# Lecture 10 Random Walk and Brownian motion * 

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## 1 1D Symmetric Random Walk

Example 1. (1D Random Walk) Suppose a particle suffers displacements along a straight line from the origin, denote its position $X_{n} \in \mathbb{Z}$. Let $\xi_{i}$ are i.i.d. random moves such that $\xi_{i}= \pm 1$ with probability $\frac{1}{2}$, and let

$$
X_{n}=\xi_{1}+\xi_{2}+\ldots+\xi_{n} \quad\left(\text { i.e. } \quad X_{0}=0\right)
$$

$\left\{X_{n}\right\}$ is called a unconstrained symmetric random walk on $\mathbb{Z}$. Given $X_{n}=i$, we have

$$
\begin{aligned}
P\left\{X_{n+1}=i \pm 1 \mid X_{n}=i\right\} & =\frac{1}{2} \\
P\left\{X_{n+1}=\text { anything else } \mid X_{n}=i\right\} & =0
\end{aligned}
$$

It is a typical example of the simplest Markov chains.

After taking $N$ steps, the particle could be at any of the points

$$
-N,-N+2, \ldots, \ldots, N-2, N
$$

### 1.1 Distribution of $X_{N}$

One basic question is the probability $W(m, N)=\operatorname{Prob}\left\{X_{N}=m\right\}$ that the particle arrives at the point $m$ after suffering $N$ displacements.

It is not difficult to find that $W(m, N)$ obeys binomial distribution

$$
W(m, N)=\frac{N!}{\left(\frac{N+m}{2}\right)!\left(\frac{N-m}{2}\right)!}\left(\frac{1}{2}\right)^{N}
$$

and it is easy to note that $m$ can be odd or even only according as N is odd or even.
The expectation position and mean square deviation are

$$
\mathbb{E} X_{N}=0, \quad \mathbb{E} X_{N}^{2}=N
$$

then the root mean square displacement is $\sqrt{N}$.

[^0]Definition 1. (Diffusion coefficient) The $1 D$ diffusion coefficient $D$ is defined as

$$
D=\frac{\left\langle\left(X_{N}-X_{0}\right)^{2}\right\rangle}{2 N}
$$

It is assumed $\mathbb{E} X_{N}=X_{0}$ here. In general continuous case, it is defined as

$$
D=\lim _{t \rightarrow \infty} \frac{\left\langle\left(X_{t}-X_{0}\right)^{2}\right\rangle}{2 d t}
$$

where $d$ is the space dimension.

For this simplest random walk, $D=\frac{1}{2}$.
Next we consider the case $N, m \gg 1$, and $m \ll N$ since we will rescale the process with the relation $x=m l, t=N \tau$ and $l \sim \mathcal{O}(\sqrt{\tau}), \tau \rightarrow 0$. Thus $m / N=x / t \cdot \tau / l \rightarrow 0$. So only the range $m \ll N$ matters. By Stirling's formula

$$
\log n!=\left(n+\frac{1}{2}\right) \log n-n+\frac{1}{2} \log 2 \pi+O\left(n^{-1}\right) \quad(n \rightarrow+\infty)
$$

we have

$$
\begin{aligned}
\log W(m, N) \approx & \left(N+\frac{1}{2}\right) \log N-\frac{1}{2}(N+m+1) \log \left[\frac{N}{2}\left(1+\frac{m}{N}\right)\right] \\
& -\frac{1}{2}(N-m+1) \log \left[\frac{N}{2}\left(1-\frac{m}{N}\right)\right]-\frac{1}{2} \log 2 \pi-N \log 2
\end{aligned}
$$

Since $m \ll N$ we have Taylor series expansion for $x \ll 1$

$$
\log (1+x)=x-\frac{1}{2} x^{2}+O\left(x^{3}\right)
$$

thus

$$
\log W(m, N) \approx-\frac{1}{2} \log N+\log 2-\frac{1}{2} \log 2 \pi-\frac{m^{2}}{2 N}+O\left(\left(\frac{m}{N}\right)^{2}\right)
$$

In other words, one obtains the the asymptotic formula

$$
W(m, N) \approx\left(\frac{2}{\pi N}\right)^{\frac{1}{2}} \exp \left(-\frac{m^{2}}{2 N}\right)
$$

