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# ABSOLUTE CONTINUITIES OF EXIT MEASURES AND TOTAL WEIGHTED OCCUPATION TIME MEASURES FOR SUPER-α-STABLE PROCESSES\*

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**Abstract** Suppose X is a super- $\alpha$ -stable process in  $\mathbb{R}^d$ ,  $(0 < \alpha < 2)$ , whose branching rate function is dt, and branching mechanism is of the form  $\Psi(z) = z^{1+\beta}$   $(0 < \beta \le 1)$ . Let  $X_{\tau}$  and  $Y_{\tau}$  denote the exit measure and the total weighted occupation time measure of X in a bounded smooth domain D, respectively. The absolute continuities of  $X_{\tau}$  and  $Y_{\tau}$  are discussed.

Key words Super- $\alpha$ -stable process, absolute continuity, exit measure, total weighted occupation time measure

2000 MR Subject Classification 60J80, 60J45

## 1 Introduction

For every Borel-measurable space  $(E, \mathcal{B}(E))$ , we denote by  $\mathcal{M}(E)$  the set of all finite measures on  $\mathcal{B}(E)$  endowed with the topology of weak convergence; denote by  $\mathcal{M}_c(E)$  the set of all finite measures on  $\mathcal{B}(E)$  with compact support; denote by  $\mathcal{M}_0(E)$  the set of all finite measures on  $\mathcal{B}(E)$  with finite points support. The expression  $\langle f, \mu \rangle$  stands for the integral of fwith respect to  $\mu$ , that is,  $\langle f, \mu \rangle = \int f(x)\mu(dx)$ . We write  $f \in \mathcal{B}(E)$  if f is a  $\mathcal{B}(E)$ -measurable function. Writing  $f \in p\mathcal{B}(E)(b\mathcal{B}(E))$  means that, in addition, f is positive (bounded). We put  $bp\mathcal{B}(E) = b\mathcal{B}(E) \cap p\mathcal{B}(E)$ . If  $E = \mathbf{R}^d$ , we simply write  $\mathcal{B}$  instead of  $\mathcal{B}(\mathbf{R}^d)$  and  $\mathcal{M}$  instead of  $\mathcal{M}(\mathbf{R}^d)$ .

Let  $\xi = \{\xi_s, \Pi_x, s \ge 0, x \in \mathbf{R}^d\}$  denote a symmetric  $\alpha$ - stable process  $(0 < \alpha < 2)$ . We denote by  $\mathcal{T}$  the set of all exit times from open sets in  $\mathbf{R}^d$ . Set  $\mathcal{F}_{\le r} = \sigma(\xi_s, s \le r)$ ;  $\mathcal{F}_{>r} = \sigma(\xi_s, s > r)$  and  $\mathcal{F}_{\infty} = \cup \{\mathcal{F}_{\le r}, r \ge 0\}$ . For  $\tau \in \mathcal{T}$ , we put  $F \in \mathcal{F}_{\ge \tau}$  if  $F \in \mathcal{F}_{\infty}$  and if for each  $r, \{F, \tau > r\} \in \mathcal{F}_{>r}$ .

Throughout this article, C denotes a constant which may change values from line to line.

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For  $\beta \in (0, 1]$ , there exists a Markov process  $X = (X_t, P_\mu)$  in  $\mathcal{M}$  such that the following conditions are satisfied:

(1) If f is a bounded continuous function, then  $\langle f, X_t \rangle$  is right continuous in t on  $[0, \infty)$ .

(2) For every  $\mu \in \mathcal{M}$  and for every  $f \in bp\mathcal{B}$ ,

$$P_{\mu} \exp\langle -f, X_t \rangle = \exp\langle -v_t, \mu \rangle, \tag{1}$$

where v is the unique solution of the integral equation

$$v_t(x) + \Pi_x \int_0^t (v_{t-s}(\xi_s))^{1+\beta} \mathrm{d}s = \Pi_x f(\xi_t).$$
(2)

Moreover, for every  $\tau \in \mathcal{J}$ , there are corresponding random measures  $X_{\tau}$  and  $Y_{\tau}$  on  $\mathbb{R}^d$  associated with the first exit time  $\tau$  such that, for  $f, g \in bp\mathcal{B}$ 

$$P_{\mu} \exp\{-\langle f, X_{\tau} \rangle - \langle g, Y_{\tau} \rangle\} = \exp\langle -u, \mu \rangle, \tag{3}$$

where u is the unique solution of the integral equation

$$u(x) + \Pi_x \int_0^\tau (u(\xi_s))^{1+\beta} ds = \Pi_x \Big[ \int_0^\tau g(\xi_s) ds + f(\xi_\tau) \Big].$$
 (4)

We call  $X = \{X_t, X_\tau, Y_\tau, P_\mu\}$  the super- $\alpha$ -stable process with branching mechanism  $z^{1+\beta}$ . Throughout this paper  $\tau$  denotes the first exit time of  $\xi$  from an open set D in  $\mathbb{R}^d$ , that is,  $\tau \equiv \inf\{t > 0 : \xi_t \notin D\}$ . And we call  $X_\tau$  the exit measure of X in D,  $Y_\tau$  the total weighted occupation time measure of X in D. From the properties of the super- $\alpha$ - stable process, we know that the support of  $X_\tau$  is contained in  $\overline{D}^c$ , the support of  $Y_\tau$  is contained in D. We will discuss the absolute continuity of  $X_\tau$  and  $Y_\tau$ .

#### 2 Absolute Continuity of $X_{\tau}$

From this point on, we always assume that D is a bounded smooth domain in  $\mathbb{R}^d$ . Let  $K_D(x, z)$  denote the Poisson kernel of  $\xi$  in D. For  $\nu \in \mathcal{M}(\overline{D}^c), f \in b\mathcal{B}(\overline{D}^c)$ , define

$$H_D \nu(x) = \begin{cases} \int_{\overline{D}^c} K_D(x, z) \nu(\mathrm{d}z), & d = 1, \\ A(d, \alpha) \int_{\overline{D}^c} K_D(x, z) \nu(\mathrm{d}z), & d \ge 2; \end{cases}$$
(5)

$$H_D f(x) = \Pi_x f(\xi_\tau) = \begin{cases} \int_{\overline{D}^c} K_D(x,z) f(z) \mathrm{d}z, & d = 1, \\ A(d,\alpha) \int_{\overline{D}^c} K_D(x,z) f(z) \mathrm{d}z, & d \ge 2, \end{cases}$$
(6)

where

$$A(d, lpha) = rac{lpha 2^{lpha - 1} \Gamma(rac{lpha + n}{2})}{\pi^{d/2} \Gamma(1 - rac{lpha}{2})}.$$

Obviously, if  $\nu(dy) = f(y)dy$ , then  $H_D f = H_D \nu$ .

