A NUMERICAL METHOD FOR COMPUTING SINGULAR MINIMIZERS

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§1. Introduction

The main purpose of this paper is to discuss a numerical method, of which a truncation method is a special case, for computing singular minimizers of integrals in the calculus of variations. The idea of trying to find a particular method for detecting singular minimizers is motivated by the so called Lavrentiev phenomenon [1 - 5].

Consider the problem of minimizing

$$I(u) = \int_0^1 (u^3 - x)^2 (u')^6 \, dx \tag{1.1}$$

in the set of admissible functions

$$\mathbf{A} = \{ u \in W^{1,1}(0,1) : u(0) = 0, u(1) = 1 \}$$
(1.2)

It is easy to see that the unique minimizer of I in \mathbf{A} is $\hat{u} = x^{1/3}$ and that $I(\hat{u}) = 0$. It was shown by Manià [2] that the Lavrentiev phenomenon occurs in the problem, i.e.

$$\inf_{u \in \mathbf{A} \cap W^{1,\infty}(0,1)} I(u) > \inf_{u \in \mathbf{A}} = I(\hat{u}) = 0$$
(1.3)

Furthermore, Ball & Mizel [3] showed that if $p \ge 3/2$

$$\lim_{i \to \infty} I(u_i) = \infty \tag{1.4}$$

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for any sequence of functions $u_i \in \mathbf{A} \cap W^{1,p}(0,1)$ converging almost everywhere to \hat{u} . It is easily seen from (1.3) and (1.4) that any numerical method based on a sufficiently accurate computation of $I(u_i)$ for Lipschitz functions u_i will fail both to locate \hat{u} and to produce the correct minimum value of Iin \mathbf{A} .

The existing numerical methods, which can avoid Lavrentiev phenomenon and detect singular minimizers, can be found in [4,6]. To apply truncation methods to compute singular minimizers was suggested by J.M.Ball.

In this paper, a numerical method with a more general form, which includes truncation methods as special cases, is described (§3). As a theoretical base of the method, some lower semicontinuity theorems [7] are given in §2. Approximation properties and convergence theorems of the method are established in §3. In §4, I describe 2 truncation methods as examples of the method given in §3. In §5, I show the results of a numerical example.

\S **2.** Lower semicontinuity theorems

Let $\Omega \subset \mathbb{R}^n$ be bounded and open.

Definition 2.1. A function $f: \Omega \times \mathbb{R}^m \times \mathbb{R}^k \to \mathbb{R}$ is a Carathéodory function if

- (1) $f(\cdot, u, P)$ is measurable for every $u \in \mathbb{R}^m, P \in \mathbb{R}^k$,
- (2) $f(x, \cdot, \cdot)$ is continuous for almost every $x \in \Omega$.

Throughout the rest of this paper \rightarrow denotes the weak convergence of sequences. The following theorems are special cases, where u and P are related by P = Du, of a general lower semicontinuity theorem given by Li [7].

Theorem 2.1. Let $f: \Omega \times R^m \times R^{m \times n} \to R$ satisfy

- (i) f(x, u, P) is a Carathéodory function;
- (ii) $f(x, u, P) \ge a(x), a(x) \in L^1(\Omega);$
- (iii) $f(x, u, \cdot)$ is convex.

Let $f_M : \Omega \times \mathbb{R}^m \times \mathbb{R}^{m \times n} \to \mathbb{R}$ satisfy

- (a) $f_M(x, u, P)$ are Carathéodory functions;
- (b) $f_M(x, u, P) \ge a(x), \quad a(x) \in L^1(\Omega);$
- (c) There exists a sequence of compact subsets Ω_l in Ω such that

$$\lim_{l \to \infty} meas \ (\Omega \setminus \Omega_l) = 0$$

and

$$f_M \longrightarrow f$$
, uniformly on $\Omega_l \times G$,

for each l and any compact set G in $\mathbb{R}^m \times \mathbb{R}^{m \times n}$. Let $\{u_M\}, u \in W^{1,p}(\Omega; \mathbb{R}^m), 1 \leq p \leq \infty$ be such that

$$u_M \rightharpoonup u, \quad in \quad W^{1,p}(\Omega; \mathbb{R}^m).$$
 (2.1)