An interesting thing is to take the continuum limit of random walk. Now suppose we rescale the random walk with the spatial steplength $l$ and the time spacing $\tau$ for each movement, we take the limit in the following sense when considering the point $(x, t)$

$$
\begin{equation*}
N, m \rightarrow \infty, \quad l, \tau \rightarrow 0, \text { and } \quad N \tau=t, m l=x \tag{1}
\end{equation*}
$$

To make the continuum limit physically reasonable, we also ask to fix the diffusion coefficient

$$
D=\frac{\left\langle\left(X_{N \tau}-X_{0}\right)^{2}\right\rangle}{2 N \tau}=\frac{l^{2}}{2 \tau}
$$

in the limit. Consider the intervals $\Delta x$ which are large compared with the length $l$, we have the probability that $y \in(x-\Delta x / 2, x+\Delta x / 2)$ for the continuous probability density $W(x, t)$ satisfies

$$
W(x, t) \Delta x \approx \int_{x-\Delta x / 2}^{x+\Delta x / 2} W(y, t) d y \approx \sum_{\substack{m^{\prime} \in\{m, m \pm 2, m \pm 4, \ldots\} \\ m^{\prime} l \in(x-\Delta x / 2, x+\Delta x / 2)}} W\left(m^{\prime}, N\right) \approx W(m, N) \frac{\Delta x}{2 l} \quad(x=m l)
$$

since $m$ can take only even or odd values depending on whether $N$ is even or odd. Combining the results above one has

$$
W(x, t) \Delta x=\frac{1}{\sqrt{2 \pi t \frac{l^{2}}{\tau}}} \exp \left(-\frac{x^{2}}{2 t \frac{l^{2}}{\tau}}\right) \Delta x
$$

thus the limiting probability density at time $t$

$$
W(x, t)=\frac{1}{\sqrt{4 \pi D t}} \exp \left(-\frac{x^{2}}{4 D t}\right)
$$

### 1.2 Random walk with reflecting and absorbing Barriers

Case 1: A reflecting barrier at $m=m_{1}$;
Suppose $m_{1}>0$ We now ask the probability $W\left(m, N ; m_{1}\right)$ that the particle will arrive at $m\left(\leq m_{1}\right)$ after $N$ steps.

This problem may be solved very efficiently in the $(m-N)$ plane in a neat way.


Figure 1: Schematics of reflection principle.

From Fig. 1, the actual sample paths are shown with solid lines (including the reflected path), and the paths crossing the barrier $m_{1}$ in the unrestricted random walk case are shown with dashed lines. These paths can be classified into two classes. One class only contains the paths not hitting $m_{1}$ and finally reaching $m$; the other class contains the paths hitting $m_{1}$ before time $N$ and finally reaching $m_{1}$ or $2 m_{1}-m$. We have the following two assertions on these paths:

- In the unrestricted random walk, all of the sample paths have equal probability $1 / 2^{N}$;
- The probability of the reflected paths which hits $m_{1}$ is equal to the sum of the probability of the paths hitting $m_{1}$ and reaching $m$ and the paths reaching $2 m_{1}-m$. A simple argument to prove this is to observe that the reflecting probability is 1 at the reflection point shown as points 1 and 2 in the
figure. From $1=1 / 2+1 / 2$, this decomposition actually decompose the paths into those go leftwards and rightwards with equal probability, which corresponds to all the paths just stated.
- The number of the paths hitting $m_{1}$ and hitting $m$ finally is equal to that of the paths hitting $2 m_{1}-m$ finally. This can be understood because these paths have to cross $m_{1}$ and we can denote the final hitting time as $N_{2}$ as shown in the figure. So after $N_{2}$, the paths go leftwards or rightwards with mirror symmetry to hit $m$ or $2 m_{1}-m$. Before $N_{1}$, the paths can be either branch.

These assertions are called the reflection principle, which is the basis of the following calculations for reflection and absorbing barrier problem.

