will be **stored in the memory**

- Type checking controls that:
  - value assignments to a variable is correct
  - the variable is used in authorized operations only
- It is done automatically by compilers

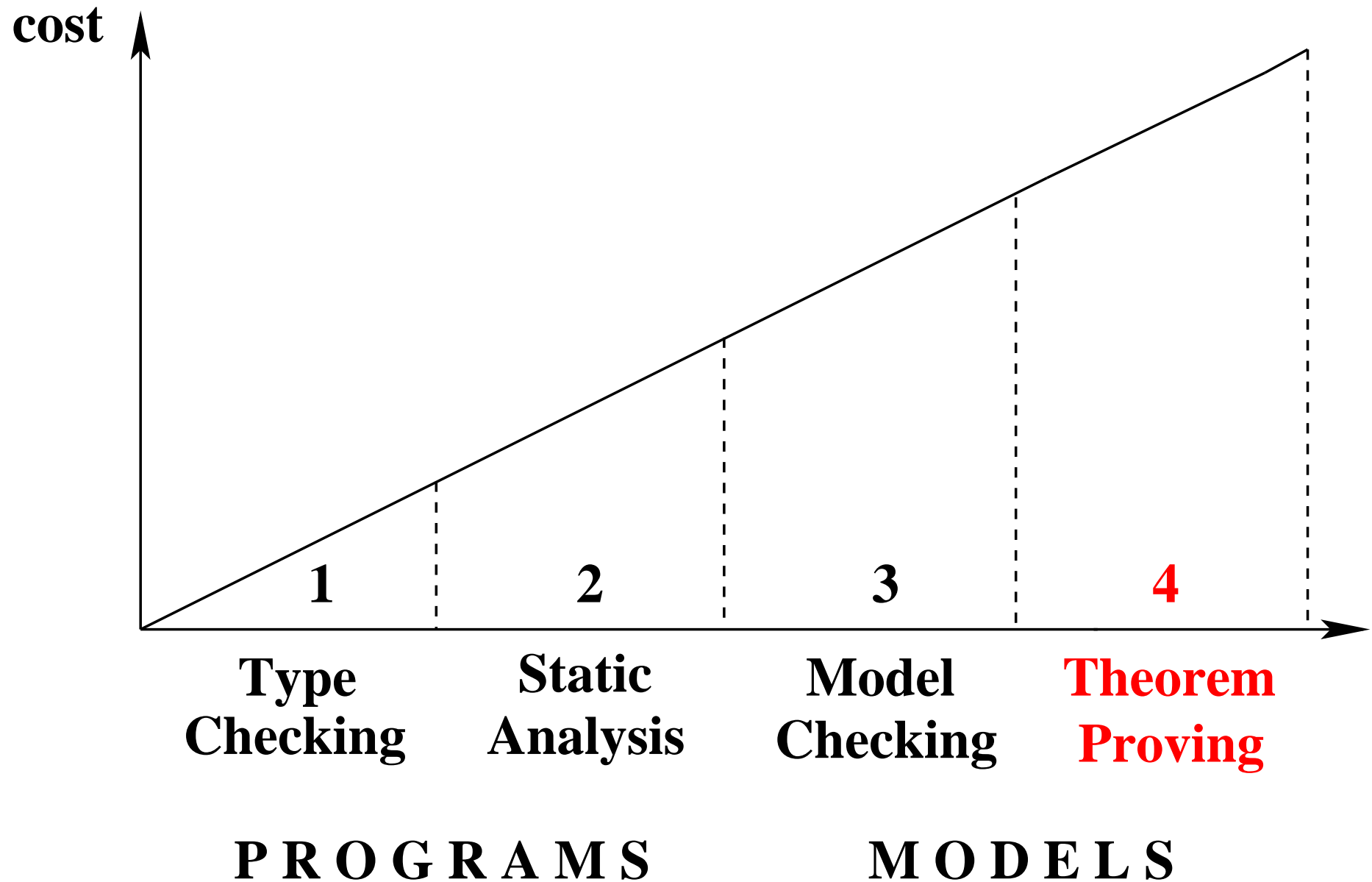
- The property to be checked is the **absence of run-time errors**
- **Typical** run-time detected:
  - **Division by zero**
  - **Array bound overflow**
  - **Arithmetic overflow** (floating point)

- The analysis is performed by **abstracting the program variables**
- Executing the **resulting abstraction** rather than the program itself
- Once the property is defined, it is an **automatic** technique

- Models to be studied usually denote **finite state machines**
- Properties to be checked:
  - **Reachability**
  - **Deadlock freeness**
- Once the property is defined, it is an **automatic** technique

- Properties to be checked are **any of the above**
- But **more abstract properties** can also be checked (more **later**)
- This is the approach **developed in this course**

- One constructs models by successive refinements
- The properties to be proved are parts of the models
- The most refined model is automatically translated into a program





	Nature	Properties
type checking	programs	defined <b>within</b> the program
abstract interpretation	programs	defined <b>after</b> writing program
model checking	models	defined <b>after</b> writing model
theorem proving	models	defined <b>within</b> the model

- When the **risk** is too high (e.g. in **embedded systems**).
- When the **verifications** of other approaches are **not sufficient**
- When people **question** their industrial **development process**.
- **Decision** of using formal methods is **always strategic**.



# How about other Engineering Disciplines?

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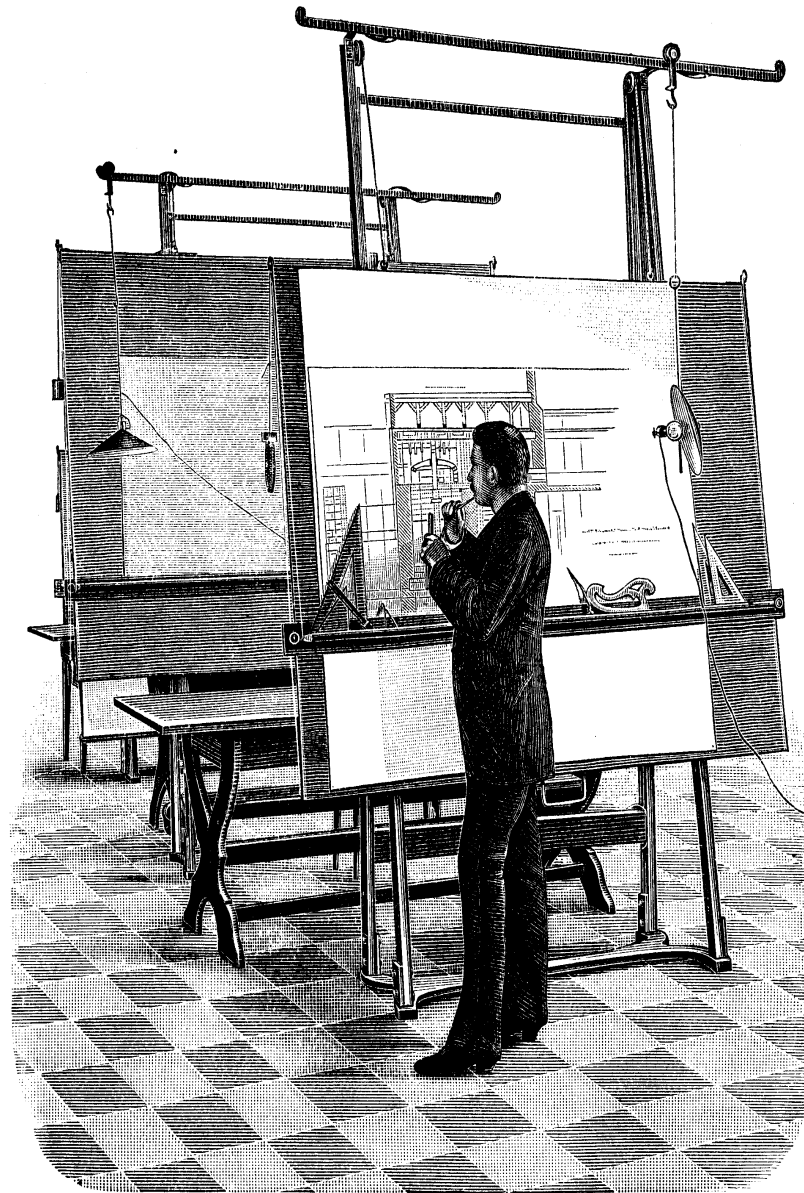
- Some **mature** disciplines:
  - Avionics,
  - Civil Engineering,
  - Mechanical Constructions,
  - Ship building,
  - . . .

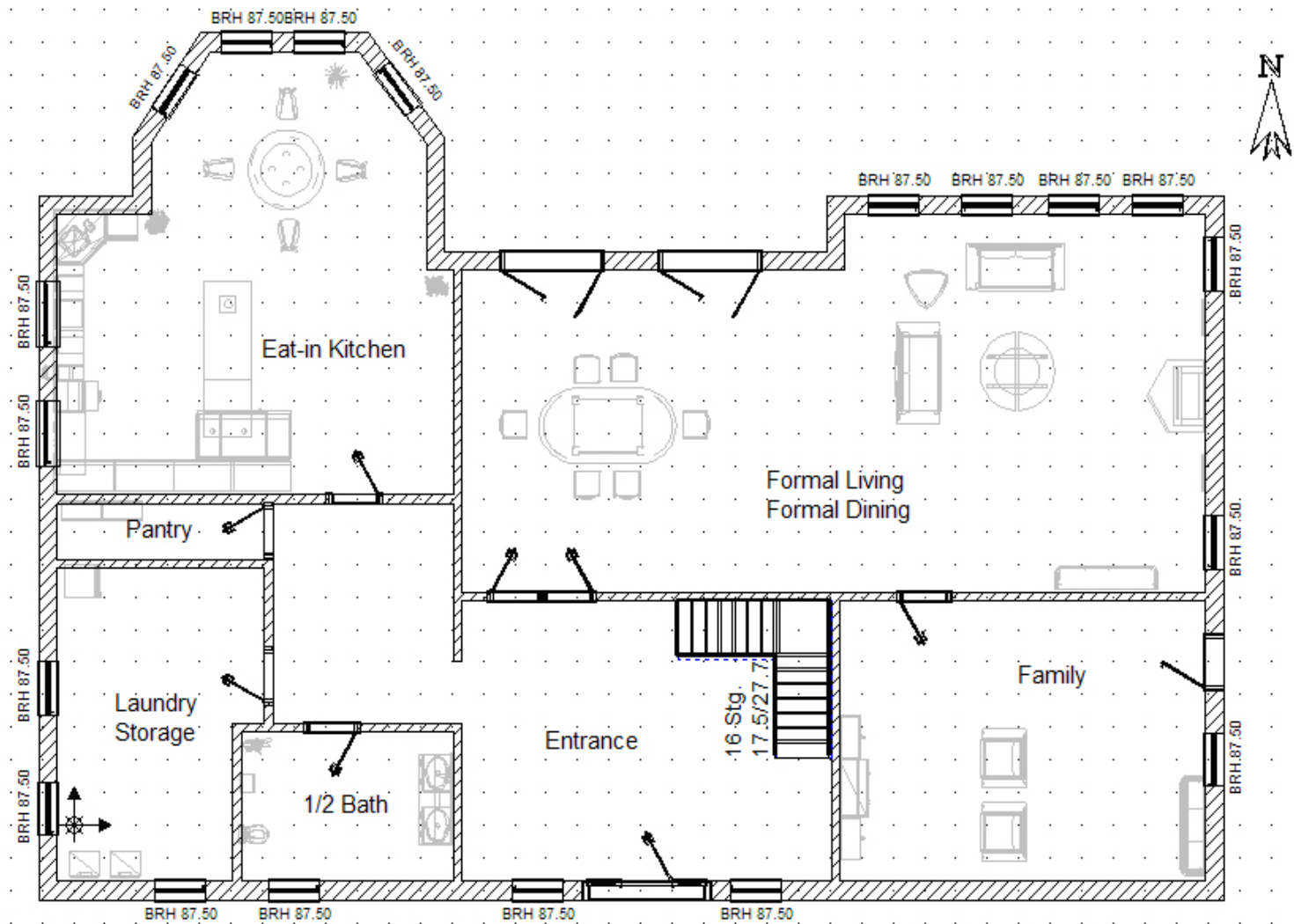
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  - Ship building,
  - ...
- Does there exist methods similar to formal methods ?