No.2

The study of the fundamental solutions of the following integral equation plays an important role in the investigation of the absolute continuity of  $X_{\tau}$ ,

$$u(x) + \Pi_x \int_0^\tau u^{1+\beta}(\xi_s) \mathrm{d}s = H_D \nu(x), \quad x \in D,$$
(7)

where  $\nu \in \mathcal{M}_0(\overline{D}^c)$ .

For 
$$\nu = \sum_{i=1}^{m} \lambda_i \delta_{z_i}$$
 with  $z_1, z_2, \cdots, z_m \in \overline{D}^c$ ,  $\lambda_i \in \mathbf{R}^+$ ,  $i = 1, 2, \cdots, m$ , let  
 $\nu_n(\mathrm{d}z) = f_n(z)\mathrm{d}z$ , (8)

where dz denotes the Lebesgue measure on  $\overline{D}^c$  and

$$f_n(z) = \sum_{i=1}^m \lambda_i f_n^{z_i}(z), \tag{9}$$

$$f_n^{z_i}(z) = \begin{cases} \frac{1}{V(\overline{D}^c \cap B(z_i, 1/n))}, \ z \in B(z_i, 1/n), \\ 0, \qquad z \notin B(z_i, 1/n) \end{cases}$$
(10)

with  $V(\overline{D}^c \cap B(z_i, 1/n))$  being the volume of  $\overline{D}^c \cap B(z_i, 1/n)$ . Clearly, as  $n \to \infty$ ,  $\nu_n \xrightarrow{w} \nu$ .  $\nu_n$  is called the regularization of  $\nu$ .

We now give a theorem on the fundamental solutions of the integral equation (7).

**Theorem 2.1** Suppose  $D \subset \mathbf{R}^d$  is a bounded smooth domain,  $\nu = \sum_{i=1}^m \lambda_i \delta_{z_i}, z_1, z_2, \cdots, z_m \in \overline{D}^c, \lambda_i \in \mathbf{R}^+, i = 1, 2, \cdots, m$ . Let  $\nu_n$  be defined by (8), (9) and (10). Then we have

(1) (Existence and Uniqueness) There is exactly one measurable nonnegative function  $U[\nu]$  defined in D which satisfies the equation (7).

(2) (Continuity of Regularization) The solution  $U[\nu]$  is continuous with respect to the operation of regulation of  $\nu$  in the following sense:

$$U[\nu_n](\cdot) \xrightarrow{bp} U[\nu](\cdot)(n \to \infty) \quad \text{in } D.$$
(11)

(3) (First Derivative with Respect to Small Parameter)

$$\lambda^{-1}U[\lambda\nu](\cdot) \xrightarrow{bp} H_D\nu(\cdot)(\lambda \to 0) \quad \text{in } D.$$
(12)

Using the above theorem we get the main result with respect to the absolute continuity of  $X_{\tau}$ .

**Theorem 2.2** Suppose  $\mu \in \mathcal{M}_c(D)$ , there exists a random measurable function  $x_D$  defined on  $\overline{D}^c$  such that

$$P_{\mu}\{X_{\tau}(\mathrm{d}z) = x_D(z)\mathrm{d}z\} = 1.$$

that is,  $X_{\tau}$  is  $P_{\mu}$ -a.s. absolutely continuous with respect to the Lebesgue measure dz on  $\overline{D}^{c}$ .

### **3** Absolute Continuity of $Y_{\tau}$

Let  $G_D(x,y)$  denote the Green function of  $\xi$  in D. For  $\nu \in \mathcal{M}(D), f \in b\mathcal{B}(D)$ , define

$$G_D 
u(x) = \int_D G_D(x,y) 
u(\mathrm{d} y),$$

Obviously, if  $\nu(dy) = f(y)dy$ , then  $G_D f = G_D \nu$ .

The study of the fundamental solutions of the following integral equation plays an important role in the investigation of the absolute continuity of  $Y_{\tau}$ :

$$u(x) + \Pi_x \int_0^\tau u^{1+\beta}(\xi_s) \mathrm{d}s = G_D \nu(x), \quad x \in D \setminus N_\nu, \tag{14}$$

where  $N_{\nu} = \{x : G_D \nu(x) = \infty\}, \nu \in \mathcal{M}_0(D).$ 

For  $\nu = \sum_{i=1}^{m} \lambda_i \delta_{y_i}$  with  $y_1, y_2, \dots, y_m \in D, \ \lambda_i \in \mathbf{R}^+, \ i = 1, 2, \dots, m$ , let

$$\nu_n(\mathrm{d}y) = g_n(y)\mathrm{d}y,\tag{15}$$

where dy denotes the Lebesgue measure on  $\overline{D}$  and

$$g_n(y) = \sum_{i=1}^m \lambda_i g_n^{y_i}(y), \tag{16}$$

$$g_n^{y_i}(z) = \begin{cases} \frac{1}{V(D \cap B(y_i, 1/n))}, \ z \in B(y_i, 1/n), \\ 0, \qquad y \notin B(y_i, 1/n). \end{cases}$$
(17)

 $\nu_n$  is the regularization of  $\nu$ .

Note that for  $\nu = \sum_{i=1}^{m} \lambda_i \delta_{y_i}, y_1, y_2, \cdots, y_m \in D, \lambda_i \in \mathbf{R}^+, i = 1, 2, \cdots, m$ , we have  $N_{\nu} = \sup \{\nu \} = \{y_1, y_2, \cdots, y_m\}.$ 

We now give a theorem on the fundamental solutions of the integral equation (14).