So we have the following identity

$$
W_{r}\left(m, N ; m_{1}\right)=W(m, N)+W\left(2 m_{1}-m, N\right)
$$

If we take large $N$ limit we have

$$
W_{r}\left(m, N ; m_{1}\right) \approx\left(\frac{2}{\pi N}\right)^{\frac{1}{2}}\left[\operatorname { e x p } \left(-\frac{m^{2}}{2 N}+\exp \left(-\frac{\left(2 m_{1}-m\right)^{2}}{2 N}\right]\right.\right.
$$

then passing to the continuum limit we have

$$
\begin{equation*}
W_{r}\left(x, t ; x_{1}\right)=\frac{1}{\sqrt{4 \pi D t}}\left[\exp \left(-\frac{x^{2}}{4 D t}\right)+\exp \left(-\frac{\left(2 x_{1}-x\right)^{2}}{4 D t}\right)\right] \tag{2}
\end{equation*}
$$

and we may note in this case

$$
\left.\frac{\partial W_{r}}{\partial x}\right|_{x=x_{1}}=0
$$

with $W$ is defined in (2).
Case 2: Absorbing wall at $m=m_{1}$;
Similarly as before we easily deduce that

$$
W_{a}\left(m, N ; m_{1}\right)=W(m, N)-W\left(2 m_{1}-m, N\right)
$$

by reflection principle.
In the large $N$ limit we have

$$
W_{a}\left(m, N ; m_{1}\right) \approx\left(\frac{2}{\pi N}\right)^{\frac{1}{2}}\left[\exp \left(-\frac{m^{2}}{2 N}\right)-\exp \left(-\frac{\left(2 m_{1}-m\right)^{2}}{2 N}\right)\right]
$$

and the continuum limit is

$$
\begin{equation*}
W_{a}\left(x, t ; x_{1}\right)=\frac{1}{\sqrt{4 \pi D t}}\left[\exp \left(-\frac{x^{2}}{4 D t}\right)-\exp \left(-\frac{\left(2 x_{1}-x\right)^{2}}{4 D t}\right)\right] \tag{3}
\end{equation*}
$$

and we may note in this case

$$
W_{a}\left(x, t ; x_{1}\right)=0
$$

with $W_{a}$ is defined in (3).
Define the first hitting probability $a\left(m_{1}, N\right)=\operatorname{Prob}\left\{X_{N}=m_{1}\right.$, and $\left.X_{n}<m_{1}, \forall n<N\right\}$ that taking $N$ steps the particle will arrive at $m_{1}$ without ever hitting $m=m_{1}$ at any earlier step. Then we have

$$
a\left(m_{1}, N\right)=\frac{1}{2} W_{a}\left(m_{1}-1, N-1 ; m_{1}\right)=\frac{m_{1}}{N} W\left(m_{1}, N\right)
$$

by the above formula and the relation $W(m, N)=\frac{N}{N+m} W(m-1, N-1)$. In the large $N$ limit we have

$$
a\left(m_{1}, N\right) \approx \frac{m_{1}}{N}\left(\frac{2}{\pi N}\right)^{\frac{1}{2}} \exp \left(-\frac{m_{1}^{2}}{2 N}\right)
$$

The continuous probability density $a\left(m_{1}, t\right)$ becomes

$$
a\left(m_{1}, t\right) \Delta t \approx a\left(m_{1}, N\right) \frac{\Delta t}{2 \tau} \quad(t=N \tau)
$$

In the continuum limit one obtains

$$
a\left(x_{1}, t\right)=\frac{x_{1}}{t} \frac{1}{\sqrt{4 \pi D t}} \exp \left(-\frac{x_{1}^{2}}{4 D t}\right)
$$

We may note in this case

$$
a\left(x_{1}, t\right)=-\left.D \frac{\partial W}{\partial x}\right|_{x=x_{1}}
$$

with $W$ is defined in (3).

## 2 Arcsine law and the law of iterated logarithm

To simplify the notations, we define the first hitting time

$$
\sigma_{2 n}=\min \left\{1 \leq k \leq 2 n: S_{k}=0\right\}
$$

and we define $\sigma_{2 n}=+\infty$ if $S_{k} \neq 0$ for $1 \leq k \leq 2 n$. For $0 \leq k \leq n$ we define

$$
\begin{equation*}
u_{2 k}=\mathbb{P}\left(S_{2 k}=0\right), \quad f_{2 k}=\mathbb{P}\left(\sigma_{2 n}=2 k\right) \tag{4}
\end{equation*}
$$

It is clear that $u_{2 k}=C_{2 k}^{k} \cdot 2^{-2 k}$. From the reflection principle, we have

$$
\begin{equation*}
f_{2 k}=2 \frac{1}{2} \cdot \frac{1}{2 k-1} W(1,2 k-1)=\frac{1}{2 k} u_{2(k-1)}=u_{2(k-1)}-u_{2 k} \tag{5}
\end{equation*}
$$

Now define $P_{2 k, 2 n}$ be the probability that during the interval $[0,2 n]$ the particle spends $2 k$ units of time on the positive side (We say that the particle is on the positive side in the interval $[m-1, m]$ if one, at least, of the value $S_{m-1}$ and $S_{m}$ is positive).