Then

$$I(u) \le \underline{\lim}_{M \to \infty} I_M(u_M), \tag{2.2}$$

where

$$I(u) = \int_{\Omega} f(x, u, Du) \, dx,$$
$$I_M(v) = \int_{\Omega} f_M(x, v, Dv) \, dx.$$

Theorem 2.2. Let f satisfy (i) - (iii) in theorem 2.1. Let $\{f_M\}$ satisfy (a), (b) in theorem 2.1 and

(c') There exists a sequence of compact subsets Ω_l in Ω such that

$$\lim_{l\to\infty} meas \ (\Omega\setminus\Omega_l)=0$$

and

$$\int_{\Omega_l \setminus E(v,K)} |f_M(x,v,Dv) - f(x,v,Dv)| \, dx \longrightarrow 0, \quad uniformly \ in \ W^{1,p}(\Omega;R^m),$$

for each l and any fixed K > 0, where $E(v, K) = \{x \in \Omega : |v| > K, or |Dv| > K\}.$

Let $\{u_M\}, u \in W^{1,p}(\Omega; \mathbb{R}^m), 1 \le p \le \infty$, satisfy

$$u_M \rightharpoonup u$$
, in $W^{1,p}(\Omega; \mathbb{R}^m)$.

Then

$$I(u) \le \underline{\lim}_{M \to \infty} I_M(u_M).$$

\S **3.** The method and its properties

Assume for simplicity that $\Omega \subset \mathbb{R}^n$ is a polyhedron and $\partial \Omega_0 \subset \partial \Omega$, where $\partial \Omega$ is the boundary of Ω , consists of faces of the polyhedron. Let T_h be regular triangulations of Ω with h being the mesh size [8]. Let

$$A(u_0; \partial \Omega_0) = \{ u \in W^{1,p}(\Omega; R^m) : u = u_0, \text{ on } \partial \Omega_0 \};$$

$$A_h = \{ u \in C(\bar{\Omega}) : u \text{ is a polynomial of degree } k \text{ on } K, \forall K \in T_h \};$$

$$A_h(u_{0h}; \partial \Omega_0) = \{ u \in A_h : u = u_{0h} \text{ on } \partial \Omega_0 \},$$

where $u_{0h} \in A_h$ satisfy

$$u_{0h} \longrightarrow u_0, \text{ in } W^{1,p}(\Omega; \mathbb{R}^m).$$
 (3.1)

Our method for computing the minimizers of $I(u) = \int_{\Omega} f(x, u, Du) dx$ in $A(u_0; \partial \Omega_0)$ is to solve the finite problem of minimizing $I_M(u_h) = \int_{\Omega} f_M(x, u_h, Du_h) dx$ in $A_h(u_{0h}; \partial \Omega_0)$ for properly chosen f_M and h.

Lemma 3.1. Let $f: \Omega \times R^m \times R^{m \times n} \to R$ satisfy

- (i) f(x, u, P) is a Carathéodory function;
- (ii) $f(x, u, P) \ge a(x), a(x) \in L^1(\Omega);$

Let $f_M: \Omega \times \mathbb{R}^m \times \mathbb{R}^{m \times n} \to \mathbb{R}$ satisfy

- (a) $f_M(x, u, P)$ are Carathéodory functions;
- (b) $a(x) \leq f_M(x, u, P) \leq \min\{f(x, u, P), b_M(x) + a_M(x)(|u|^p + |P|^p)\},\$ where $a(x), b_M(x) \in L^1(\Omega), a_M(x) \in L^{\infty}(\Omega) \text{ and } 1 \leq p \leq \infty;$
- (c'') For any $v \in W^{1,p}(\Omega; \mathbb{R}^m)$

$$f_M(x, v, Dv) \longrightarrow f(x, v, Dv),$$
 in measure,

i.e. for any $\epsilon > 0$

meas
$$\{x \in \Omega : |f_M(x, v, Dv) - f(x, v, Dv)| \ge \epsilon\} \to 0$$
, as $M \to \infty$.