**Theorem 3.1** Suppose  $D \subset \mathbf{R}^d$  is a bounded smooth domain,  $\nu = \sum_{i=1}^m \lambda_i \delta_{y_i}$ ,  $y_1, y_2, \dots, y_m \in D, \lambda_i \in \mathbf{R}^+, i = 1, 2, \dots, m$ . Let  $\nu_n$  be defined by (15), (16) and (17). Assume that there exists a sequence of bounded smooth domains  $(D_i)^{\infty}$  exists in  $D_i \downarrow (D_i)^{\infty}$ .

that there exists a sequence of bounded smooth domains  $\{D_n\}_{n=1}^{\infty}$  satisfying  $D_n \uparrow (D \setminus N_{\nu})$  as  $n \uparrow \infty$  and

$$\limsup_{n \to \infty} \prod_{x} \int_{\tau_k}^{\tau} (G_D \nu_n(\xi_s))^{1+\beta} \mathrm{d}s \to 0 (k \to \infty), \quad \text{for } x \in D \setminus N_{\nu}, \tag{18}$$

where  $\tau_k \equiv \inf\{t > 0 : \xi_t \notin D_k\}$ . Then we have

(1) (Existence and Uniqueness) There is exactly one measurable nonnegative function  $U[\nu]$  defined in D which satisfies the equation (14).

(2) (Continuity of Regularization) The solution  $U[\nu]$  is continuous with respect to the operation of regulation of  $\nu$  in the following sense:

$$U[\nu_n](\cdot) \xrightarrow{bp} U[\nu](\cdot)(n \to \infty) \quad \text{in each compact subsect } K \quad \text{of} \quad D \setminus N_{\nu}. \tag{19}$$

(3) (First Derivative with Respect to Small Parameter)

$$\lambda^{-1}U[\lambda\nu](\cdot) \xrightarrow{bp} G_D\nu(\cdot)(\lambda \to 0) \text{ in each compact subsect } K \text{ of } D \setminus N_\nu.$$
(20)

Using the above theorem we get the main results with respect to the absolute continuity of  $Y_{\tau}$ .

**Theorem 3.2** Suppose there exists a Borel subset N of D with 0 Lebesgue measure such that for every  $\nu \in M_0(D \setminus N)$  condition (18) holds. Then for  $\mu \in \mathcal{M}_c(D)$ , there exists a random measurable function  $y_D$  defined on D such that

$$P_{\mu}\{Y_{\tau}(\mathrm{d}y) = y_D(y)\mathrm{d}y\} = 1$$

that is,  $Y_{\tau}$  is  $P_{\mu}$ -a.s. absolutely continuous with respect to the Lebesgue measure dy on D.

**Theorem 3.3** Suppose  $\mu \in \mathcal{M}_c(D)$ . When  $d < \alpha + \alpha/\beta$ ,  $Y_\tau$  is  $P_{\mu}$ -a.s. absolutely continuous with respect to the Lebesgue measure dy on D.

## 4 Proofs of Theorems in Sections 2 and 3

In the sequel we will use the following two lemmas. By the Fubini theorem and the Markov property of  $\xi$ , using an argument similar to that appearing in Lemma 2.1 in [1], we have the following lemma:

**Lemma 4.1** Let  $\tau \in \mathcal{T}$ ,  $g \in bp\mathcal{B}$ , C is a positive constant. Assume that  $\omega \in \mathcal{B}$ ,  $F \in \mathcal{F}_{\geq \tau}$  satisfy

$$\Pi_x \int_0^\tau |\omega(\xi_s)| \mathrm{d} s < \infty, \quad \Pi_x |F| < \infty, \quad x \in \mathbf{R}^d.$$

Then

$$g(x) = \Pi_x \Big[ \mathrm{e}^{-C au} F + \int_0^ au \mathrm{e}^{-Cs} \omega(\xi_s) \mathrm{d}s \Big]$$

if and only if

$$g(x) + \Pi_x \int_0^{ au} Cg(\xi_s) \mathrm{d}s = \Pi_x \Big[ F + \int_0^{ au} \omega(\xi_s) \mathrm{d}s \Big].$$

We will also use another lemma which is a modification of Lemma 2.7.1 in [2].

**Lemma 4.2** Let Y be a random measure defined on a probability space  $(\Omega, \mathcal{B}(E), P)$  with values in  $\mathcal{M}(E)$ . Assume that

(1) there exists a Borel subset N of E of Lebesgue measure 0 such that for  $\forall z \in E \setminus N$ , there exists a sequence  $\varepsilon_n(z) \to 0 \ (n \to \infty)$ , and as  $n \to \infty$ 

$$\frac{Y(O_{\varepsilon_n}(z))}{V(O_{\varepsilon_n}(z))} \stackrel{d}{\longrightarrow} \eta(z),$$

where  $O_{\varepsilon}(z) \equiv \{x : \|x - z\| < \varepsilon\}, \varepsilon > 0$ , and  $\eta(z)$  is a random variable with  $P\eta(z) < \infty$ .

(2)  $P\langle f, Y \rangle = \int_E f(z) P \eta(z) dz$  for all  $f \in bp\mathcal{B}(E)$ .

Then there exists a random measurable function y in E such that

$$P\{Y(\mathrm{d}z) = y(z)\mathrm{d}z\} = 1,$$

and for  $\forall z \in E \setminus N$ , the random variable y(z) and  $\eta(z)$  are identically distributed. In particular, Y is P-a.s. absolutely continuous with respect to dz in E.