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- Yes



- Some **mature** disciplines:
  - Avionics,
  - Civil Engineering,
  - Mechanical Constructions,
  - Ship building,
  - ...
- Does there exist methods similar to formal methods ?
- Yes, **Blueprints**





- An abstract **representation** of the **system** we want to build
- The **basis is lacking** (you cannot “drive” the blue print of a car)
- Allows to **reason** about the system **during its design**, NOT AFTER
- Example: constructing a **freeway** or a **bridge**

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- **Is it important?** (according to professionals)

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- Allows to **reason** about the system **during its design**, NOT AFTER
- Example: constructing a **freeway** or a **bridge**
- **Is it important?** (according to professionals) **YES**

- Defining and calculating its **behavior** (what it does)
- Incorporating **constraints** (what it must not do)
- Defining **architecture**
- Based on some **underlying theories**
  - strength of materials,
  - fluid mechanics,
  - gravitation,
  - etc.

- Using pre-defined conventions (often computerized these days)
- Conventions should help facilitate reasoning
- Adding details on more accurate versions
- Postponing choices by having some open options
- Decomposing one blue print into several
- Reusing “old” blue prints (with slight changes)



## 2. About requirements

- Place of requirement document in the system life cycle
- Difficulties and weak point
- Characterizing the requirement document
- Proposing some structuring rules

1. Feasibility Study

2. Requirement Analysis

3. Technical Specification

4. Design

4. Coding

5. Test

6. Documentation

7. Maintenance

- Ensuring **relative consistency** between the phases
- **Formal Methods** could help (in the later phases)
- But still a problem in the **earlier phases**
- **Weakest part:** the requirement document

- Importance of this document (due to its **position** in the life cycle)
- Obtaining a **good** requirement document is **not easy**:
  - **missing** points
  - too **specific** (over-specified)
- Industrial requirement document are usually **difficult to exploit**

- Hence **very often** necessary to **rewrite it**
- It will cost a significant amount of **time and money** (but well spent)
- The famous **specification change** syndrome might **disappear**

- Two **separate texts** in the same document:
  - **explanatory** text: the **why**
  - **reference** text: the **what**
- Reference text (**what**) and explanatory text (**why**) defined together
- The **reference** text eventually becomes the **official** document
- Must be **signed** by concerned parties

- Contains the **properties** of the future **system**
- Contains the **assumptions** about its **environment**
- The properties **must hold** for the **system to be correct**
- This must be the case **if the assumptions hold**



- It is made of short **labeled** English statements
- Should be **easy to read** (different font) and **easy to extract** (boxed)
- The problem of the **traceability**

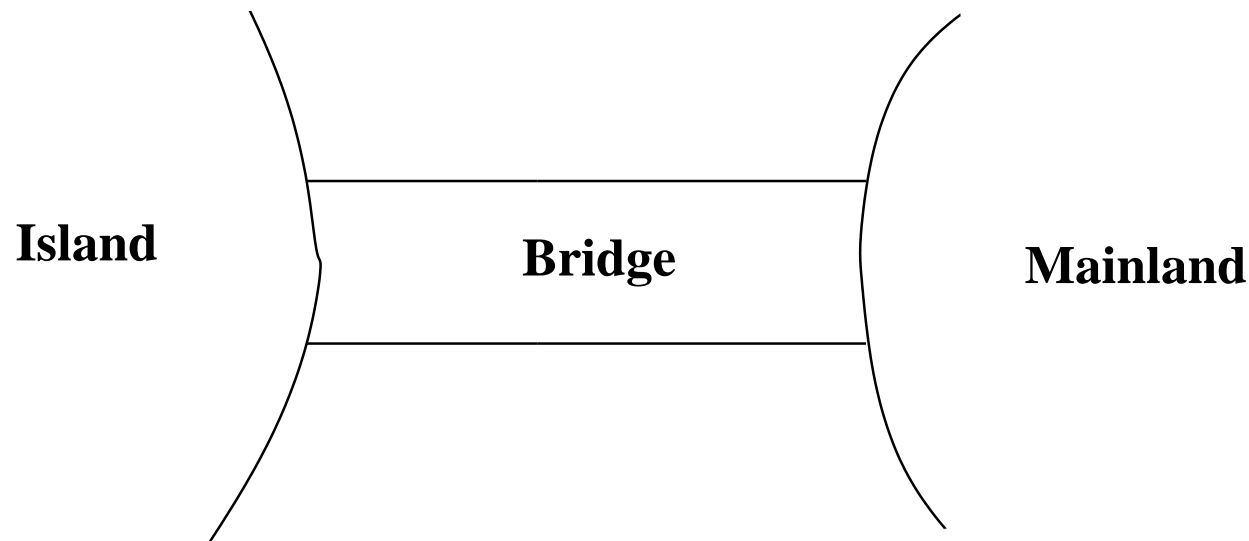
- We show the **embedding** of the Explanations and the References
- **Explanation:**
- The function of this system is to **control cars on a narrow bridge**.
- This bridge is supposed to link the **mainland** to a **small island**.

- There are **two kinds** of requirements:
  - the **equipment** (environment) labeled **EQP**,
  - the **function** of the system, labeled **FUN**.

- **Reference:**

The system is controlling cars on a bridge between the mainland and an island	FUN-1
---	-------

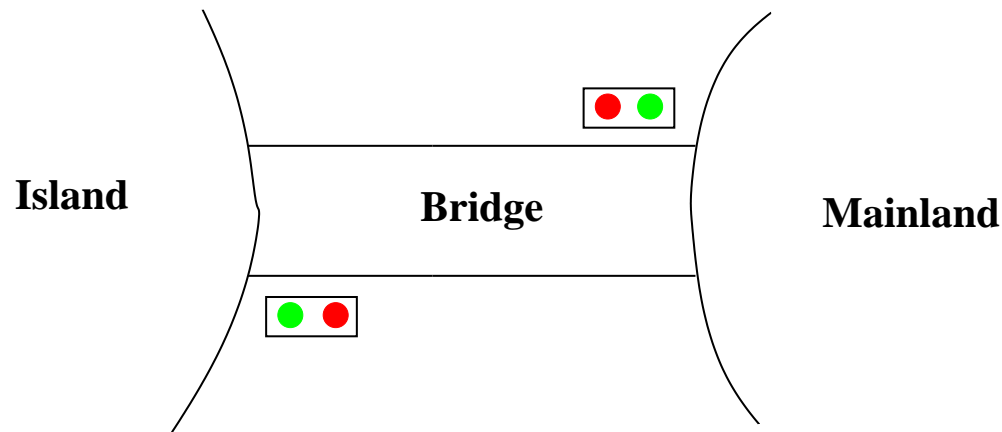
- **Explanation:** This can be illustrated as follows



- **Explanation:** The controller is equipped with two **traffic lights**.
- **Reference:**

The system has two traffic lights with two colors: green and red	EQP-1
--	-------

- **Explanation:**
- One of the traffic lights is situated on the **mainland**.
- The other one on the **island**.
- This can be illustrated as follows:



- Reference:

The traffic lights control the entrance to the bridge at both ends of it	EQP-2
--	-------

- Explanation: Drivers are supposed to obey the traffic light

- Reference:

Cars are not supposed to pass on a red traffic light, only on a green one	EQP-3
---	-------

- **Explanation:**
- There are also four **car sensors**
- These sensors are situated at both ends of the bridge.
- They are supposed to **detect the presence of cars**
- **Reference:**

The system is equipped with four car sensors each with two states: on or off

EQP-4

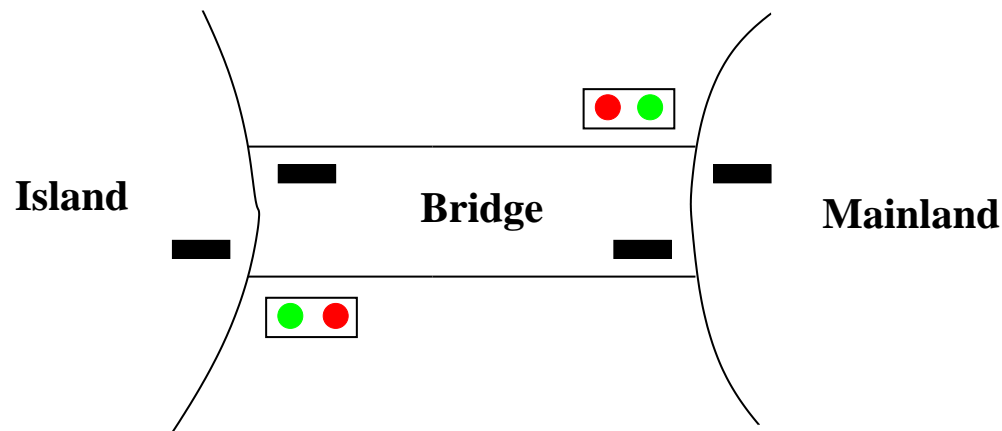


- **Reference:**

The sensors are used to detect the presence of cars entering or leaving the bridge

EQP-5

- **Explanation:** The pieces of equipment can be illustrated as follows:



- **Explanation:** This system has two main **constraints**:
  - the **number of cars** on the bridge and the island is **limited**
  - the **bridge is one way**.

- Reference:

The number of cars on the bridge and the island is limited

FUN-2

The bridge is one way or the other, not both at the same time

FUN-3

The system is controlling cars on a bridge between the mainland and an island

FUN-1

The number of cars on the bridge and the island is limited

FUN-2

The bridge is one way or the other, not both at the same time

FUN-3

The system has two traffic lights with two colors: green and red

EQP-1

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EQP-2

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EQP-3

The system is equipped with four car sensors each with two states: on or off

EQP-4

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EQP-5

### 3. About modeling

- What are they used for?
- When are they to be used?
- Is UML a formal method?
- Are formal methods needed when doing OO programming?
- What is their definition?



- **Formal methods** are techniques for **building and studying blue prints**
- Such blue prints should be **ADAPTED TO OUR DISCIPLINE**
- Our discipline: **design of hardware and software SYSTEMS**
- These blue prints are now called **models**
- Reminder:
  - **Models allow to reason about a FUTURE system**
  - **The basis is lacking** (hence you cannot “execute” a model)

- Models allow to reason about a FUTURE system
- The basis is lacking (hence you cannot “execute” a model)
- Using pre-defined conventions
- Conventions should help facilitate reasoning (more to come)

- Using ordinary discrete mathematical conventions
- Classical Logic (Predicate Calculus)
- Basic Set Theory (sets, relations and functions)
- Such conventions will be reviewed in subsequent lectures

- a “classical” piece of software
- an electronic circuit
- a file transfer protocol
- an airline booking system
- a PC operating system

- a nuclear plant controller
- a Smart-Card electronic purse
- a launch vehicle flight controller
- a driverless train controller
- a mechanical press controller
- etc.