Let $u \in A(u_0; \partial \Omega_0)$ be such that $f(x, u(x), Du(x)) \in L^1(\Omega)$. Let $u_h \in A_h(u_{0h}; \partial \Omega_0)$ be such that

$$u_h \longrightarrow u, \quad in \ W^{1,p}(\Omega; \mathbb{R}^m).$$
 (3.2)

Then, for any $\epsilon > 0$, there exist $M(\epsilon) > 0$ and $h(\epsilon, M) > 0$ such that

$$|I_M(u_h) - I(u)| < \epsilon, \quad for \ M > M(\epsilon) \ and \ 0 < h < h(\epsilon, M).$$
(3.3)

Proof.

$$I_M(u_h) - I(u)$$

= $\int_{\Omega} (f_M(x, u_h, Du_h) - f_M(x, u, Du)) dx$
+ $\int_{\Omega} (f_M(x, u, Du) - f(x, u, Du)) dx$
= $I_1 + I_2$

It follows from $f(x, u(x), Du(x)) \in L^1(\Omega)$ and $a(x) \in L^1(\Omega)$ that for any $\epsilon > 0$ there exists $\delta(\epsilon) > 0$ such that

$$\int_{\Omega'} \left| f(x,u(x),Du(x)) \right| \, dx < \epsilon,$$

and

$$\int_{\Omega'} |a(x)| \, dx < \epsilon,$$

for any $\Omega' \subset \Omega$ with $meas(\Omega') < \delta(\epsilon)$.

On the other hand, let

$$\Omega_M(\epsilon) = \{x \in \Omega : |f_M(x, u(x), Du(x)) - f(x, u(x), Du(x))| > \epsilon/(8 \ meas(\Omega))\}.$$

Then, by (c''), for any $\epsilon > 0$ and $\delta > 0$ there exists $M(\epsilon, \delta) > 1$ such that

 $meas(\Omega_M(\epsilon)) < \delta, \quad \forall M \ge M(\epsilon, \delta).$

Now, by taking $M(\epsilon) = M(\epsilon/8, \delta(\epsilon/8))$ and by using the fact (see (b)) that

$$|f_M(x, u(x), Du(x))| \le |a(x)| + |f(x, u(x), Du(x))|,$$

we have

$$|I_2| \leq \int_{\Omega_M(\epsilon)} (|a(x)| + 2 |f(x, u(x), Du(x))|) dx + \int_{\Omega \setminus \Omega_M(\epsilon)} |f_M(x, u, Du) - f(x, u, Du)| dx \leq 4 \cdot \epsilon/8 = \epsilon/2, \quad \forall M \geq M(\epsilon).$$
(3.4)

We claim that for any $\epsilon > 0$ and M > 0 there exists $h(\epsilon, M) > 0$ such that

$$|I_1| < \epsilon/2, \quad \forall 0 < h \le h(\epsilon, M). \tag{3.5}$$

Suppose otherwise. Then, there would be $\epsilon_0 > 0, M_0 > 0$ and a decreasing sequence $\{h_j\}$ with $\lim_{j\to\infty} h_j = 0$ such that

$$|\int_{\Omega} (f_{M_0}(x, u_{h_j}, Du_{h_j}) - f_{M_0}(x, u, Du)) \, dx| \ge \epsilon_0/2, \quad \forall j$$

By (3.2), we may assume

$$u_{h_j} \longrightarrow u$$
, almost everywhere in Ω ,
 $Du_{h_j} \longrightarrow Du$, almost everywhere in Ω .

Thus by (a)

$$f_{M_0}(x, u_{h_j}, Du_{h_j}) \to f_{M_0}(x, u, Du), \text{ almost everywhere in } \Omega.$$
 (3.6)

On the other hand, by (b)

$$|f_{M_0}(x, u_{h_j}, Du_{h_j}) - f_{M_0}(x, u, Du)| \le b_{M_0}(x) + a_{M_0}(x)(|u_{h_j}|^p + |u|^p + |Du_{h_j}|^p + |Du|^p).$$
(3.7)

By (3.2), the right hand side of (3.7) is uniformly integral continuous. Hence by (3.6) and (3.7),

$$|I_1| \longrightarrow 0$$
, as $j \to \infty$.

This is a contradiction.

(3.3) now follows from (3.4) and (3.5). \Box

As a direct corollary of lemma 3.1, we have

Theorem 3.1. Let f, f_M satisfy the hypotheses in lemma 3.1. Then, for any $\epsilon > 0$, there exist $M(\epsilon) > 0$ and $h(\epsilon, M) > 0$ such that

$$\inf_{u_h \in A_h(u_{0h};\partial\Omega_0)} I_M(u_h) < \inf_{u \in A(u_0;\partial\Omega_0)} I(u) + \epsilon,$$

for $M \ge M(\epsilon), 0 < h \le h(\epsilon, M).$

Now, we can prove the following convergence theorem for the method.