**Proof of Theorem 2.1** Assume that,  $u_n, n = 1, 2, \cdots$  is a nonnegative solution of the equation (7) with  $\nu$  replaced by  $\nu_n$ , that is,  $u_n$  satisfies the following equation

$$u_n(x) = H_D \nu_n(x) - \Pi_x \int_0^\tau u_n^{1+\beta}(\dot{\xi_s}) ds = \Pi_x f_n(\xi_\tau) - \Pi_x \int_0^\tau u_n^{1+\beta}(\xi_s) ds.$$
(21)

However, for  $x \in D$ ,

$$\Pi_x f_n(\xi_\tau) = \begin{cases} \int_{\overline{D}^c} K_D(x, z) \nu_n(\mathrm{d} z), & d = 1, \\ A(d, \alpha) \int_{\overline{D}^c} K_D(x, z) \nu_n(\mathrm{d} z), & d \ge 2. \end{cases}$$

Suppose d = 1, without loss of generality, let D = (a, b). From [3] we know for  $x \in D, z \in \overline{D}^c$ , the following estimate holds:

$$K_{D}(x,z) \leq C \frac{|x-a|^{\alpha/2}|x-b|^{\alpha/2}}{|z-a|^{\alpha/2}|z-b|^{\alpha/2}} \frac{1}{|x-z|}$$
  
$$\leq C \frac{|x-a|^{\alpha/2}|x-b|^{\alpha/2}}{|z-a|^{\alpha/2}|z-b|^{\alpha/2}} \frac{1}{\delta(z)}$$
  
$$\leq C \frac{1}{|z-a|^{\alpha/2}|z-b|^{\alpha/2}} \frac{1}{\delta(z)} \leq C \frac{1}{\delta(z)^{1+\alpha}},$$
(22)

where  $\delta(z) \equiv \min\{|z-a|, |z-b|\}.$ 

Suppose  $d \ge 2$ , from [4] we know for  $x \in D, z \in \overline{D}^c$ , the following estimate holds:

$$K_{D}(x,z) \leq \frac{C|x-z|^{\alpha/2}}{\delta(z)^{\alpha/2}(1+\delta(z))^{\alpha/2}} \frac{1}{|x-z|^{d}} = \frac{C}{\delta(z)^{\alpha/2}(1+\delta(z))^{\alpha/2}} \frac{1}{|x-z|^{d-\alpha/2}}$$

$$\leq \frac{C}{\delta(z)^{\alpha/2}(1+\delta(z))^{\alpha/2}} \frac{1}{\delta(z)^{d-\alpha/2}} \leq \frac{C}{\delta(z)^{d}},$$
(23)

where  $\delta(x) = d(x, \partial D)$  denotes the distance between x and  $\partial D$ .

Noticing that  $\nu_n$  is only charged on  $B(z_i, 1/n), i = 1, 2, \dots, m$ , from (22) and (23), we conclude that there exists an  $n_0$  such that, for  $n \ge n_0$ ,

$$\Pi_x f_n(\xi_\tau) \le C \int_{\overline{D}^c} \nu_n(\mathrm{d} z) \le C$$

Then from  $\nu_n \xrightarrow{w} \nu$  it follows that

$$\Pi_x f_n(\xi_\tau) \xrightarrow{bp} H_D \nu(x), \quad n \to \infty, \quad x \in D.$$
(24)

Let

$$M = \left(\sup_{x \in D, n \ge n_0} H_D f_n(x)\right) \lor 1, \quad \eta = (1+\beta)M^{\beta}, \quad R(z) = \eta z - z^{1+\beta}$$

From (21) it follows that for  $x \in D$ ,  $n \ge n_0$ ,  $0 \le u_n(x) \le M$ . Since  $0 \le \frac{d(R(z))}{dz} \le \eta$  for  $z \in (0, M)$ , we have  $|R(z_1) - R(z_2)| \le \eta |z_1 - z_2|$ ,  $0 \le z_1, z_2 \le M$ .

Then we get, for  $x \in D$ ,  $m, n \ge n_0$ ,

$$|R(u_m(x)) - R(u_n(x))| \le \eta |u_m(x) - u_n(x)|.$$
(25)

Using Lemma 4.1 with

$$g = u_n, \quad F = f_n(\xi_\tau), \quad \omega = \eta u_n - u_n^{1+\beta}, \quad C = \eta,$$

we get

$$u_n(x) = \Pi_x[e^{-\eta\tau} f_n(\xi_\tau)] + \Pi_x \int_0^\tau e^{-\eta s} R(u_n(\xi_s)) \mathrm{d}s.$$
(26)

From (25) and (26) we have for  $x \in D$ ,  $m, n \ge n_0$ ,

$$|u_m(x) - u_n(x)| \le \Pi_x e^{-\eta \tau} |f_m(\xi_\tau) - f_n(\xi_\tau)| + \Pi_x \int_0^\tau e^{-\eta s} \eta |u_m(\xi_s) - u_n(\xi_s)| ds.$$
(27)

Iterating the inequality (27)  $l \ge 1$  times, using the strong Markov property of  $\xi$  and the fact that  $\int \cdots \int_{0 < s_1 < \cdots < s_l < s} = \frac{1}{l!} \int_0^s \cdots \int_0^s$ , we get

$$|u_m(x) - u_n(x)| \le \Pi_x |f_m(\xi_\tau) - f_n(\xi_\tau)| + 2M\Pi_x \int_0^\tau \eta e^{-\eta s} \frac{(\eta s)^l}{l!} ds.$$
(28)

From (24) we have

$$\lim_{m,n\to\infty} \Pi_x |f_m(\xi_\tau) - f_n(\xi_\tau)| = 0, \quad x \in D.$$
<sup>(29)</sup>

Noticing  $\prod_x \tau < \infty$ , and by using the dominated convergence theorem it follows that

$$\lim_{l \to \infty} \Pi_x \int_0^\tau \eta \mathrm{e}^{-\eta s} \frac{(\eta s)^l}{l!} \mathrm{d}s = 0.$$
(30)

Combing (28), (29) and (30), we have

$$\limsup_{m,n\to\infty}|u_m(x)-u_n(x)|=0,\quad x\in D.$$

Therefore there exists a nonnegative measurable function u in D such that,

$$u_n(x) \xrightarrow{bp} u(x), \quad n \to \infty, \quad x \in D.$$

By the dominated convergence theorem it follows that, u solves the equation (7). Repeating the procedure from the beginning with two different solutions of the equation (7) instead of  $u_n$  and  $u_m$ , respectively, we can conclude that u is uniquely determined by the equation. Summarizing the above, we now have proved the statements (1) and (2) of Theorem 2.1.