- They are made of many parts
- They interact with a possibly hostile environment
- They involve several executing agents

- They require a high degree of correctness
- Their construction spreads over several years
- Their specifications are subjected to many changes

- These systems operate in a **discrete fashion**
- Their dynamical behavior can be **abstracted** by:
  - A succession of **steady states**
  - Intermixed with **sudden jumps**



- The possible number of state changes are enormous
- Usually such systems never halt
- They are called DISCRETE TRANSITION SYSTEMS

- **Test** reasoning (a **vast majority**): **VERIFICATION**
- **Blue Print** reasoning (a **very few**): **CORRECT CONSTRUCTION**

- Based on laboratory execution
- Obvious incompleteness
- The oracle is usually missing
- Properties to be checked are chosen a posteriori
- Re-adapting and re-shaping after testing
- Reveals an immature technology

- Based on a **formal model**: the “blue print”
- **Gradually** describing the system with the **needed precision**
- **Relevant Properties** are chosen **a priori**
- Serious thinking made **on the model**, not on the final system
- **Reasoning is validated by proofs**
- Reveals a **mature technology**

- The proof **succeeds**
- The proof fails but **refutes the statement to prove**
  - the model is **erroneous**: it has to be modified
- The proof **fails but is probably provable**
  - the model is **badly structured**: it has to be reorganized
- The proof **fails and is probably not provable nor refutable**
  - the model is **too poor**: it has to be enriched



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 $n.x/100.f.p$  is the number of man-day for the interactive proofs
- $m$ : number of man-months to perform the interactive proofs.  
 $n.x/100.f.p.20$  is the number of man-month for proving

-  $m = n.x/100.f.p.20$  is the number of **man-months** needed for proving

$n$	100, 000	100, 000	100, 000
$f$	2	2	2
$x$	2.5%	5%	10%
$p$	20	20	20
$m$	<b>3.12</b>	<b>6.25</b>	<b>12.5</b>

This shows the importance **to prove as many automatic proofs as we can**

### - Rules of Thumb:

$n$  lines of final code implies  $n/3$  proofs

95% of proofs discharged automatically

5% of proofs discharged interactively

350 interactive proofs per man-month

- 60,000 lines of final code  $\leadsto$  20,000 proofs  $\leadsto$  1,000 int. proofs
- 1,000 interactive proofs  $\leadsto$   $1000/350 \simeq 3$  man-months
- Far less expensive than heavy testing

## 4. A Light Introduction to Event-B

- Event-B is not a programming language (even very abstract)
- Event-B is a notation used for developing mathematical models
- Mathematical models of discrete transition systems
- <http://www.event-b.org>

- Such **models**, once finished, can be used to **eventually construct**:
  - **sequential** programs,
  - **distributed** programs,
  - **concurrent** programs,
  - **electronic circuits**,
  - **large systems** involving a possibly **fragile environment**,
  - . . .
- The underlined statement is an **important** case.
- In this lecture, we shall construct a **small sequential programs**.



**Action Systems** developed by the Finnish school (Turku):

**R.J.R. Back and R. Kurki-Suonio**

**Decentralization of Process Nets with Centralized Control.**

2nd ACM SIGACT-SIGOPS Symposium

Principles of Distributed Computing (1983)

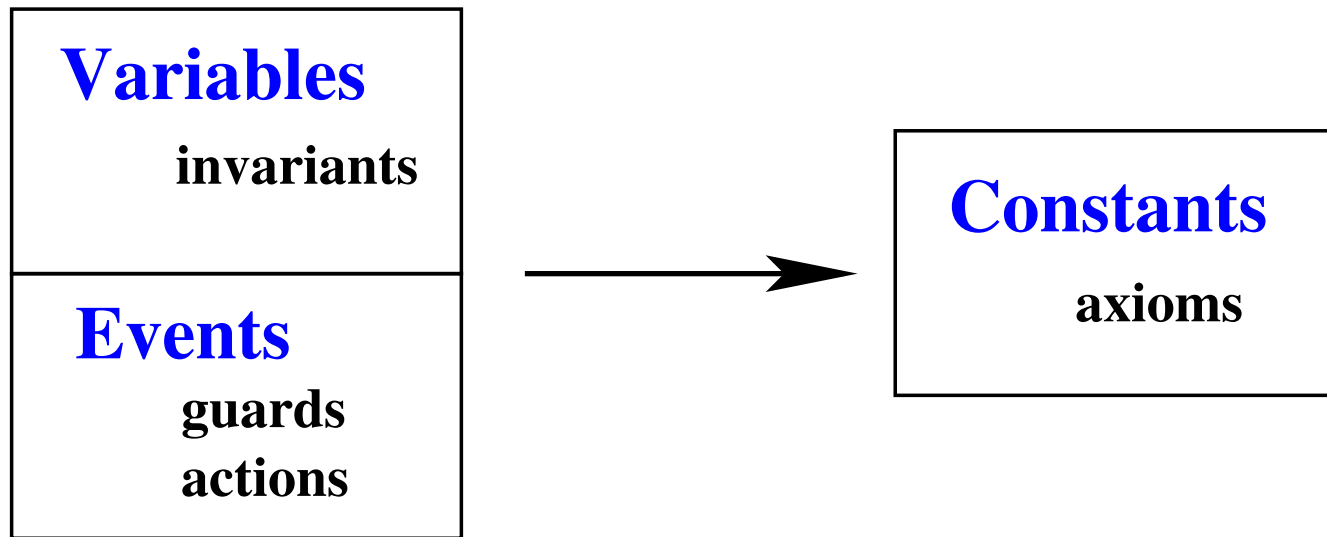
**M.J. Butler**

**Stepwise Refinement of Communicating Systems.**

Science of Computer Programming (1996)

- A discrete model is first made of a **state**
- The state is represented by some **constants** and **variables**
- Constants are linked by some **axioms**
- Variables are linked by some **invariants**
- Axioms and invariants are written using **set-theoretic expressions**

- A discrete model is also made of a number of **events**
- An event is made of a **guard** and an **action**
- The **guard** denotes the **enabling condition** of the event
- The **action** denotes the way the **state is modified** by the event
- Guards and actions are written using **set-theoretic expressions**



**Dynamic Parts**

(Machines)

**Static Parts**

(Contexts)

- An event execution is supposed to **take no time**
- Thus, **no two events can occur simultaneously**
- When all events have false guards, the **discrete system stops**
- When some events have true guards, **one of them** is chosen non-deterministically and **its action modifies the state**
- The previous phase is **repeated** (if possible)

Initialize;

**while** (some events have true guards) {  
    **Choose** one such event;  
    **Modify** the state accordingly;  
}

- Stopping is not necessary: a discrete system may run for ever
- This interpretation is just given here for informal understanding
- The meaning of such a discrete system will be given by the proofs which can be performed on it.

- A **model** is made of several **components**
- A component is either a **machine** or a **context**:

## **Machine**

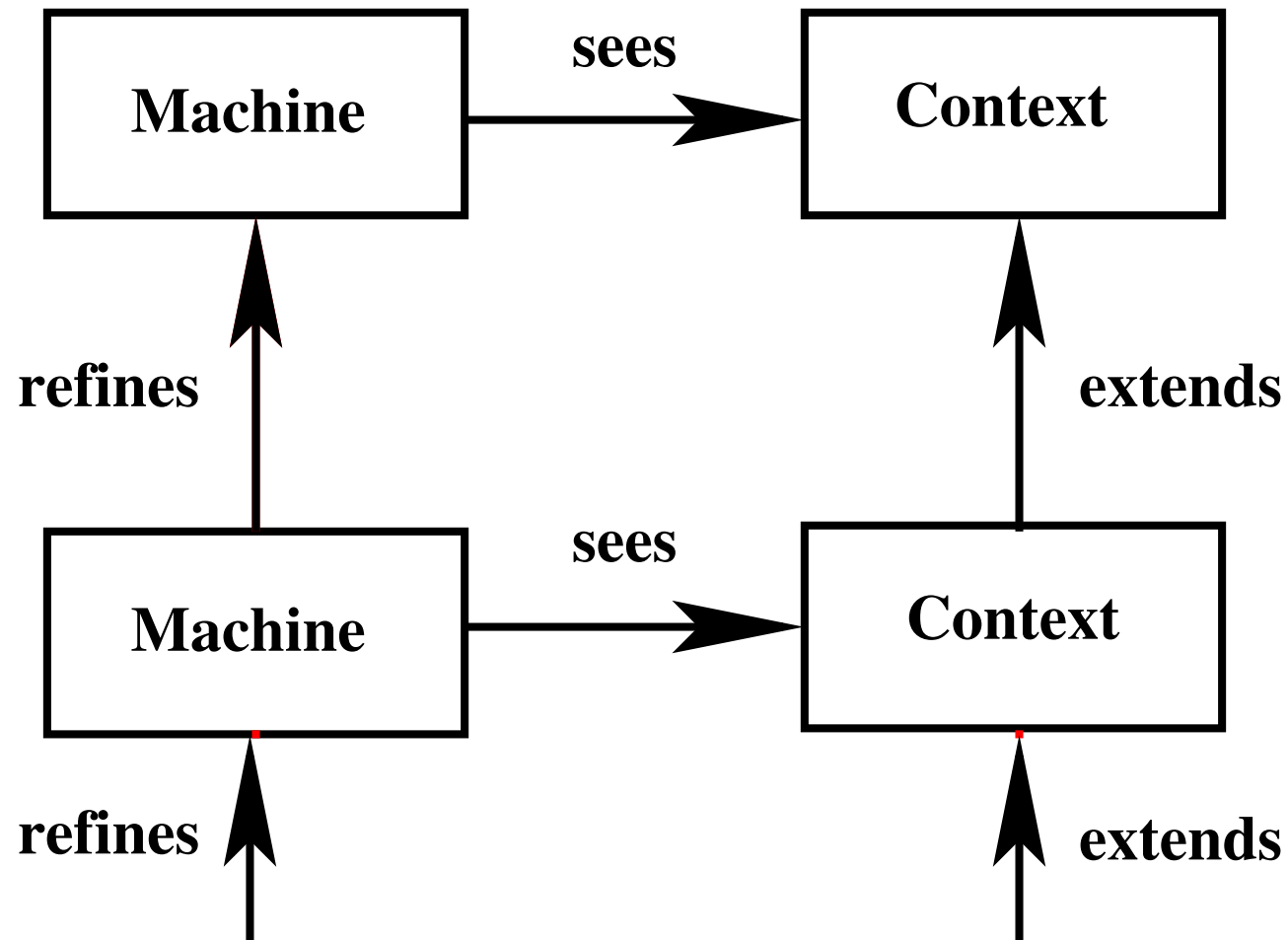
**variables**  
**invariants**  
**theorems**  
**events**

## **Context**

**carrier sets**  
**constants**  
**axioms**  
**theorems**



- **Contexts** contain the **static structure** of a discrete system  
(constants and axioms)
- **Machines** contain the **dynamic structure** of a discrete system  
(variables, invariants, and events)
- Machines **see** contexts
- Contexts can be **extended**
- Machines can be **refined**



## 5. Presentation of a Small Example

We are given a non-empty finite array of natural numbers

FUN-1

We like to find the maximum of the range of this array

FUN-2

We are given a non-empty finite array of natural numbers

FUN-1

We like to find the maximum of the range of this array

FUN-2

We want to find that **10** is the greatest element of this array

9	3	10	8	3	5
---	---	----	---	---	---

- First, we show an initial model **specifying** the problem
- Later, we **refine** our model to produce an **algorithm**.
- In the initial model, we have:
  - a **context** where the constant array is defined
  - a **machine** where the maximum is "computed"

- Constant  $n$  denotes the size of the non-empty array,
- Constant  $f$  denotes the array,
- Constant  $M$  denotes a natural number.