Lemma 1. Let $u_{0}=1$ and $0 \leq k \leq n$. Then

$$
\begin{equation*}
P_{2 k, 2 n}=u_{2 k} \cdot u_{2 n-2 k} \tag{6}
\end{equation*}
$$

Proof. At first let us show that (6) holds for $k=0$. Suppose we have a path with $S_{2 n}=0$ and $\min _{0 \leq k \leq 2 n} X_{k}=-m$, where $m>0$. Denote $l=\min \left\{k \mid X_{k}=-m\right\}$. We can map this path into a path only in the positive side. Take a reflection of the path $\left\{X_{k}\right\}_{0 \leq k \leq l}$ with respect to the axis $t=l$ and denote the new path by $\left\{\tilde{X}_{k}\right\}_{0 \leq k \leq l}$ such that $\tilde{X}_{k}=X_{l-k}$. Concatenate $\tilde{X}_{0}$ to the point $(2 n, 0)$ and translate the left endpoint of the new path into the origin. With such manipulation, we get a path on the positive side and the right endpoint is $(2 n, 2 m)$. Conversely, for each path on the positive side with the right endpoint is $(2 n, 2 m)$, we take $l=\max \left\{k \mid X_{k}=m\right\}$. We can cut the part beyond $t=k$, make a reflection with respect



Figure 2: Schematics of construction from a path with $S_{2 n}=0$ to a new path on the positive side.
to $t=l$, concatenate it to the left endpoint of the rest part and translate the whole path into the origin, we then get a new path with $S_{2 n}=0$. A special case is illustrate in Figure 2. The case for $k=n$ is trivially true by symmetry and the case $k=0$.

Then let us prove the following relation

$$
\begin{equation*}
u_{2 k}=\sum_{r=1}^{k} f_{2 r} \cdot u_{2(k-r)} \tag{7}
\end{equation*}
$$

Since $\left\{S_{2 k}=0\right\} \subset\left\{\sigma_{2 n} \leq 2 k\right\}$, we have

$$
\begin{equation*}
\left\{S_{2 k}=0\right\}=\left\{S_{2 k}=0\right\} \cap\left\{\sigma_{2 n} \leq 2 k\right\}=\sum_{r=1}^{k}\left\{S_{2 k}=0\right\} \cap\left\{\sigma_{2 n}=2 r\right\} \tag{8}
\end{equation*}
$$

Consequently

$$
\begin{align*}
u_{2 k} & =\mathbb{P}\left(S_{2 k}=0\right)=\sum_{r=1}^{k} \mathbb{P}\left(S_{2 k}=0, \sigma_{2 n}=2 r\right) \\
& =\sum_{r=1}^{k} \mathbb{P}\left(S_{2 k}=0 \mid \sigma_{2 n}=2 r\right) \mathbb{P}\left(\sigma_{2 n}=2 r\right) \tag{9}
\end{align*}
$$

But

$$
\begin{align*}
& \mathbb{P}\left(S_{2 k}=0 \mid \sigma_{2 n}=2 r\right)=\mathbb{P}\left(S_{2 k}=0 \mid S_{1} \neq 0, \ldots, S_{2 r-1} \neq 0, S_{2 r}=0\right) \\
& \quad=\mathbb{P}\left(S_{2 r}+\left(\xi_{2 r+1}+\cdots+\xi_{2 k}\right)=0 \mid S_{1} \neq 0, \ldots, S_{2 r-1} \neq 0, S_{2 r}=0\right) \\
& \quad=\mathbb{P}\left(S_{2 r}+\left(\xi_{2 r+1}+\cdots+\xi_{2 k}\right)=0 \mid S_{2 r}=0\right) \\
& \quad=\mathbb{P}\left(\xi_{2 r+1}+\cdots+\xi_{2 k}=0\right)=\mathbb{P}\left(S_{2(k-r)}=0\right) \tag{10}
\end{align*}
$$

Combing (9) and (10) we obtain (7). To prove (6), we apply the induction method. Now let $1 \leq k \leq n-1$. If the particle is on the positive side for exactly $2 k$ instants, it must pass through zero. Let $2 r$ be the time of first passage through zero. There are two possibilities: either $S_{k} \geq 0, k \leq 2 r$, or $S_{k} \leq 0, k \leq 2 r$.