Theorem 3.2. Let $1 . Let <math>f : \Omega \times R^m \times R^{m \times n} \to R$ satisfy

- (i) f(x, u, P) is a Carathéodory function;
- (ii) $f(x, u, P) \ge a(x), a(x) \in L^1(\Omega);$
- (iii) $f(x, u, \cdot)$ is convex.

Let $f_M: \Omega \times \mathbb{R}^m \times \mathbb{R}^{m \times n} \to \mathbb{R}$ satisfy

- (a) $f_M(x, u, P)$ are Carathéodory functions;
- (b) $a(x) \leq f_M(x, u, P) \leq \min\{f(x, u, P), b_M(x) + a_M(x)(|u|^p + |P|^p)\},\$ where $a(x), b_M(x) \in L^1(\Omega), a_M(x) \in L^{\infty}(\Omega);$
- (c') There exists a sequence of compact subsets Ω_l in Ω such that

$$\lim_{l\to\infty} meas \ (\Omega\setminus\Omega_l)=0$$

and

$$\int_{\Omega_l \setminus E(v,K)} |f_M(x,v,Dv) - f(x,v,Dv)| \, dx \longrightarrow 0,$$

uniformly in $W^{1,p}(\Omega; \mathbb{R}^m)$

for each l and any fixed K > 0, where $E(v, K) = \{x \in \Omega : |v| > K, or |Dv| > K\}$.

Let $\{\epsilon_j\}$ be a decreasing sequence satisfying $\lim_{j\to\infty} \epsilon_j = 0$. Let $M_j = M(\epsilon_j)$ and $h_j = h(\epsilon_j, M_j)$, where $M(\epsilon_j)$ and $h(\epsilon_j, M_j)$ are valued by theorem 3.1. Let $u_{h_j} \in A_{h_j}(u_{0h_j}; \partial\Omega_0)$ be such that

$$I_{j}(u_{j}) = \int_{\Omega} f_{M_{j}}(x, u_{j}, Du_{j}) \, dx < \inf_{v \in A_{h_{j}}(u_{0h_{j}}; \partial\Omega_{0})} I_{j}(v) + \epsilon_{j}, \qquad (3.8)$$

and

$$u_{0h_j} \longrightarrow u_0, \quad in \ W^{1,p}(\Omega; \mathbb{R}^m).$$
 (3.9)

Assume $\{u_j\}$ are uniformly bounded in $W^{1,p}(\Omega; \mathbb{R}^m)$, i.e. there is a constant C > 0 such that

$$\|u_j\|_{1,p} \le C, \quad \forall j. \tag{3.10}$$

Then, there exists a function $u \in A(u_0; \partial \Omega_0)$ and a subsequence of $\{u_j\}$, again denoted $\{u_j\}$, such that

$$u_j \rightharpoonup u, \quad in \ W^{1,p}(\Omega; \mathbb{R}^m),$$

$$(3.11)$$

and

$$I(u) = \inf_{v \in A(u_0; \partial \Omega_0)} I(v) = \underline{\lim}_{j \to \infty} I_j(u_j).$$
(3.12)

Proof. It is a classical result that (3.11) holds for a function $u \in W^{1,p}(\Omega; \mathbb{R}^m)$. From (3.9), it follows that $u = u_0$ on $\partial\Omega_0$, i.e. $u \in A(u_0; \partial\Omega_0)$.

By theorem 2.2, we have

$$I(u) \le \underline{\lim}_{j \to \infty} I_j(u_j). \tag{3.13}$$

It follows from (c') that f_M also satisfy (c'') in lemma 3.1. Hence by theorem 3.1, we have

$$\underline{\lim}_{j \to \infty} I_j(u_j) \le \inf_{v \in A(u_0; \partial \Omega_0)} I(v).$$
(3.14)

Combining (3.13) and (3.14), we have (3.12).

Remark. If (c') is replaced by (c) in theorem 3.2, the conclusion of the theorem still holds.

§4. Truncation methods

To apply the results in §2 and §3, we need to find an appropriate sequence of functions $\{f_M\}$. We may use the truncation method to construct such sequences.