**constants:**  $n$   
 $f$   
 $M$

$$0 < n$$

$$f \in 1 .. n \rightarrow 0 .. M$$

$$\text{ran}(f) \neq \emptyset$$

- Mind the inference typing

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**constants:**  $n$   
 $f$   
 $M$

**axm0\_1:**  $0 < n$

**axm0\_2:**  $f \in 1 .. n \rightarrow 0 .. M$

**thm0\_1:**  $\text{ran}(f) \neq \emptyset$

- Mind the inference typing



## Context

sets

constants

axioms

theorems

Notice that we have **no set**

**context**

**maxi\_ctx\_0**

**constants**

$n$

$f$

$M$

**axioms**

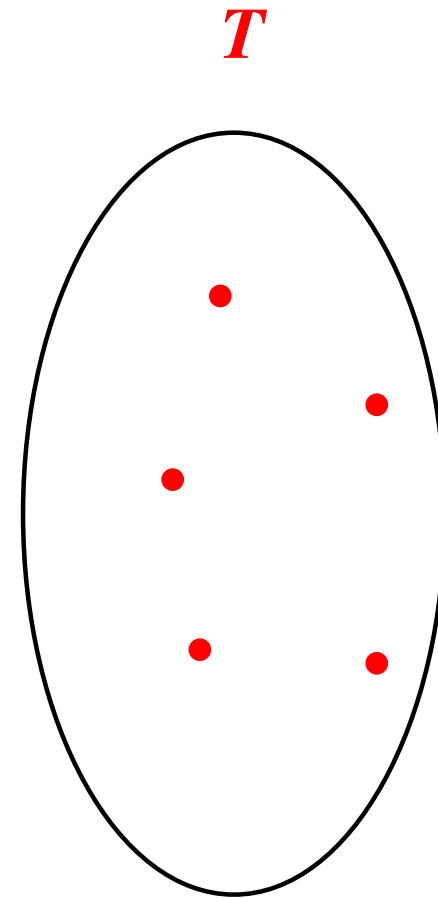
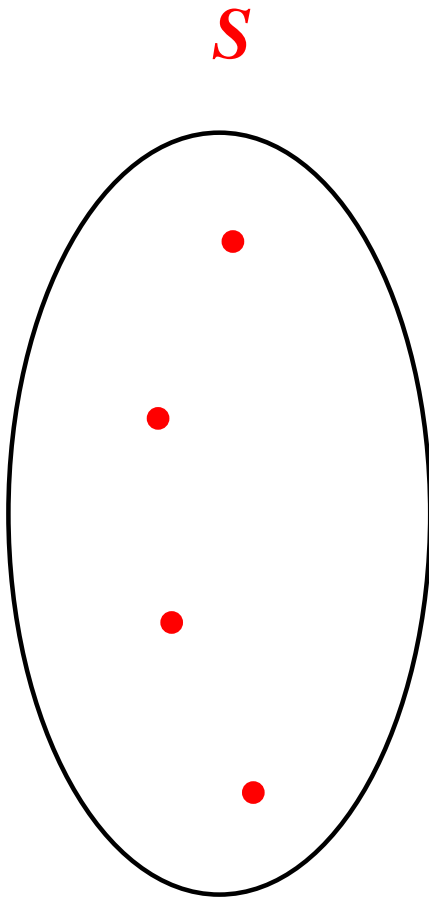
**axm1** :  $0 < n$

**axm2** :  $f \in 1..n \rightarrow 0 .. M$

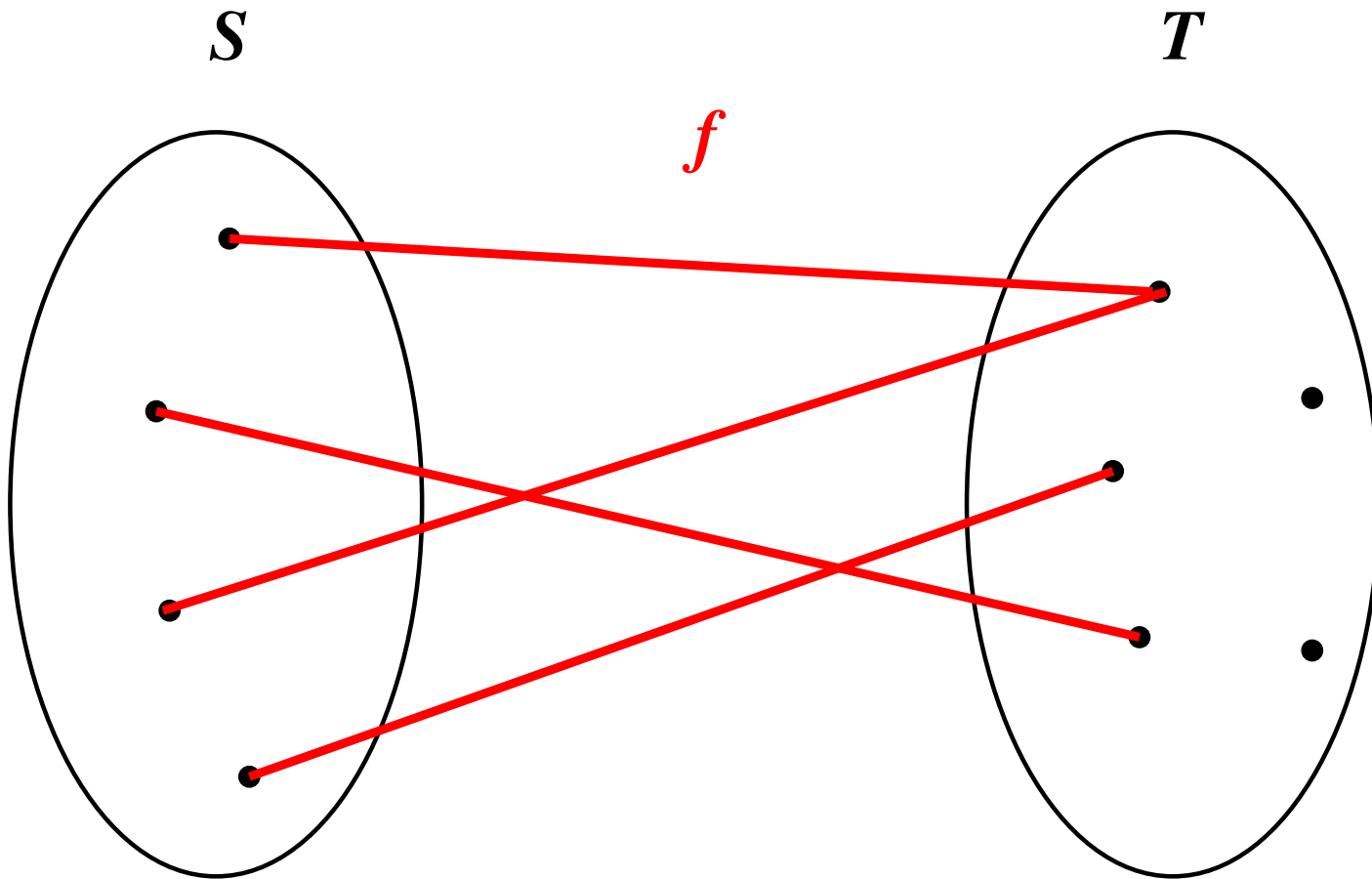
**thm1** :  $\text{ran}(f) \neq \emptyset$

**end**

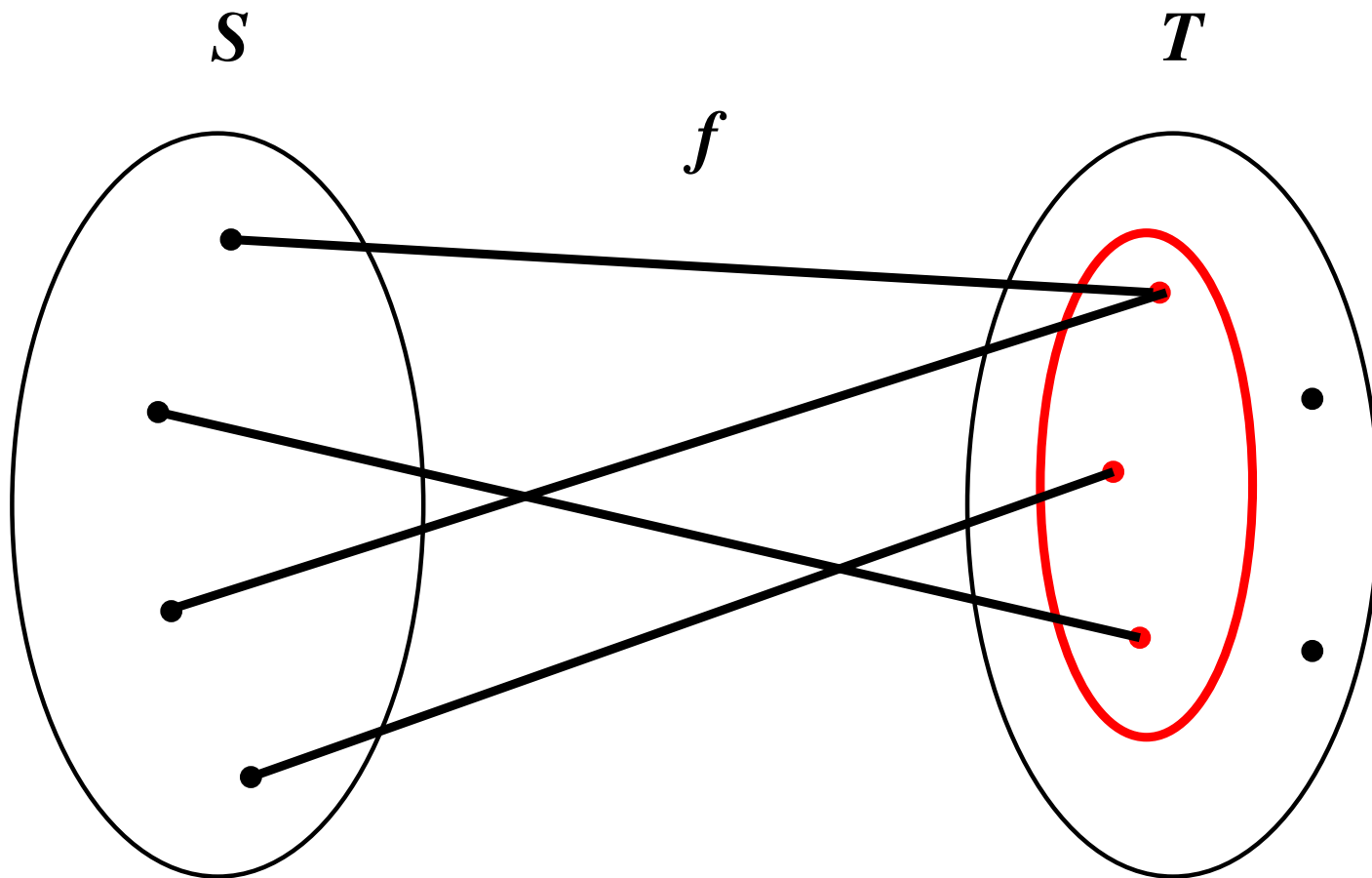
- We are given two sets  $S$  and  $T$



- Here is a total function  $f$  from  $S$  to  $T$ :  $f \in S \rightarrow T$



- Here is the **range of  $f$**



D E M O (showing a context)

```
context
  < context_identifier >
sets
  < set_identifier >
  ...
constants
  < constant_identifier >
  ...
axioms
  < label >: < predicate >
  ...
end
```

- "**sets**" lists various sets, which define pairwise disjoint types
- "**constants**" lists the different constants introduced in the context
- "**axioms**" defines the properties of the constants

- Variable  $m$  denotes the result.