The number of paths of the first kind is

$$
\left(2^{2 r} \cdot \frac{1}{2} f_{2 r}\right) \cdot\left(2^{2(n-r)} \cdot P_{2(k-r), 2(n-r)}\right)=\frac{1}{2} 2^{2 n} f_{2 r} P_{2(k-r), 2(n-r)}
$$

The number of paths of the second kind is

$$
\frac{1}{2} 2^{2 n} f_{2 r} P_{2 k, 2(n-r)}
$$

Consequently, for $1 \leq k \leq n-1$,

$$
\begin{equation*}
P_{2 k, 2 n}=\frac{1}{2} \sum_{r=1}^{k} f_{2 r} P_{2(k-r), 2(n-r)}+\frac{1}{2} \sum_{r=1}^{k} f_{2 r} P_{2 k, 2(n-r)} \tag{11}
\end{equation*}
$$

Suppose that $P_{2 k, 2 m}=u_{2 k} \cdot u_{2 m-2 k}$ holds for $m=k, k+1, \ldots, n-1$. Then by (7) and (11) we have (How is the induction applied here?)

$$
\begin{aligned}
P_{2 k, 2 n} & =\frac{1}{2} u_{2 n-2 k} \sum_{r=1}^{k} f_{2 r} u_{2 k-2 r}+\frac{1}{2} u_{2 k} \sum_{r=1}^{k} f_{2 r} u_{2 n-2 k-2 r} \\
& =\frac{1}{2} u_{2 n-2 k} u_{2 k}+\frac{1}{2} u_{2 k} u_{2 n-2 k}=u_{2 k} u_{2 n-2 k}
\end{aligned}
$$

This completes the proof.

Now let $\gamma(2 n)$ be the number of time units that the particle spends on the positive axis in the interval $[0,2 n]$. Then when $x<1$,

$$
\mathbb{P}\left\{\frac{1}{2}<\frac{\gamma(2 n)}{2 n} \leq x\right\}=\sum_{k, 1 / 2<2 k / 2 n \leq x} P_{2 k, 2 n}
$$

Since

$$
u_{2 k} \sim \frac{1}{\sqrt{\pi k}}
$$

by Stirling's formula as $k \rightarrow \infty$, we have

$$
P_{2 k, 2 n} \sim \frac{1}{\pi \sqrt{k(n-k)}}
$$

as $k, n-k \rightarrow \infty$.
Therefore

$$
\sum_{\{k, 1 / 2<2 k / 2 n \leq x\}} P_{2 k, 2 n}-\sum_{k, 1 / 2<2 k / 2 n \leq x} \frac{1}{\pi n} \cdot\left[\frac{k}{n}\left(1-\frac{k}{n}\right)\right]^{-\frac{1}{2}} \rightarrow 0, \quad n \rightarrow \infty
$$

Whence

$$
\sum_{\{k, 1 / 2<2 k / 2 n \leq x\}} P_{2 k, 2 n} \rightarrow \frac{1}{\pi} \int_{\frac{1}{2}}^{x} \frac{d t}{\sqrt{t(1-t)}}, \quad n \rightarrow \infty
$$

From the symmetry,

$$
\sum_{\{k, 2 k / 2 n \leq 1 / 2\}} P_{2 k, 2 n} \rightarrow \frac{1}{2}
$$

and

$$
\frac{1}{\pi} \int_{\frac{1}{2}}^{x} \frac{d t}{\sqrt{t(1-t)}}=\frac{2}{\pi} \arcsin \sqrt{x}-\frac{1}{2}
$$

Thus we have the following theorem:
Theorem 1 (Arcsine Law). The probability that the fraction of the time spent by the particle on the positive side is at most $x$ tends to $\frac{2}{\pi} \arcsin \sqrt{x}$ :

$$
\sum_{\{k, k / n \leq x\}} P_{2 k, 2 n} \rightarrow \frac{2}{\pi} \arcsin \sqrt{x}
$$