It remains to verify the asymptotic property (12). Let  $U[\lambda\nu]$  be the nonnegative solution of the equation (7) with  $\nu$  replaced by  $\lambda\nu$ , then

$$\begin{aligned} |\lambda^{-1}U[\lambda\nu] - H_D\nu|(x) &= \Pi_x \int_0^\tau \lambda^{-1} U^{1+\beta}[\lambda\nu](\xi_s) \mathrm{d}s \\ &\leq \Pi_x \int_0^\tau \lambda^{-1} (\lambda H_D\nu(\xi_s))^{1+\beta} \mathrm{d}s \\ &= \lambda^\beta \Pi_x \int_0^\tau (H_D\nu(\xi_s))^{1+\beta} \mathrm{d}s. \end{aligned}$$
(31)

Noticing that  $\nu$  is only charged on finite points, we know that  $H_D\nu(\cdot)$  is bounded in D, it follows that

$$\Pi_x \int_0^\tau (H_D \nu(\xi_s))^{1+\beta} \mathrm{d}s < \infty.$$

Let  $\lambda \downarrow 0$  in (31), it follows that

$$\lim_{\lambda \downarrow 0} |\lambda^{-1} U[\lambda \nu] - H_D \nu|(x) \leq \lim_{\lambda \downarrow 0} \lambda^{\beta} \Pi_x \int_0^{\tau} (H_D \nu(\xi_s))^{1+\beta} \mathrm{d}s = 0.$$

Therefore we conclude that

$$\lambda^{-1}U[\lambda\nu](\cdot) \xrightarrow{p} H_D\nu(\cdot)(\lambda \to 0) \quad \text{in } D.$$

But  $\lambda^{-1}U[\lambda\nu](\cdot)$  are dominated by  $H_D\nu(\cdot)$  and  $H_D\nu(\cdot)$  is bounded in D. The statement (3) follows.

**Proof of Theorem 2.2** (1) We choose  $z_1, z_2, \dots, z_m \in \overline{D}^c$  and let

$$\nu_n(\mathrm{d} z) = \sum_{i=1}^m \lambda_i f_n^{z_i}(z) \mathrm{d} z,$$

where  $f_n^{z_i}(z)$  is given by (10),  $\lambda_i \in \mathbf{R}^+, i = 1, 2, \cdots, m$ . We have by (3)

$$P_{\mu} \exp\langle -\sum_{i=1}^{m} \lambda_{i} f_{n}^{z_{i}}, X_{\tau} \rangle = \exp\langle -U(\nu_{n}), \mu \rangle,$$

where  $U[\nu_n]$  is the unique solution of (7) with  $\nu$  replaced by  $\nu_n$ . Clearly

$$\nu_n \xrightarrow{w} \nu \equiv \sum_{i=1}^m \lambda_i \delta_{z_i}, \quad n \to \infty.$$

By Theorem 2.1

$$U[\nu_n] \xrightarrow{bp} U[\nu](n \to \infty) \quad \text{in } D,$$
 (32)

where  $U[\nu]$  is the unique solution of (7). Then it follows that

$$\exp\langle -U[\nu_n], \mu\rangle \to \exp\langle -U[\nu], \mu\rangle, \quad n \to \infty.$$
(33)

Let  $O_n(z_i) \equiv \{x \in \overline{D}^c : |x - z_i| < \frac{1}{n}\}$ , then the left-hand side of (33) determines the Laplace transform of the random vector

$$\left(\frac{X_{\tau}(O_n(z_1))}{V(O_n(z_1))},\frac{X_{\tau}(O_n(z_2))}{V(O_n(z_2))},\cdots,\frac{X_{\tau}(O_n(z_m))}{V(O_n(z_m))}\right).$$

Note that

$$\langle U[
u], \mu 
angle \leq \langle H_D
u, \mu 
angle \leq \|\mu\| \sup_{x \in \mathrm{supp}(\mu)} H_D
u(x) \leq C|\lambda|,$$

where  $|\lambda| = \max_i \lambda_i$ . Therefore the right-hand side of (33) determines the Laplace transform of a random vector, we denote  $(\eta(z_1), \eta(z_2), \dots, \eta(z_m))$ . Consequently as  $n \to \infty$ ,

$$\left(\frac{X_{\tau}(O_n(z_1))}{V(O_n(z_1))}, \frac{X_{\tau}(O_n(z_2))}{V(O_n(z_2))}, \cdots, \frac{X_{\tau}(O_n(z_m))}{V(O_n(z_m))}\right) \stackrel{d}{\longrightarrow} (\eta(z_1), \eta(z_2), \cdots, \eta(z_m)),$$

where

$$P_{\mu} \exp\left\{-\sum_{i=1}^{m} \lambda_{i} \eta(z_{i})\right\} = \exp\langle-U[\nu], \mu\rangle.$$
(34)

Assumption (1) of Lemma 4.2 is satisfied.

(2) Set m = 1, and write  $\lambda$  and z instead of  $\lambda_1$  and  $z_1$ , respectively. Then

$$P_{\mu} \exp\{-\lambda \eta(z)\} = \exp\langle -U[\lambda \delta_z], \mu \rangle.$$
(35)

Differentiating with respect to  $\lambda$  at  $\lambda = 0$  in (35), we get

$$P_{\mu}(-\eta(z)) = \exp\langle -U[\lambda \delta_{oldsymbol{z}}], \mu 
angle \langle -rac{\mathrm{d} U[\lambda \delta_{oldsymbol{z}}]}{\mathrm{d} \lambda}, \mu 
angle |_{\lambda=0}.$$

Further by (12)

$$egin{aligned} P_{\mu}(\eta(z)) &= \langle H_D \delta_z, \mu 
angle \ &= egin{cases} \langle K_D(\cdot, z), \mu 
angle &= \int_{\overline{D}^c} K_D(x, z) \mu(dx), & d = 1, \ &\langle A(d, lpha) K_D(\cdot, z), \mu 
angle &= \int_{\overline{D}^c} A(d, lpha) K_D(x, z) \mu(dx), & d \geq 2. \end{aligned}$$