**variable:**  $m$

**inv0\_1:**  $m \in \mathbb{N}$

- Next are the two events:

INIT

**begin**

$m := 0$

**end**

maximum

**begin**

$m := \max(\text{ran}(f))$

**end**

- Event **maximum** presents the final intended result (in one shot)



## Machine

variables  
invariants  
theorems  
events

**machine**

**maxi\_0**

**sees**

**ctx\_0**

**variables**

*i*

**invariants**

**inv1** :  $i \in 1 .. n$

**events**

...

**end**

```
machine
  maxi_0
sees
  maxi_ctx_0
variables
   $m$ 
invariants
```

```
  inv1 :  $m \in \mathbb{N}$ 
```

```
events
  ...
end
```

```
context
  maxi_ctx_0
sets
   $D$ 
constants
   $n$ 
   $f$ 
   $v$ 
axioms
```

```
  axm1 :  $0 < n$ 
```

```
  axm2 :  $f \in 1..n \rightarrow 0..M$ 
```

```
  thm1 :  $\text{ran}(f) \neq \emptyset$ 
```

```
end
```

D E M O (showing a machine)

```
machine
  < machine_identifier >
sees
  < context_identifier >
  ...
variables
  < variable_identifier >
  ...
invariants
  < label >: < predicate >
  ...
events
  ...
variant
  < variant >
end
```

- "**variables**" lists the **state variables** of the machine
- "**invariants**" states the **properties** of the variables
- "**events**" defines the **dynamics** of the transition system (next slides)
- "**variant**" is explained later

- 
- An event defines a **transition** of our discrete system
  - An event is made of a **Guard**  $G$  and an **Action**  $A$
  - $G$  defines the **enabling conditions** of the transition
  - $A$  defines a **parallel assignment** of the variables

**begin**  
 $A$   
**end**

No guard

**when**  
 $G$   
**then**  
 $A$   
**end**

Simple guard

**any**  $x$  **where**  
 $G(x)$   
**then**  
 $A(x)$   
**end**

Quantified guard

```
begin
   $A$ 
end
```

No guard

```
when
   $G$ 
then
   $A$ 
end
```

Simple guard

```
any  $x$  where
   $G(x)$ 
then
   $A(x)$ 
end
```

Quantified guard

Our event (so far) have no guards

```
INIT
  begin
     $m := 0$ 
  end
```

```
maximum
  begin
     $m := \max(\text{ran}(f))$ 
  end
```



**constants:**  $n$   
 $f$   
 $M$

**axm0\_1:**  $0 < n$

**axm0\_2:**  $f \in 1 .. n \rightarrow 0 .. M$

**thm0\_1:**  $\text{ran}(f) \neq \emptyset$

**variable:**  $m$

**inv0\_1:**  $m \in \mathbb{N}$

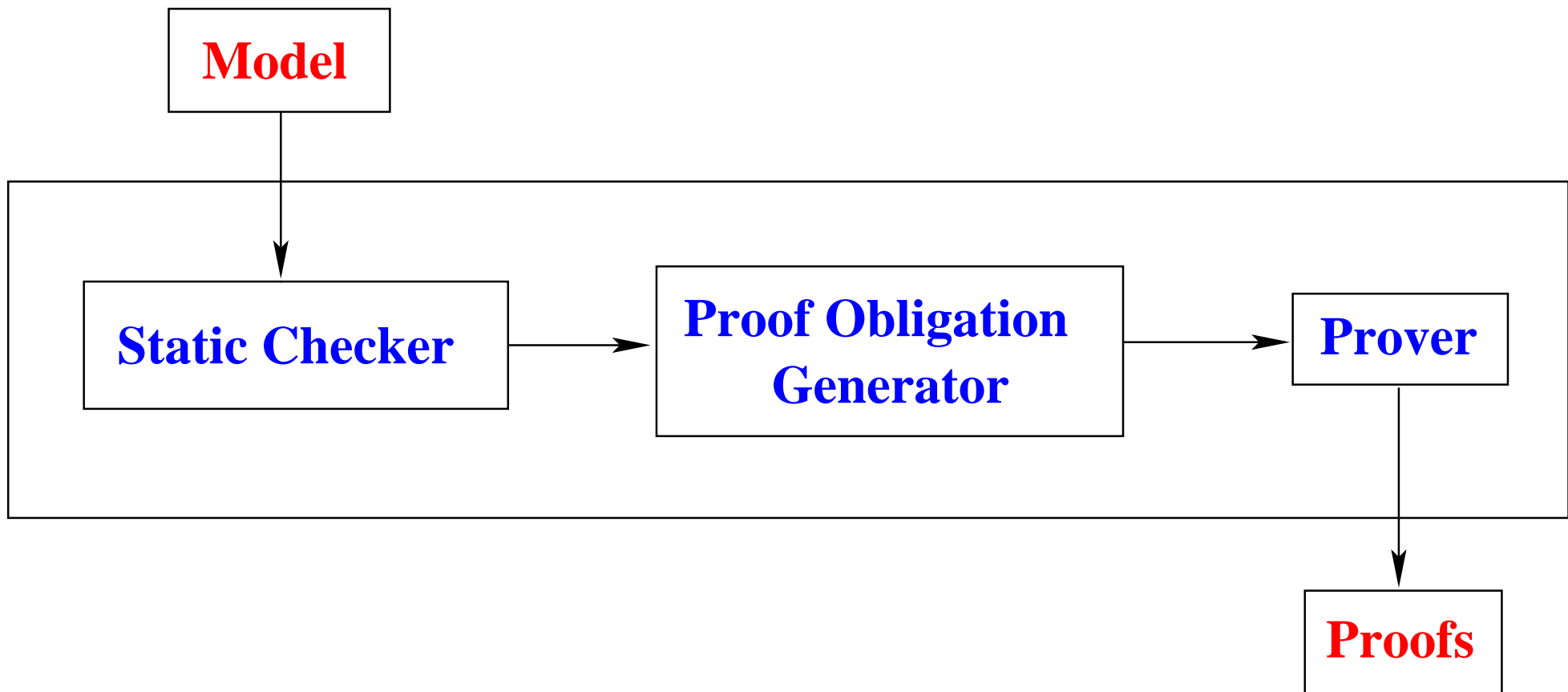
INIT  
**begin**  
     $m := 0$   
**end**

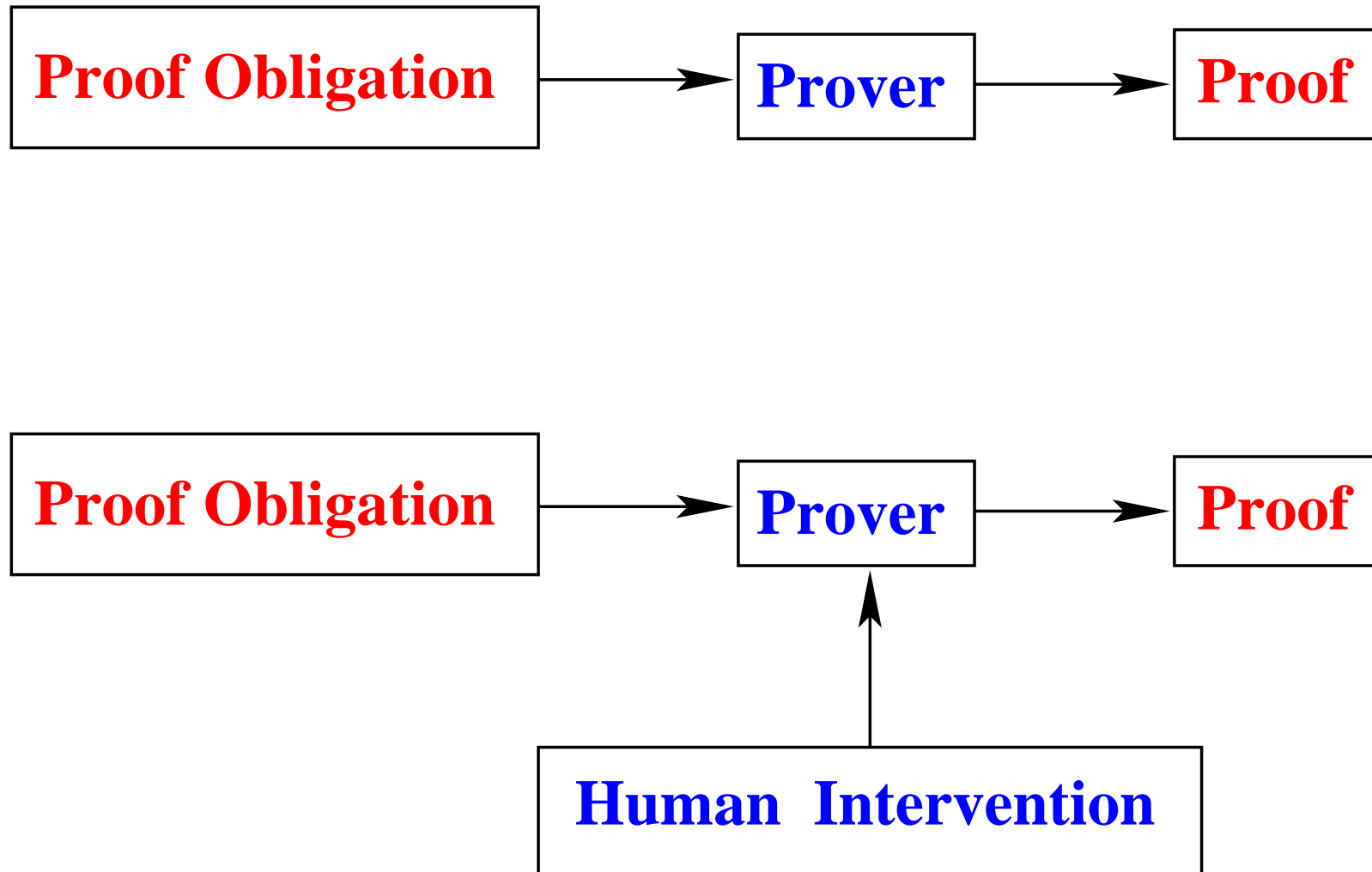
maximum  
**begin**  
     $m := \max(\text{ran}(f))$   
**end**

- We have to perform **some proofs**:
  - **thm0\_1 holds**
  - Invariant **inv0\_1** is **established** by event "INIT"
  - Invariant **inv0\_1** is **maintained** by event "maximum"
  - Expression " $\max(\text{ran}(f))$ " is **well-defined**

- Stated theorems
- Invariant maintenance
- Well-definedness

D E M O (showing proof obligations)