Let 1 and define

$$\bar{f}_M(x, u, P) = \begin{cases} f(x, u, P), & \text{if } |u| \le M \text{ and } |P| \le M; \\ f(x, u_M, P_M) + \alpha_M(x)(\chi^p_M(|u|) + \chi^p_M(|P|)), \text{ otherwise}, \end{cases}$$

where

$$u_{M} = \begin{cases} u, & \text{if } |u| \leq M; \\ \frac{M}{|u|}u, & \text{if } |u| > M, \end{cases}$$
$$P_{M} = \begin{cases} P, & \text{if } |P| \leq M; \\ \frac{M}{|P|}P, & \text{if } |P| > M, \end{cases}$$
$$\chi_{M}^{p}(t) = \begin{cases} 0, & \text{if } t \leq 0; \\ t^{p} - M^{p}, & \text{if } t > 0, \end{cases}$$

and

$$\alpha_M \in L^{\infty}, \quad \alpha_M(x) \ge c > 0, \ \forall x \in \Omega$$

$$(4.1)$$

Define

$$f_M^1(x, u, P) = \min\{f(x, u, P), \bar{f}_M(x, u, P)\}.$$
(4.2)

Let $\{\bar{\alpha}_M\}$ be an increasing sequence satisfying

$$\bar{\alpha}_1 \ge c > 0, \lim_{M \to \infty} \bar{\alpha}_M = \infty \tag{4.3}$$

Define

$$f_M^2(x, u, P) = \min\{f(x, u, P), \bar{\alpha}_M(1 + |P|^p)\}.$$
(4.4)

Lemma 4.1. Let $f: \Omega \times R^m \times R^{m \times n} \to R$ satisfy

- (i) f(x, u, P) is a Carathéodory function;
- (ii) $f(x, u, P) \ge a(x), a(x) \in L^1(\Omega);$
- (iii) $f(x, u, \cdot)$ is convex.

(iv) Let
$$g_K(x) = \sup_{|u| \le K, |P| \le K} |f(x, u, P)|$$
. Then $g_K(\cdot) \in L^1(\Omega)$.

Then, f_M^i , i = 1, 2, defined by (4.2) and (4.4) respectively, satisfy

- (a) $f_M^i(x, u, P)$ are Carathéodory functions;
- (b) $\bar{a}(x) \leq f_M^i(x, u, P) \leq \min\{f(x, u, P), b_M(x) + a_M(x)(|u|^p + |P|^p)\},\$ where $\bar{a}(x), b_M(x) \in L^1(\Omega), a_M(x) \in L^\infty(\Omega), a_M(x) \geq c > 0,\$ *a.e.* in Ω .

and furthermore f_M^1 satisfy

(c) There exists a sequence of compact sets Ω_l in Ω such that

$$\lim_{l \to \infty} meas \ (\Omega \setminus \Omega_l) = 0$$

and

$$f_M^1 \longrightarrow f$$
, uniformly on $\Omega_l \times G$

for each l and any compact set $G \in \mathbb{R}^m \times \mathbb{R}^{m \times n}$;

 f_M^2 satisfy

(c') There exists a sequence of compact sets Ω_l in Ω such that

$$\lim_{l \to \infty} meas \ (\Omega \setminus \Omega_l) = 0$$

and

$$\int_{\Omega_l \setminus E(v,K)} |f_M^2(x,v,Dv) - f(x,v,Dv)| \, dx \longrightarrow 0,$$

uniformly in $W^{1,p}(\Omega; \mathbb{R}^m),$

for each l and any fixed K > 0 where $E(v, K) = \{x \in \Omega : |v| > K, or |Dv| > K\}.$

Proof. (a) is obvious.

For i = 1, take $\bar{a}(x) = a(x), b_M(x) = g_M(x)$ (see (iv)) and $a_M(x) = \alpha_M(x)$. For i = 2, take $\bar{a}(x) = \min\{a(x), \alpha_1\}$, and $a_M(x) = b_M(x) = \bar{\alpha}_M$. Then, it is easy to check that (b) holds.

It is obvious that (c) is satisfied by f_M^1 , since $f_M(x, u, P) = f(x, u, P)$ for all $x \in \Omega$, $|u| \leq M$ and $|P| \leq M$.

Now we show that (c') is satisfied by f_M^2 .