By (3) it follows that for  $\forall f \in bp\mathcal{B}(\overline{D}^c)$ 

$$P_{\mu} \exp\langle -\lambda f, X_{\tau} \rangle = \exp\langle -v_{\lambda}, \mu \rangle, \tag{36}$$

where  $v_{\lambda}$  is the unique solution of the integral equation

$$v_{\lambda}(x) = \lambda \Pi_x f(\xi_{\tau}) - \Pi_x \int_0^{\tau} v_{\lambda}^{1+\beta}(\xi_s) \mathrm{d}s.$$
(37)

Differentiating with respect to  $\lambda$  at  $\lambda = 0$  in (36), we get

$$\begin{split} P_{\mu}\langle f, X_{\tau} \rangle &= \langle \Pi.f(\xi_{\tau}), \mu \rangle = \int_{D} \Pi_{x} f(\xi_{\tau}) \mu(\mathrm{d}x) \\ &= \begin{cases} \int_{D} \mu(\mathrm{d}x) \int_{\overline{D}^{c}} K_{D}(x,z) f(z) \mathrm{d}z, & d = 1 \\ \int_{D} \mu(\mathrm{d}x) \int_{\overline{D}^{c}} A(d,\alpha) K_{D}(x,z) f(z) \mathrm{d}z, & d \geq 2 \end{cases} \\ &= \begin{cases} \int_{\overline{D}^{c}} f(z) \int_{D} K_{D}(x,z) \mu(\mathrm{d}x) \mathrm{d}z, & d = 1 \\ \int_{\overline{D}^{c}} f(z) \int_{D} A(d,\alpha) K_{D}(x,z) \mu(\mathrm{d}x) \mathrm{d}z, & d \geq 2 \end{cases} \\ &= \int_{\overline{D}^{c}} f(z) P_{\mu}(\eta(z)) \mathrm{d}z. \end{split}$$

Assumption (2) of Lemma 4.2 is satisfied.

Therefore the statements of Theorem 2.2 follow from Lemma 4.2.

**Proof of Theorem 3.1** Assume  $u_n, n = 1, 2, \cdots$  is a nonnegative solution of the equation (14) with  $\nu$  replaced by  $\nu_n$ , that is,  $u_n$  satisfies the following equation

$$u_n(x) = G_D \nu_n(x) - \prod_x \int_0^\tau u_n^{1+\beta}(\xi_s) \mathrm{d}s = \int_D G_D(x,y) g_n(y) \mathrm{d}y - \prod_x \int_0^\tau u_n^{1+\beta}(\xi_s) \mathrm{d}s.$$
(38)

From [3] and [4] we know that for  $x, y \in D$  the following estimate holds: for d = 1

$$G_D(x,y) \le \begin{cases} C|\ln\frac{1}{|x-y|}|, & \alpha = 1, \\ C|x-y|^{\alpha-1}, & \alpha \neq 1; \end{cases}$$
(39)

for  $d \geq 2$ 

$$G_D(x,y) \le C \frac{1}{|x-y|^{d-\alpha}}.$$
(40)

Let K be any fixed compact subset of  $D \setminus N_{\nu}$ . Noticing that  $g_n$  is only non-zero on  $B(y_i, 1/n), i = 1, 2, \dots, m$ , we have there exists an  $n_0$  such that, for  $n \ge n_0$ ,  $g_n = 0$  in a neighborhood of K. Therefore, there exists constant C > 0 such that

$$G_D(x,y) \leq C, \quad \forall x \in K, y \in B(y_i, 1/n) (n \geq n_0, i = 1, 2, \cdots, m).$$

Hence we have

$$0 \le u_n(x) \le \int_D G_D(x, y) g_n(y) \mathrm{d}y \le C \int_D g_n(y) \mathrm{d}y = C \nu_n(D) \le C, \quad x \in K, \quad n \ge n_0.$$
(41)

Therefore for  $\forall k \geq 1$ , there exists an integer  $n_k$  such that, for  $n \geq n_k$ ,  $g_n = 0$  and  $G_D g_n$  are uniformly bounded in  $D_k$ . Let

$$M_k = \left(\sup_{x \in D_k, n \ge n_k} G_D g_n(x)\right) \vee 1, \quad \eta_k = (1+\beta) M_k^\beta, \quad R_k(z) = \eta_k z - z^{1+\beta}.$$

From (38) it follows that for  $x \in D_k$ ,  $n \ge n_k$ ,  $0 \le u_n(x) \le M_k$ . Since  $0 \le \frac{d(R_k(z))}{dz} \le \eta_k$  for  $z \in (0, M_k)$ , we have

$$|R_k(z_1) - R_k(z_2)| \le \eta_k |z_1 - z_2|, \quad 0 \le z_1, z_2 \le M_k.$$

Then we get, for  $x \in D_k, m, n \ge n_k$ ,

$$|R(u_m(x)) - R(u_n(x))| \le \eta_k |u_m(x) - u_n(x)|.$$
(42)

Using Lemma 4.1 with

$$g=u_n, \quad F=\int_{ au_k}^ au g_n(\xi_s)\mathrm{d}s -\int_{ au_k}^ au u_n^{1+eta}(\xi_s)\mathrm{d}s, \quad \omega=\eta_k u_n+g_n-u_n^{1+eta}, \quad C=\eta_k,$$

and noticing that, for all  $n \ge n_k$ ,  $g_n = 0$  in  $D_k$ , we get

$$u_n(x) = \Pi_x \left[ e^{-\eta_k \tau_k} \int_{\tau_k}^{\tau} (g_n(\xi_s) - u_n^{1+\beta}(\xi_s)) ds \right] + \Pi_x \int_0^{\tau_k} e^{-\eta_k s} R(u_n(\xi_s)) ds.$$
(43)

From (42) and (43), using the strong Markov property of  $\xi$  and noticing that for  $x \in D$ ,  $u_m(x) \leq G_D g_m(x), u_n(x) \leq G_D g_n(x)$ . We have for  $x \in D \setminus N_\nu, m, n \geq n_k$  and sufficiently large k (satisfying  $x \in D_k$ ),

$$|u_{m}(x) - u_{n}(x)| \leq \Pi_{x} e^{-\eta_{k}\tau_{k}} \left| \Pi_{\xi_{\tau_{k}}} \int_{0}^{\tau} (g_{m}(\xi_{s}) - g_{n}(\xi_{s})) \mathrm{d}s \right|$$
  