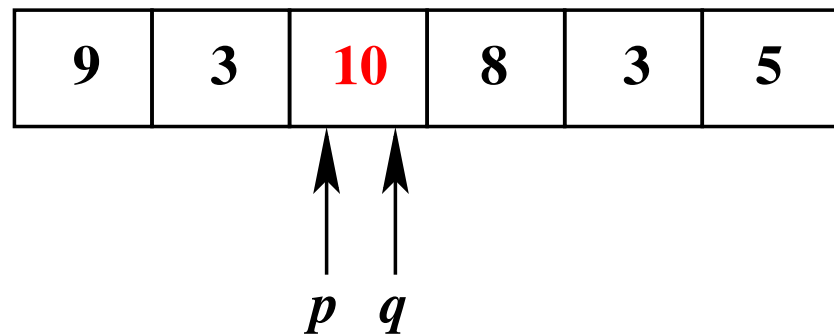
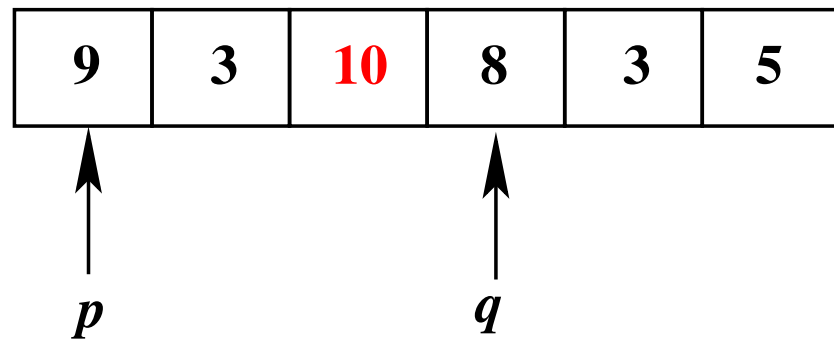
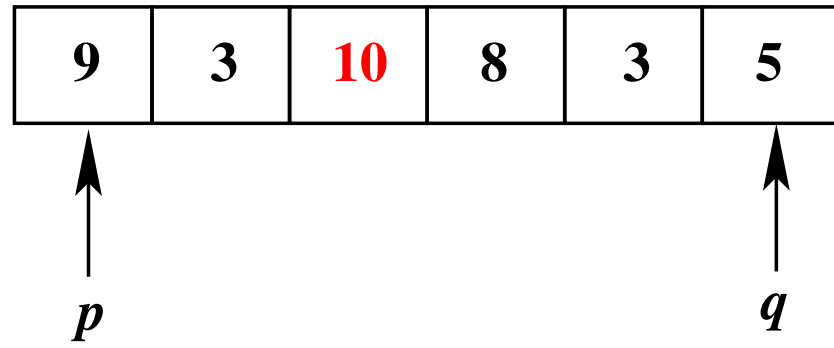
- We introduce **two new variables** in our model
- Variables  **$p$**  and  **$q$**  denote two indices in the domain of  $f$ .

**variables:**    $m$   
                   **$p$**   
                   **$q$**

**inv1\_1:**    $p \in 1 .. n$

**inv1\_2:**    $q \in 1 .. n$

The maximum is **always**  
"between"  $p$  and  $q$





- Interval  $p .. q$  is **never** empty (**inv1\_3**)
- The maximum is **always** in the image of  $p .. q$  under  $f$  (**inv1\_4**)

**variables:**  $m$   
 $p$   
 $q$

**inv1\_1:**  $p \in 1 .. n$

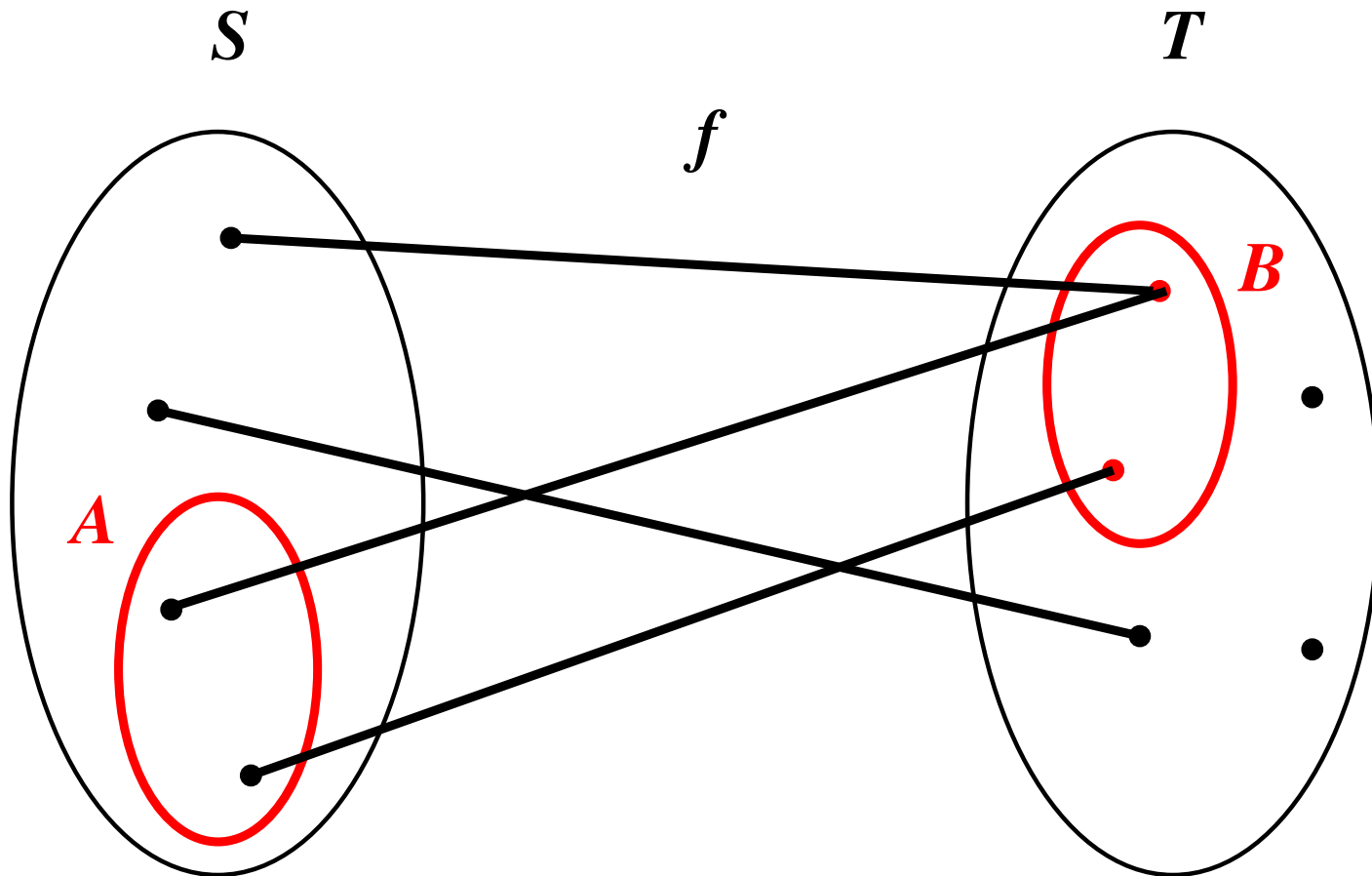
**inv1\_2:**  $q \in 1 .. n$

**inv1\_3:**  $p \leq q$

**inv1\_4:**  $\max(\text{ran}(f)) \in f[p .. q]$

- **inv1\_4** is the main invariant

- $B$  is the **image** of  $A$  under  $f$ :  $B = f[A]$



```
INIT  
  begin  
     $m := 0$   
     $p := 1$   
     $q := n$   
  end
```

```
maximum  
  when  
     $p = q$   
  then  
     $m := f(p)$   
  end
```

```
INIT
  begin
     $m := 0$ 
     $p := 1$ 
     $q := n$ 
  end
```

```
maximum
  when
     $p = q$ 
  then
     $m := f(p)$ 
  end
```

```
increment
  when
     $p < q$ 
     $f(p) \leq f(q)$ 
  then
     $p := p + 1$ 
  end
```

```
decrement
  when
     $p < q$ 
     $f(q) < f(p)$ 
  then
     $q := q - 1$ 
  end
```