For any $\epsilon > 0$ and K > 1, it follows from (iv) that there exist C(K) > 0and $\delta(\epsilon, K) > 0$ such that

$$\int_{\Omega} g_K(x) \le C(K), \tag{4.5}$$

and

$$\int_{\Omega'} g_K(x) \le \epsilon, \ \forall \Omega' \subset \Omega \quad \text{with } meas \ (\Omega') < \delta(\epsilon, K), \tag{4.6}$$

where g_K is defined as in (iv).

For any $\delta > 0$ and K > 1, it follows from (4.5) that there exists $A(K, \delta) > 1$ such that

$$meas (G(K, A)) < \delta, \quad \forall A \ge A(K, \delta), \tag{4.7}$$

where $G(K, A) = \{x \in \Omega : g_K(x) > A\}.$

By (4.3), for any A > 0 there exists M(A) > 1 such that

$$\bar{\alpha}_M \ge A, \quad \forall M \ge M(A).$$
 (4.8)

By (4.4) and (4.8),

$$f_M^2(x, v(x), Dv(x)) = f(x, v(x), Dv(x)),$$

$$\forall x \in \Omega \setminus G(K, A), \text{ and } \forall M \ge M(A).$$

(4.9)

Thus, by taking $\delta = \delta(\epsilon, K)$, $A = A(\epsilon, K) = A(K, \delta(\epsilon, K))$, and $M(\epsilon, K) = M(A(\epsilon, K))$ and by (4.4), (4.6), (4.7) and (4.9), we have

$$\int_{\Omega \setminus E(v,K)} |f_M^2(x,v,Dv) - f(x,v,Dv)| dx$$

$$= \int_{(\Omega \setminus E(v,K)) \cap G(K,A)} |f_M^2(x,v,Dv) - f(x,v,Dv)| dx$$

$$\leq 2 \int_{(\Omega \setminus E(v,K)) \cap G(K,A)} |f(x,v,Dv)| dx$$

$$\leq 2 \int_{G(K,A)} g_K(x) dx$$

$$< 2 \epsilon, \quad \forall M \ge M(\epsilon,K) \quad \text{and} \quad v \in W^{1,p}(\Omega;R^m). \tag{4.10}$$

(4.10) implies that f_M^2 satisfy (c'). \Box

By lemma 4.1, we know that all the results in §2 and §3 remain valid if f_M is substituted by f_M^1 defined by (4.2) or f_M^2 defined by (4.4).

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Let Ω , $\partial \Omega_0$ and T_h be the same as in §3. Let

$$A = \{ u \in W^{1,1}(\Omega; \mathbb{R}^m) : u = 0, \text{ on } \partial\Omega_0 \},$$

$$A_h = \{ u \in C(\overline{\Omega}) : u \text{ is a polynomial of degree} \le k \text{ on each element in } T_h,$$

$$u = 0 \text{ on } \partial\Omega_0 \}$$

Suppose $\hat{u} \in W^{1,p}(\Omega; \mathbb{R}^m), p > 1$, is a minimizer of

$$I(u) = \int_{\Omega} f(x, u, Du) \ dx$$

in A. Let

$$L = 1 + |\hat{u}|_{1,p}^p, \tag{4.11}$$

$$A_h(L) = \{ u \in A_h : \int_{\Omega} |Du|^p \, dx \le L \}.$$
(4.12)

Theorem 4.1. Let $f: \Omega \times \mathbb{R}^m \times \mathbb{R}^{m \times n} \to \mathbb{R}$ satisfy

- (i) f(x, u, P) is a Carathéodory function;
- (ii) $f(x, u, P) \ge a(x), a(x) \in L^1(\Omega);$
- (iii) $f(x, u, \cdot)$ is convex.
- (iv) Let $g_K(x) = \sup_{|u| \le K, |P| \le K} |f(x, u, P)|$. Then $g_K(\cdot) \in L^1(\Omega)$.