+  $\Pi_{x} e^{-\eta_{k}\tau_{k}} \int_{\tau_{k}}^{\tau} [(G_{D}g_{n}(\xi_{s}))^{1+\beta} + (G_{D}g_{m}(\xi_{s}))^{1+\beta})] \mathrm{d}s$ (44)  
+  $\Pi_{x} \int_{0}^{\tau_{k}} e^{-\eta_{k}s} \eta_{k} |u_{m}(\xi_{s}) - u_{n}(\xi_{s})| \mathrm{d}s.$ 

Using Fubini theorem and the Markov property of  $\xi$ , iterating the inequality (44)  $l \ge 1$  times yields

$$|u_{m}(x) - u_{n}(x)| \leq \Pi_{x} \Big| \Pi_{\xi_{\tau_{k}}} \int_{0}^{\tau} (g_{m}(\xi_{s}) - g_{n}(\xi_{s})) \mathrm{d}s \Big| + \Pi_{x} \int_{\tau_{k}}^{\tau} [(G_{D}g_{m}(\xi_{s}))^{1+\beta} + (G_{D}g_{n}(\xi_{s}))^{1+\beta}] \mathrm{d}s \qquad (45) + 2M_{k}\Pi_{x} \int_{0}^{\tau_{k}} \eta_{k} \mathrm{e}^{-\eta_{k}s} \frac{(\eta_{k}s)^{l}}{l!} \mathrm{d}s.$$

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From  $\nu_n \xrightarrow{w} \nu$ , it follows that for fixed k,

$$\Pi_x \int_0^\tau g_n(\xi_s) \mathrm{d}s = G_D g_n(x) = G_D \nu_n(x) \xrightarrow{bp} G_D \nu(x), \quad n \to \infty, \quad x \in \bar{D}_k$$

From the dominated convergence theorem, we obtain

$$\lim_{m,n\to\infty} \Pi_x \left| \Pi_{\xi_{\tau_k}} \int_0^\tau (g_m(\xi_s) - g_n(\xi_s)) \mathrm{d}s \right| = 0.$$
(46)

Noticing  $\prod_x \tau_k < \infty$ , and using the dominated convergence theorem, it follows that

$$\lim_{l \to \infty} \prod_x \int_0^{\tau_k} \eta_k e^{-\eta_k s} \frac{(\eta_k s)^l}{l!} ds = 0.$$
(47)

Combining (45), (46), (47) and the condition (18), we have

$$\limsup_{m,n o\infty} |u_m(x)-u_n(x)|=0, \quad x\in D\setminus N_
u.$$

Therefore there exists a nonnegative measurable function u in  $D \setminus N_{\nu}$  such that, for each compact subset  $K \subset D \setminus N_{\nu}$ ,

$$u_n(x) \xrightarrow{bp} u(x), \quad n \to \infty, \quad x \in K.$$

Repeating the procedure from the beginning with this u instead of  $u_m$  we conclude that u solves the equation (14). By similar arguments we conclude that u is uniquely determined by the equation. Summarizing the above, we now have proved the statements (1) and (2) of Theorem 3.1.

It remains to verify the asymptotic property (20). Let  $U[\lambda\nu]$  be the nonnegative solution of the equation (14) with  $\nu$  replaced by  $\lambda\nu$ , then

$$|\lambda^{-1}U[\lambda\nu] - G_D\nu|(x) = \Pi_x \int_0^\tau \lambda^{-1}U^{1+\beta}[\lambda\nu](\xi_s)ds$$

$$\leq \Pi_x \int_0^\tau \lambda^{-1}(\lambda G_D\nu(\xi_s))^{1+\beta}ds$$

$$= \lambda^{\beta}\Pi_x \int_0^\tau (G_D\nu(\xi_s))^{1+\beta}ds.$$
(48)

Condition (18) and Fatou Lemma imply that

$$\Pi_x \int_{\tau_k}^{\tau} (G_D \nu(\xi_s))^{1+\beta} \mathrm{d}s \to 0, \quad k \to \infty.$$

Noticing that for  $n \ge n_k$ ,  $G_D \nu_n$  is uniformly bounded in  $D_k$ , then it follows that

$$\Pi_x \int_0^\tau (G_D \nu(\xi_s))^{1+\beta} \mathrm{d}s < \infty.$$

Let  $\lambda \downarrow 0$  in (48), it follows that

$$\limsup_{\lambda \downarrow 0} |\lambda^{-1} U[\lambda \nu] - G_D \nu|(x) \le \lim_{\lambda \downarrow 0} \lambda^{\beta} \Pi_x \int_0^{\tau} (G_D \nu(\xi_s))^{1+\beta} \mathrm{d}s = 0.$$

Therefore we conclude that

$$\lambda^{-1}U[\lambda\nu](\cdot) \xrightarrow{p} G_D\nu(\cdot)(\lambda \to 0) \quad \text{in } D.$$

But  $\lambda^{-1}U[\lambda\nu](\cdot)$  is dominated by  $G_D\nu(\cdot)$  and  $G_D\nu(\cdot)$  is bounded in any compact subset K of  $D \setminus N_{\nu}$ , the statement (3) follows.

**Proof of Theorem 3.2** Using an argument similar to that of the proof of Theorem 2.2, we can prove the results of Theorem 3.2. hold. We omit the details.