9	3	10	8	3	5
---	---	----	---	---	---

**$5 < 9$  (decrement)**

9	3	10	8	3	5
---	---	----	---	---	---

**$3 < 9$  (decrement)**

9	3	10	8	3	5
---	---	----	---	---	---

**$8 < 9$  (decrement)**

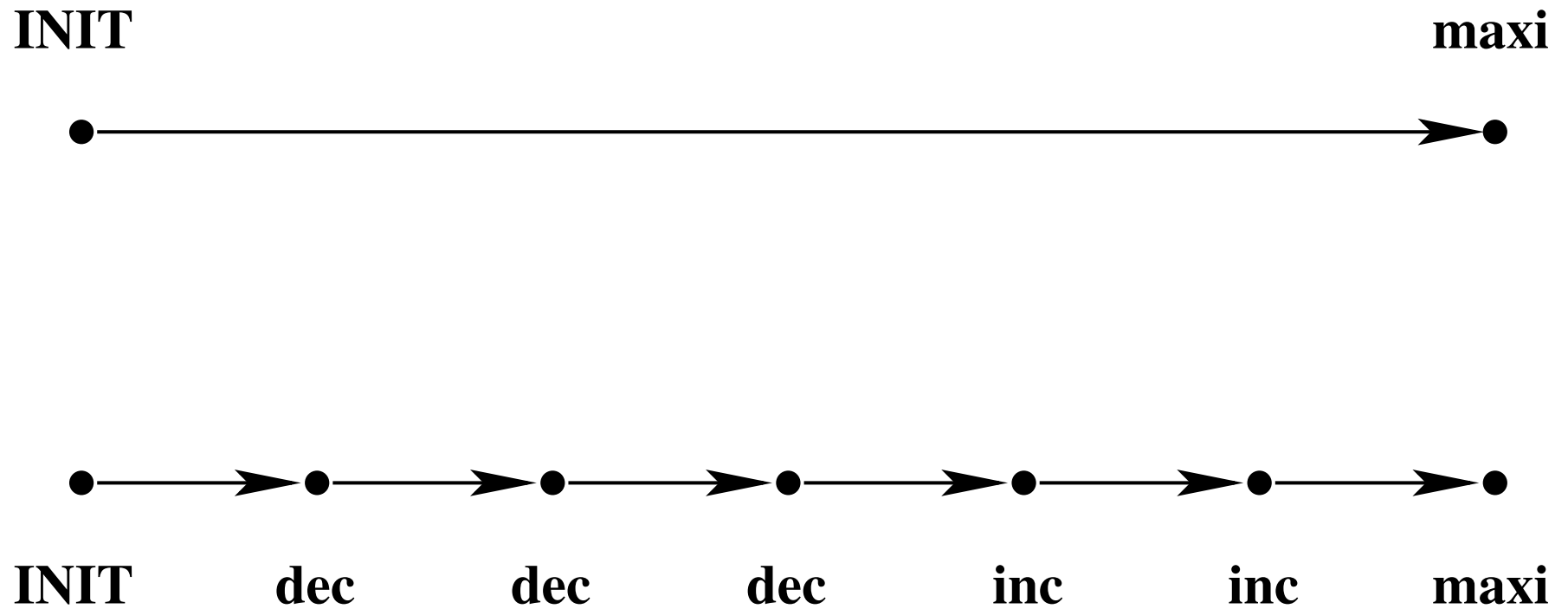
9	3	10	8	3	5
---	---	----	---	---	---

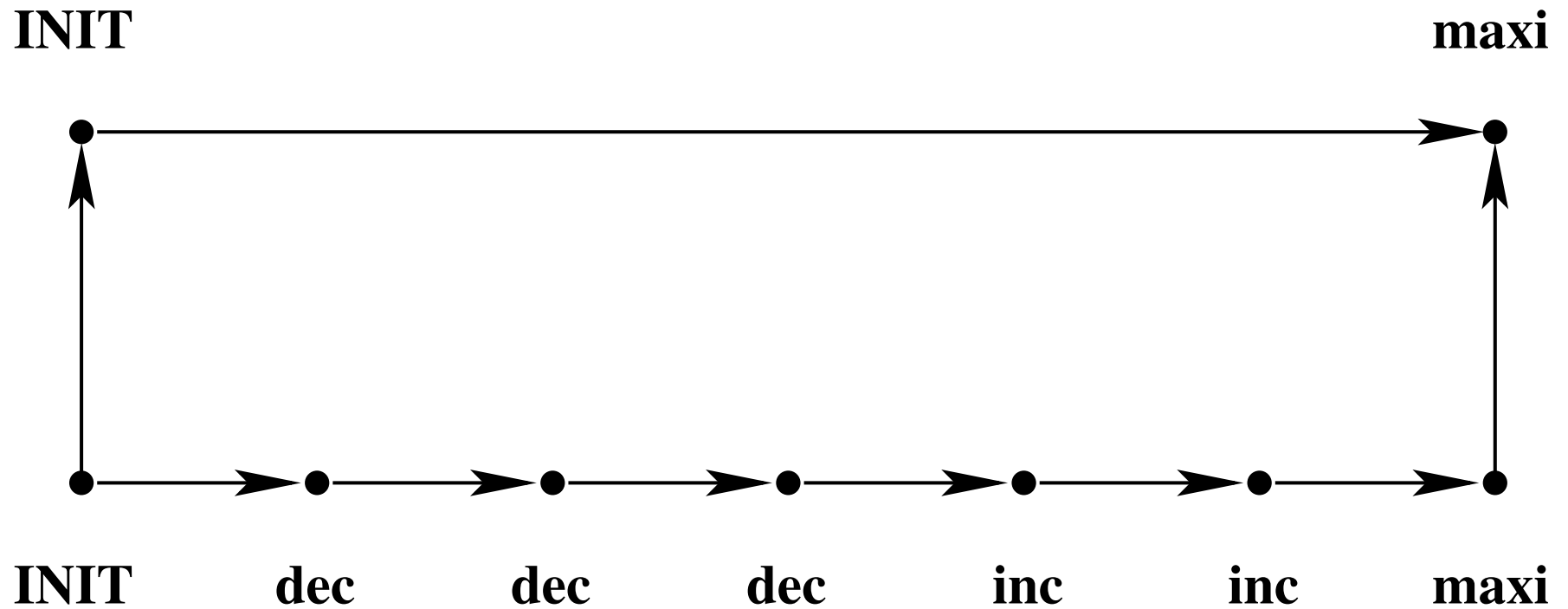
**$9 < 10$  (increment)**

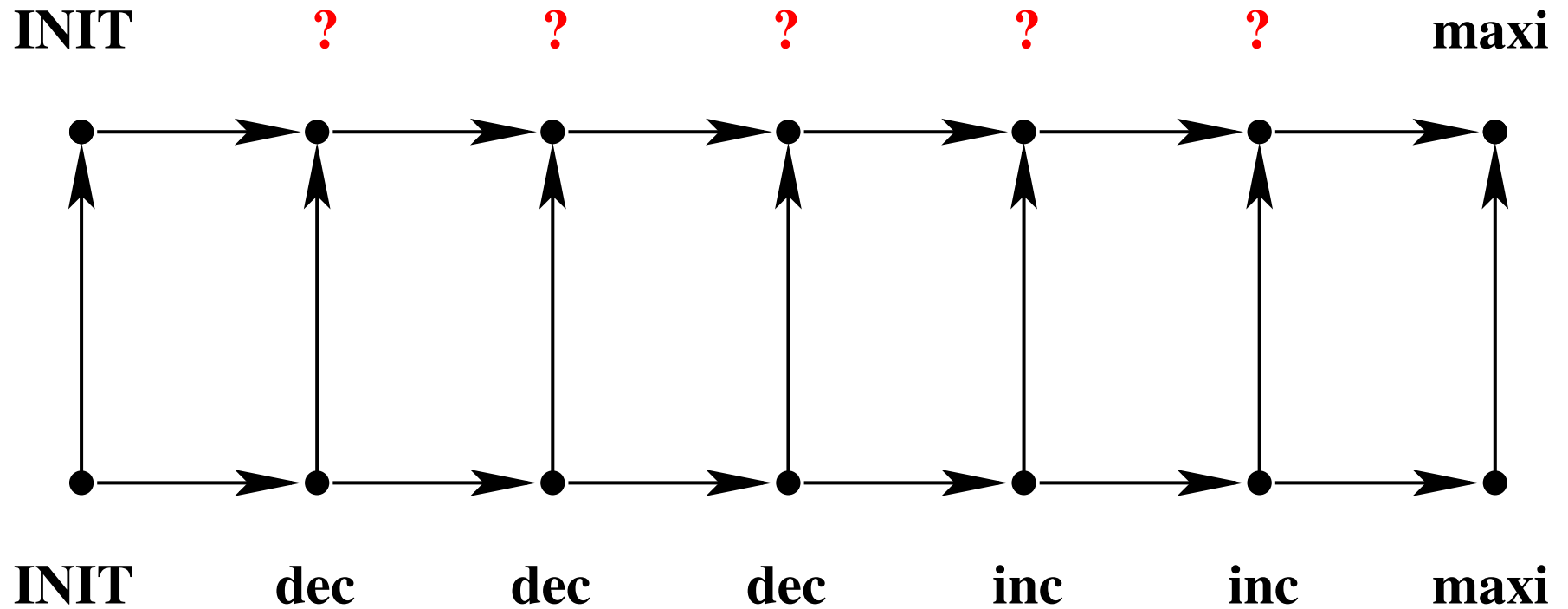
9	3	10	8	3	5
---	---	----	---	---	---

**$3 < 10$  (increment)**

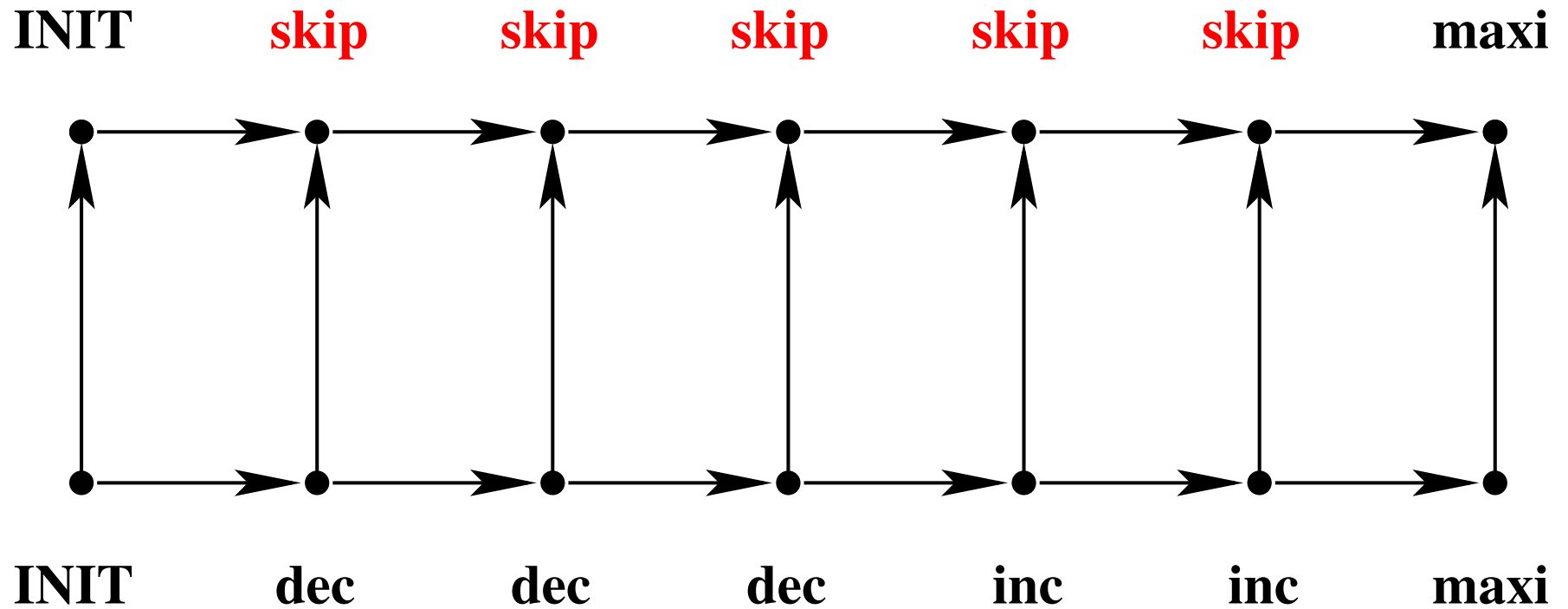
9	3	10	8	3	5
---	---	----	---	---	---





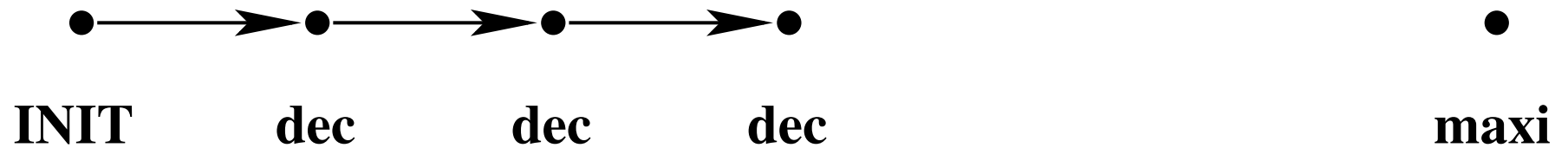




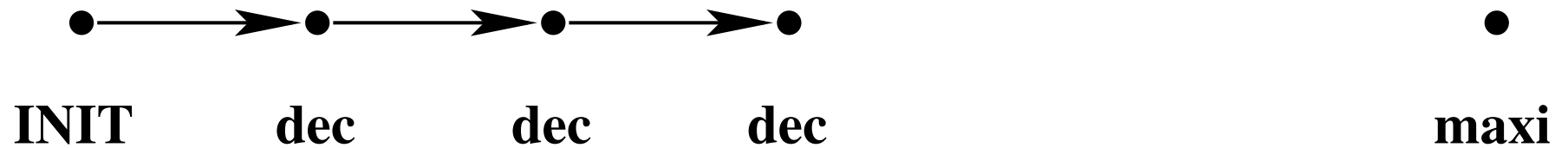


- Invariant maintenance
- Event refinement
  - guard strengthening
  - concrete action **simulates** the abstract one
- Well-definedness

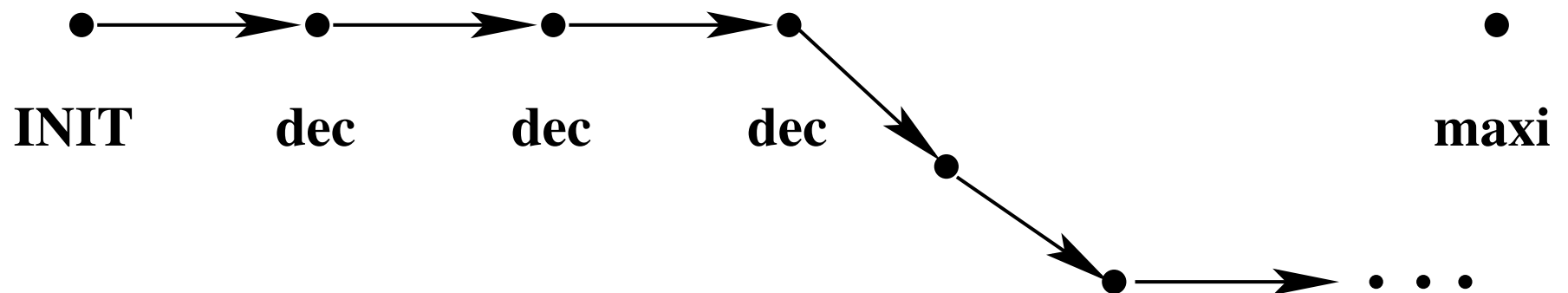
## - Early deadlock



## - Early deadlock



## - Divergence



- Invariant maintenance
- Event refinement
  - guard strengthening
  - concrete action **simulates** the abstract one
- Well-definedness
- Trace refinement
  - Disjunction of guards must hold (no early deadlock)
  - New events must be **convergent** (must decrease a variant)

```
INIT
  begin
     $m := 0$ 
     $p := 1$ 
     $q := n$ 
  end
```

```
maximum
  when
     $p = q$ 
  then
     $m := f(p)$ 
  end
```

```
increment
  when
     $p \neq q$ 
     $f(p) \leq f(q)$ 
  then
     $p := p + 1$ 
  end
```