Let f_M^i , i = 1, 2, be defined by (4.2) and (4.4) respectively. Let $\{\epsilon_j\}$ be a decreasing sequence with $\lim_{j\to\infty} \epsilon_j = 0$. We have

(1) There exist a nonincreasing function $M(\epsilon) > 0$ and a function $h(\epsilon, M)$ with $h(\cdot, M)$ nondecreasing and $h(\epsilon, \cdot)$ nonincreasing such that

 $\inf_{v \in A_h(L)} I^i_M(v) < I(\hat{u}) + \epsilon_j, \quad for \ M \ge M(\epsilon_j), \ 0 < h \le h(\epsilon_j, M), \quad (4.13)$

where

$$I_M^i(v) = \int_\Omega f_M^i(x, v, Dv) \ dx.$$

(2) Let $M_j \ge M(\epsilon_j)$, $0 < h_j \le h(\epsilon_j, M_j)$. Let $u_j^i \in A_{h_j}(L)$ be minimizers of $I_{M_j}^i$ in $A_{h_j}(L)$. Then there exist functions $\bar{u}^i \in A \cap W^{1,p}(\Omega; \mathbb{R}^m)$ and subsequences of $\{u_j^i\}_{j=1}^\infty$, again denoted by $\{u_j^i\}_{j=1}^\infty$, such that

$$u_j^i \rightharpoonup \bar{u}^i, \quad in \ W^{1,p}(\Omega; \mathbb{R}^m),$$

and

$$I(\bar{u}^i) = \inf_{u \in A} I(u) = \underline{\lim}_{j \to \infty} I^i_{M_j}(u^i_j).$$

Proof. (1) follows from a similar argument as in lemma 3.1. (2) follows from a similar argument as in theorem 3.2. \Box

Remark. The arguments in the proof of lemma 4.1 show that the conclusions in lemma 4.1 and theorem 4.1 for f_M^1 hold without the hypothesis (iv).

Remark. Comparing the truncation method presented here with the element removal method [6], we see that both methods replaced the fast growth part of the integrand by certain slower growth functions so that the Lavrentiev phenomenon can be avoided. The difference is that in the element removal method the substitution is taken to be zero, while in the truncation method the truncation functions themselves, even though their growth is to a certain degree under control, still grow fast.

§5. Numerical example

I now apply the truncation method to the following 2-D problem, which is motivated by the 1-D problem of minimizing (1.1) in (1.2).

Take $\Omega = (-1, 1) \times (0, 1)$, and

$$f(x, y, u, u'_x, u'_y) = h(x, y)((u^3 - x)^2 (u'_x)^6 + (u'_y)^2),$$

where

$$h(x,y) = \begin{cases} a y^2 |x|^{3-b y^2}, & \text{if } y \in (0,0.3); \\ 1, & \text{if } y \in [0.3,0.7]; \\ a (1-y)^2 |x|^{3-b (1-y)^2}, & \text{if } y \in (0.7,1), \end{cases}$$

with a = 100/9, b = 100/3. Here h(x, y) is so defined that for y near either 0 or 1 the value of h(x, y) goes to zero faster than x^2 . This guarentees that the Lavrentiev phenonmenon still occurs in the problem.

Take

$$\mathbf{A} = \{ u \in W^{1,1}(\Omega) : u(\pm 1, y) = \pm 1; u(x, y) = x, \text{ on } y = 0 \text{ and } y = 1 \}.$$

Take $f_M = f_M^2$ defined by (4.4) with $\alpha_M = 10^{-3}M, p = 1.2$.

For M = 10, devide Ω into rectangulars by introducing lines

$$x_i = -1 + \frac{i}{10}, 1 \le i < 20;$$

 $y_j = \frac{j}{10}, 1 \le j < 10.$

Bilinear elements are used to construct the finite element function space \mathbf{A}_h . The numerical results of the truncation method and the standard finite element method are shown in Figure-1 and Figure-2 respectively.

For M = 20, devide Ω into rectangulars by introducing lines

$$\begin{aligned} x_i &= -1 + \frac{i}{10}, \quad 1 \le i < 8; \\ x_9 &= -0.13, x_{10} = -0.08, x_{11} = -0.04, x_{12} = -0.02, \\ x_{13} &= -0.01, x_{14} = 0.0, x_{15} = 0.01, x_{16} = 0.02, \\ x_{17} &= 0.04, \quad x_{18} = 0.08, x_{19} = 0.13, \\ x_i &= 0.2 + \frac{i - 20}{10}, \quad 20 \le i < 28; \\ y_j &= \frac{j}{10}, \quad 1 \le j < 10. \end{aligned}$$

Bilinear elements are used to construct the finite element function space \mathbf{A}_h . The numerical results of the truncation method and the standard finite element method are shown in Figure-3 and Figure-4 respectively.

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