**Proof of Theorem 3.3** We need only to prove that for every  $\nu \in M_0(D)$ , condition (18) holds. For  $x \in D \setminus N_{\nu}$  and any integer k, from the proof of Theorem 3.1 we know that, there exists an integer  $n_k$  such that, for  $n \ge n_k$ ,  $G_D\nu_n(\cdot)$  is uniformly bounded in  $D_k$ . Then

$$\lim_{n\to\infty} \prod_x \int_0^{\tau_k} (G_D \nu_n(\xi_s))^{1+\beta} \mathrm{d}s < \infty.$$

Consequently, condition (18) is satisfied if

$$\lim_{n \to \infty} \Pi_x \int_0^\tau (G_D \nu_n(\xi_s))^{1+\beta} \mathrm{d}s = \Pi_x \int_0^\tau (G_D \nu(\xi_s))^{1+\beta} \mathrm{d}s < \infty,$$

that is,

$$\lim_{n \to \infty} \int_D G_D(x, y) (G_D \nu_n(y))^{1+\beta} dy = \int_D G_D(x, y) (G_D \nu(y))^{1+\beta} dy < \infty.$$
(49)

From the dominated convergence theorem,

$$\lim_{n\to\infty}\int_{D_k}G_D(x,y)(G_D\nu_n(y))^{1+\beta}\mathrm{d}y=\int_{D_k}G_D(x,y)(G_D\nu(y))^{1+\beta}\mathrm{d}y<\infty.$$

It is sufficient to prove

$$\sup_{n\geq 1} \int_{D\setminus D_k} G_D(x,y) (G_D\nu_n(y))^{1+\beta} \mathrm{d}y \to 0, \quad \text{as } k \to \infty.$$
(50)

Without loss of generality, we can assume that  $x \in D_k, k \ge 1$ . Then there exists a constant C such that  $G_D(x, y) \le C, y \in D \setminus D_k$ . Hence it is sufficient to show

$$\sup_{n\geq 1} \int_{D\setminus D_k} (G_D\nu_n(y))^{1+\beta} \mathrm{d}y \to 0, \quad k\to\infty.$$
(51)

Put  $g_n(x) = G_D \nu_n(x), \alpha_n(\lambda) = \int_{D \cap (G_D \nu_n > \lambda)} \mathrm{d}y$ . For M > 0, we have

$$\int_{D\setminus D_k} (G_D \nu_n(y))^{1+\beta} \mathrm{d}y \le M^{1+\beta} \int_{D\setminus D_k} \mathrm{d}y + \int_{D\cap (g_n > M)} g_n^{1+\beta}(y) \mathrm{d}y, \tag{52}$$

and

$$\int_{D\cap(g_n>M)} g_n^{1+\beta}(y) \mathrm{d}y = -\int_M^\infty \lambda^{1+\beta} \mathrm{d}\alpha_n(\lambda).$$
(53)

Then we have the estimate

$$\lambda \alpha_{n}(\lambda) \leq \int_{D \cap (g_{n} > \lambda)} g_{n}(y) dy = \int_{D} \nu_{n}(dy_{1}) \int_{D \cap (g_{n} > \lambda)} G_{D}(y, y_{1}) dy$$
  
$$\leq C \sup_{y_{1} \in D} \int_{D \cap (g_{n} > \lambda)} G_{D}(y, y_{1}) dy.$$
(54)

Choose  $a > 1 + \beta$ , from the Hölder inequality, we have

$$\int_{D\cap(g_n>\lambda)} G_D(y,y_1) \mathrm{d}y \le (B(y_1))^{\frac{1}{a}} (\alpha_n(\lambda))^{\frac{1}{b}},$$

where  $B(y_1) = \int_D G_D(y, y_1)^a dy$ ,  $\frac{1}{a} + \frac{1}{b} = 1$ . Then from (54), it follows that

$$\lambda \alpha_n(\lambda) \leq C \sup_{y_1 \in D} (B(y_1))^{\frac{1}{a}} (\alpha_n(\lambda))^{\frac{1}{b}}.$$

Using the estimate of the Green function in [3] and [4], we can conclude that when  $d > \alpha$ ,

$$B(y_1) = \int_D G_D(y, y_1)^a \mathrm{d}y \le \int_D C\left(\frac{1}{|y - y_1|^{d - \alpha}}\right)^a \mathrm{d}y \le \int_0^{\mathrm{diam}D} Cr^{a(\alpha - d) + d - 1} \mathrm{d}r,$$

where diam *D* is the diameter of *D*. Since  $d < \alpha + \alpha/\beta$ , we can choose  $a > 1 + \beta$  such that  $\int_0^{\operatorname{diam } D} Cr^{a(\alpha-d)+d-1} \mathrm{d}r < \infty$ . When  $d = \alpha = 1$ ,

$$\begin{split} B(y_1) &= \int_D G_D(y,y_1)^a \mathrm{d}y \leq \int_D C |\ln \frac{1}{|y-y_1|}|^a \mathrm{d}y \leq \int_0^{\mathrm{diam}D} C |\ln r|^a \mathrm{d}r \\ &= \int_0^1 C (-\ln r)^a \mathrm{d}r + \int_1^{\mathrm{diam}D} C (\ln r)^a \mathrm{d}r < \infty. \end{split}$$

When  $\alpha > d = 1$ ,

$$B(y_1) = \int_D G_D(y, y_1)^a \mathrm{d}y \le \int_D C|y - y_1|^{a(\alpha - 1)} \mathrm{d}y \le \int_0^{\mathrm{diam}D} Cr^{a(\alpha - 1)} \mathrm{d}r < \infty.$$

Thus we conclude that in any dimension  $d < \alpha + \alpha/\beta$ ,

 $\lambda \alpha_n(\lambda) \leq C[\alpha_n(\lambda)]^{rac{1}{b}}, \qquad \lambda > 0, \quad n \geq 1,$ 

that is,

$$\alpha_n(\lambda) \le C\lambda^{-a}, \qquad \lambda > 0, \quad n \ge 1.$$
(55)

Since  $a > 1 + \beta$ , by integration by parts we have

$$-\int_{M}^{\infty} \lambda^{1+\beta} \mathrm{d}\alpha_{n}(\lambda) = M^{1+\beta}\alpha_{n}(M) + (1+\beta)\int_{M}^{\infty} \alpha_{n}(\lambda)\lambda^{\beta} \mathrm{d}\lambda \leq CM^{1+\beta-a}.$$
 (56)

Combining (52), (53) and (56), we have

$$\int_{D \setminus D_k} (G_D \nu_n(y))^{1+\beta} \mathrm{d}y \le M^{1+\beta} \int_{D \setminus D_k} \mathrm{d}y + C M^{1+\beta-a}.$$
(57)

Letting  $k \to \infty, M \to \infty$  in the above inequality, we conclude that (51) holds.

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