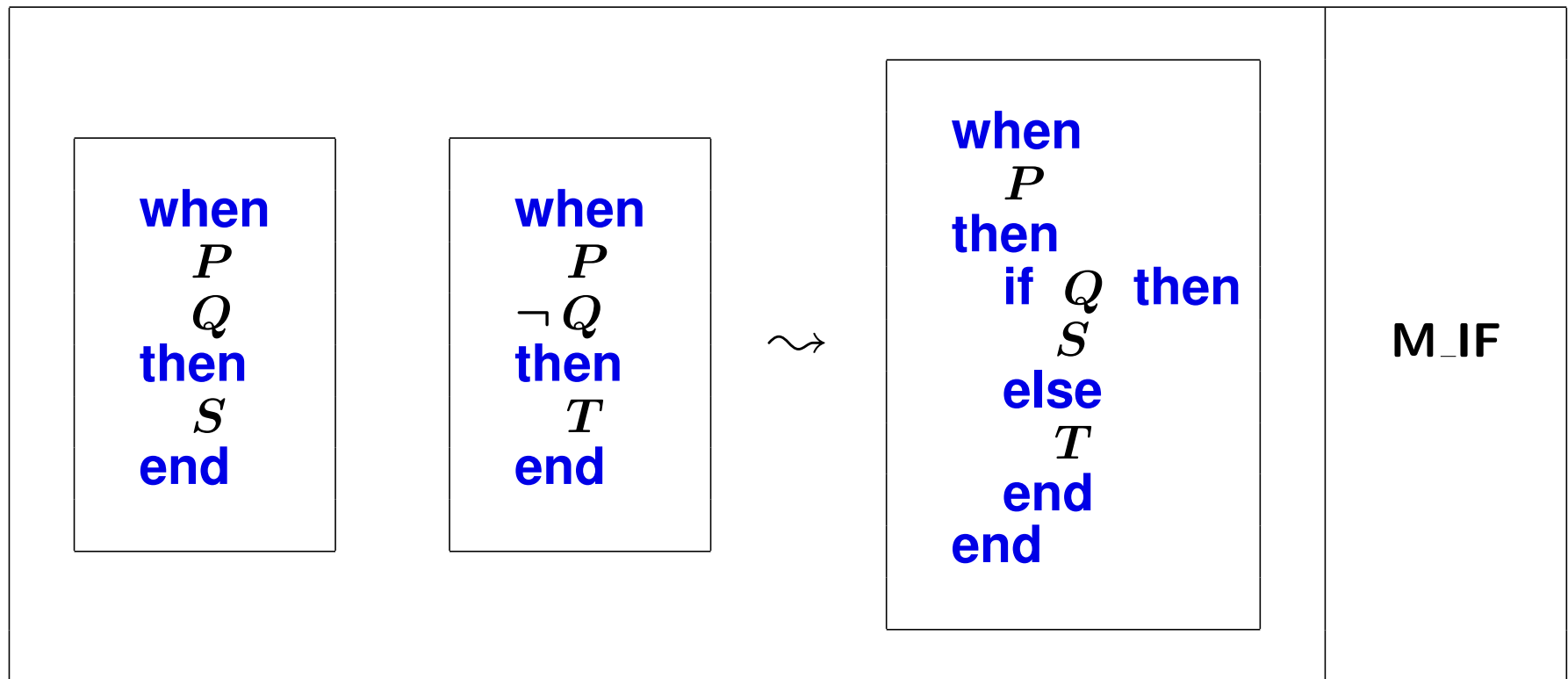
```
decrement
  when
     $p \neq q$ 
     $f(q) < f(p)$ 
  then
     $q := q - 1$ 
  end
```

**while** *condition* **do** *statement* **end**

**if** *condition* **then** *statement* **else** *statement* **end**

*statement* ; *statement*

*variable\_list* := *expression\_list*



- The two events must have been introduced at the same step



decrement

**when**

$p \neq q$

$f(q) < f(p)$

**then**

$q := q - 1$

**end**

increment

**when**

$p \neq q$

$f(p) \leq f(q)$

**then**

$p := p + 1$

**end**

decrement\_increment

**when**

$p \neq q$

**then**

**if**  $f(q) < f(p)$  **then**

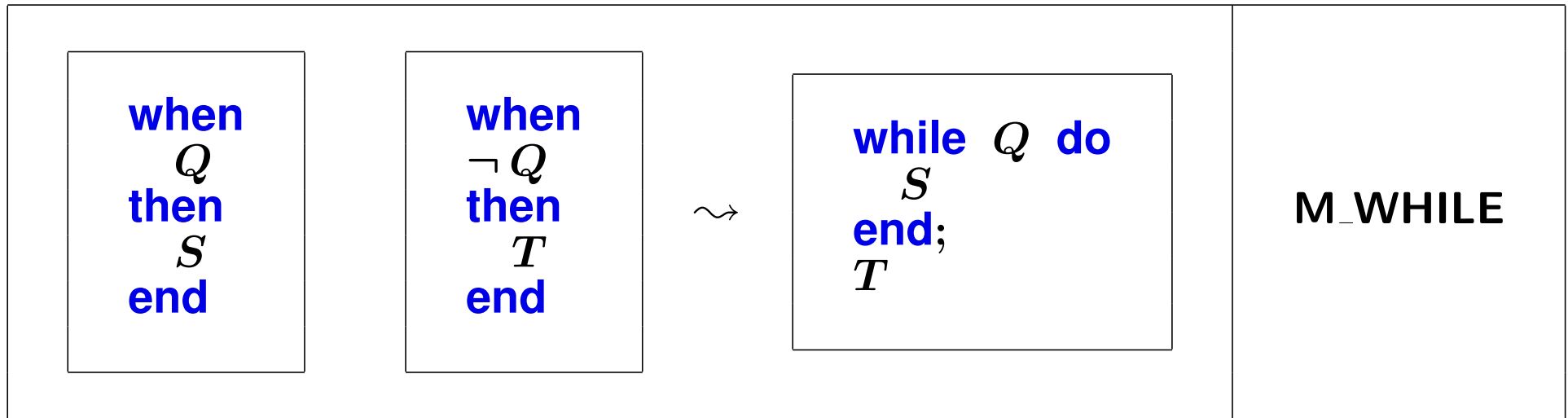
$q := q - 1$

**else**

$p := p + 1$

**end**

**end**

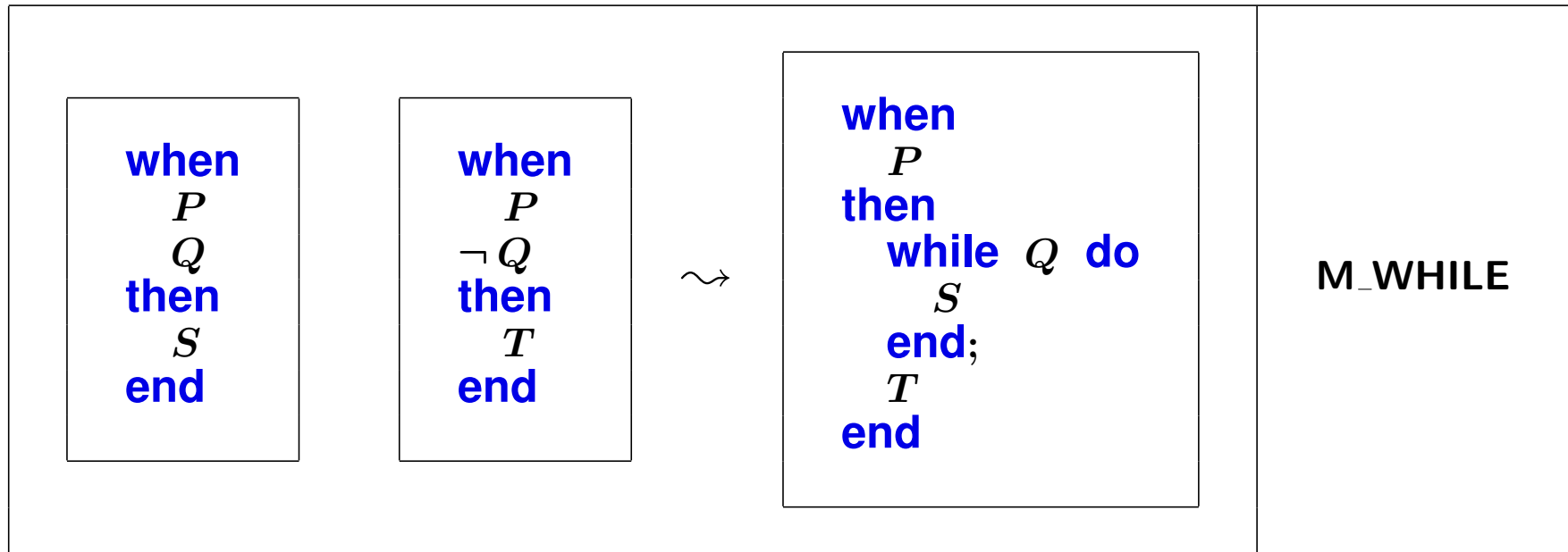


- The **first event** must have been introduced at **one** refinement step below the second one.

```
decrement_increment
  when
     $p \neq q$ 
  then
    if  $f(q) < f(p)$  then
       $q := q - 1$ 
    else
       $p := p + 1$ 
    end
  end
```

```
maximum
  when
     $p = q$ 
  then
     $m := f(p)$ 
  end
```

```
decrement_increment_maximum
  while  $p \neq q$  do
    if  $f(q) < f(p)$  then
       $q := q - 1$ 
    else
       $p := p + 1$ 
    end
  end;
   $m := f(p)$ 
```



- $P$  must be invariant under  $S$
- The first event must have been introduced at one refinement step below the second one.

- Once we have obtained an “event” **without guard**
- We add to it the event **init** by **sequential composition**
- We then obtain the final “program”

```
 $m, p, q := 0, 1, n;$  INIT  
while  $p < q$  do  
  if  $f(q) < f(p)$  then  
     $q := q - 1$  decrement  
  else  
     $p := p + 1$  increment  
  end  
end;  
 $m := f(p)$  maximum
```

```
INIT  
begin  
   $m := 0$   
   $p := 1$   
   $q := n$   
end
```

```
decrement  
when  
   $p < q$   
   $f(q) < f(p)$   
then  
   $q := q - 1$   
end
```

```
increment  
when  
   $p < q$   
   $f(p) \leq f(q)$   
then  
   $p := p + 1$   
end
```

```
maximum  
when  
   $p = q$   
then  
   $m := f(p)$   
end
```

- Modify the development to search for the **minimum of the array**

```
 $m, p, q := 0, 1, n;$  INIT  
while  $p < q$  do  
  if  $f(p) > f(q)$  then  
     $p := p + 1$  increment  
  else  
     $q := q - 1$  decrement  
  end  
end;  
 $m := f(p)$  maximum
```

- Write the **requirement document**
- Propose a **refinement strategy**
- Develop the model by **successive refinements** and **proofs**
- Perform some **animation** (if useful)



- Refinement allows us to build models **gradually**
- We build an **ordered sequence** of more precise models
- Each model is a **refinement** of the one preceding it
- A useful analogy: looking through a **microscope**
- **Spatial** (more variables) as well as **temporal** (more events) extensions