The following deep theorem is due to Hartman and Wintler (1941).
Theorem 2 (Law of Iterated Logarithm). Let $\xi_{1}, \ldots, \xi_{n}$ are i.i.d. R.V. with $\mathbb{E} \xi_{i}=0, \operatorname{Var} \xi_{i}=\sigma^{2}>0$, Then

$$
\mathbb{P}\left\{\limsup \frac{S_{n}}{\sqrt{2 \sigma^{2} n \ln \ln n}}=1\right\}=1
$$

Remark 1. Application of the above result to $-\xi_{i}$, one also obtains

$$
\mathbb{P}\left\{\liminf \frac{S_{n}}{\sqrt{2 \sigma^{2} n \ln \ln n}}=-1\right\}=1
$$

## 3 Random Flights With Gaussian Displacements

In the general problem of random flights, the position $\boldsymbol{R}$ of the particle after $N$ displacements is given by

$$
\boldsymbol{R}=\sum_{i=1}^{N} \boldsymbol{r}_{i}
$$

where the $\boldsymbol{r}_{i}=\left(r_{i}^{1}, r_{i}^{2}, r_{i}^{3}\right)$ 's denote the different displacements. Assume the probability that the $i$ th displacement between $\boldsymbol{r}_{i}$ and $\boldsymbol{r}_{i}+d \boldsymbol{r}_{i}$ is given by

$$
\tau_{i}\left(r_{i}^{1}, r_{i}^{2}, r_{i}^{3}\right) d r_{i}^{1} d r_{i}^{2} d r_{i}^{3}=\tau_{i} d \boldsymbol{r}_{i} \quad(i=1, \ldots, N)
$$

Now we ask the probability $W_{N}(\boldsymbol{R}) d \boldsymbol{R}$ that the position of the particle after $N$ displacements lies in the interval $\boldsymbol{R}, \boldsymbol{R}+d \boldsymbol{R}$. The method presented in the following is originally devised by A.A. Markov.

It is a standard exercise to have

$$
\widehat{W_{N}(\boldsymbol{R})}=\int W_{N}(\boldsymbol{R}) \exp (i \boldsymbol{\rho} \cdot \boldsymbol{R}) d \boldsymbol{R}=\prod_{i=1}^{N} \int \tau_{i}\left(\boldsymbol{r}_{i}\right) \exp \left(i \boldsymbol{\rho} \cdot \boldsymbol{r}_{i}\right) d \boldsymbol{r}_{i}=\prod_{i=1}^{N} \widehat{\tau_{i}\left(\boldsymbol{r}_{i}\right)}
$$

In the case of Gaussian distribution of random displacement $\boldsymbol{r}_{i}$, we have the pdf

$$
\tau_{i}\left(\boldsymbol{r}_{i}\right)=\frac{1}{\left(2 \pi l^{2}\right)^{\frac{3}{2}}} \exp \left(-\frac{\left|\boldsymbol{r}_{i}\right|^{2}}{2 l^{2}}\right)
$$

From the property of Fourier transform for Gaussian distribution, we have

$$
W_{N}(\boldsymbol{R})=\frac{1}{\left(2 \pi N l^{2}\right)^{\frac{3}{2}}} \exp \left(-\frac{|\boldsymbol{R}|^{2}}{2 N l^{2}}\right)
$$

Suppose the time spacing is $\tau$ each time and define the diffusion coefficient as before

$$
D=\lim _{t \rightarrow 0} \frac{\left\langle\left(X_{t}-X_{0}\right)^{2}\right\rangle}{2 d t}=\frac{3 N l^{2}}{6 N \tau}=\frac{l^{2}}{2 \tau}
$$

Then we have the continuum limit pdf for free Gaussian random flight

$$
W(\boldsymbol{R}, t)=\frac{1}{(4 \pi D t)^{\frac{3}{2}}} \exp \left(-\frac{|\boldsymbol{R}|^{2}}{4 D t}\right) \quad(t=N \tau)
$$

Remark 2. Similar results for $W_{N}(\boldsymbol{R})$ holds for other distributions which can be refereed in [1]. These results will be further clarified in next lecture on Brownian motion.

Question 1. How about more general reflecting and absorbing barrier problem in high dimensions?

## 4 Einstein's work on the theory of Brownian motion

In 1905, A. Einstein published a seminal paper on the theory of Brownian motion (he also publishes two other seminal papers on Special Relativity and photoemission in this year). Two major points in Einstein's solution to Brownian motion are
(i) The motion is caused by the exceedingly frequent impacts on the pollen grain of the incessantly moving molecules of liquid in which it is suspended;
(ii) The motion of these molecules is so complicated that its effect on the pollen grain can only be described probabilistically in terms of exceedingly frequent statistically independent impacts.

His mathematical interpretation is as follows (1D version).
In a small time interval $\tau$, the $X$-coordinates of an individual particle will increase by an amount $\Delta$. There will be a certain "frequency law" for $\Delta$

$$
d n=n \phi(\Delta) d \Delta
$$

where

$$
\int_{-\infty}^{+\infty} \phi(\Delta) d \Delta=1, \quad \phi(-\Delta)=\phi(\Delta)
$$

and $\phi$ is only different from 0 for very small values of $\Delta$.
Let $f(x, t)$ be the number of particles per unit volume, then

$$
f(x, t+\tau) d x=\int_{-\infty}^{+\infty} f(x-\Delta, t) d x \phi(\Delta) d \Delta
$$

Since $\tau$ is small

$$
f(x, t+\tau)=f(x, t)+\frac{\partial f}{\partial t} \tau
$$

furthermore

$$
f(x-\Delta, t)=f(x, t)-\Delta \frac{\partial f}{\partial x}+\frac{\Delta^{2}}{2} \frac{\partial^{2} f}{\partial x^{2}}+\cdots
$$

Thus

$$
f(x, t)+\frac{\partial f}{\partial t} \tau=f \int_{-\infty}^{+\infty} \phi(\Delta) d \Delta+\frac{\partial f}{\partial x} \int_{-\infty}^{+\infty} \Delta \phi(\Delta) d \Delta+\frac{\partial^{2} f}{\partial x^{2}} \int_{-\infty}^{+\infty} \frac{\Delta^{2}}{2} \phi(\Delta) d \Delta+\cdots
$$

Set

$$
\frac{1}{\tau} \int_{-\infty}^{+\infty} \frac{\Delta^{2}}{2} \phi(\Delta) d \Delta=D
$$

throwing h.o.t., we have

$$
\frac{\partial f}{\partial t}=D \frac{\partial^{2} f}{\partial x^{2}}
$$

His description contains very many of the major concepts which have been developed more and more generally and rigorously since then, such as
(i) Chapman-Kolmogorov equation;
(ii) Fokker-Planck equation;
(iii) Kramers-Moyal expansion;
etc.

## 5 Homeworks

- HW1. Prove that the continuum limit pdf $W(x, t)$ for free random walk satisfies the PDE

$$
\left\{\begin{array}{l}
\frac{\partial W}{\partial t}=D \frac{\partial^{2} W}{\partial x^{2}}, \quad x \in R, t \geq 0 \\
\left.W(x, t)\right|_{t=0}=\delta(x)
\end{array}\right.
$$

- HW2. Prove that the continuum limit pdf $W(x, t)$ with reflecting barrier satisfies the PDE

$$
\left\{\begin{array}{l}
\frac{\partial W}{\partial t}=D \frac{\partial^{2} W}{\partial x^{2}}, \quad x \leq x_{1}, t \geq 0 \\
\left.W(x, t)\right|_{t=0}=\delta(x) \\
\left.\frac{\partial W}{\partial x}(x, t)\right|_{x=x_{1}}=0
\end{array}\right.
$$

- HW3. Prove that the continuum limit pdf $W(x, t)$ with absorbing barrier satisfies the PDE

$$
\left\{\begin{array}{l}
\frac{\partial W}{\partial t}=D \frac{\partial^{2} W}{\partial x^{2}}, \quad x \leq x_{1}, t \geq 0 \\
\left.W(x, t)\right|_{t=0}=\delta(x) \\
\left.W(x, t)\right|_{x=x_{1}}=0
\end{array}\right.
$$

- HW4 (optional). Give the detailed procedure for the induction in proving the Arcsine Law.


## References

[1] S. Chandrasekhar, Stochstic problems and in physics and astronomy, Rev. Mod. Phys. 15(1943), 1-89.
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