

00103335: Deep Learning and Reinforcement Learning
Homework 2 Due: November 4, 2022

Note: Unless otherwise noted, equation and figure numbers refer to those in the DL book.

1. State and prove a convergence theorem for stochastic gradient descent under conditions (8.12) and (8.13).
Hint: See Robbins and Monro (1951, *Ann. Math. Statist.*, 22, 400–407).

2. In this exercise, we establish a convergence result for gradient descent with Polyak averaging.

- (a) Let $\mathbf{v}_1, \dots, \mathbf{v}_T$ be an arbitrary sequence of vectors. For the algorithm with initialization $\mathbf{w}^{(1)} = \mathbf{0}$ and update rule

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \eta \mathbf{v}_t,$$

show that

$$\sum_{t=1}^T \langle \mathbf{w}^{(t)} - \mathbf{w}^*, \mathbf{v}_t \rangle \leq \frac{\|\mathbf{w}^*\|^2}{2\eta} + \frac{\eta}{2} \sum_{t=1}^T \|\mathbf{v}_t\|^2.$$

- (b) Let f be a convex, ρ -Lipschitz function, $\mathbf{w}^* = \arg \min_{\|\mathbf{w}\| \leq B} f(\mathbf{w})$, and $\bar{\mathbf{w}} = \sum_{t=1}^T \mathbf{w}^{(t)} / T$. Use part (a) to show that the gradient descent algorithm for minimizing f with $\eta = B/(\rho\sqrt{T})$ satisfies

$$f(\bar{\mathbf{w}}) - f(\mathbf{w}^*) \leq \frac{B\rho}{\sqrt{T}}.$$

3. Represent the convolution example in Figure 9.1 (3×4 input, 2×2 kernel, “valid” convolution) as matrix multiplication with a doubly block circulant matrix.
4. Consider the pooling example in Figure 9.9. Design a set of filters such that the max pooling unit can learn to be invariant to (a) rotation, and (b) scaling.
5. The Hopfield network is a type of recurrent network consisting of n units with states s_i and update rule

$$s_i \leftarrow \sigma \left(\sum_{j \neq i} w_{ij} s_j - \theta_i \right),$$

where $\sigma(x) = 2I(x \geq 0) - 1$, $w_{ij} = w_{ji}$, and $w_{ii} = 0$. The network is updated in an asynchronous manner, so that one unit is randomly selected and updated at each time step. Prove that the network will eventually reach a stable state at a local minimum of the energy function

$$E(\mathbf{s}) = -\frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n w_{ij} s_i s_j + \sum_{i=1}^n \theta_i s_i.$$

6. Design a recurrent neural network to approximate the dynamics of the Lorenz 96 model

$$\frac{dx_i}{dt} = (x_{i+1} - x_{i-2})x_{i-1} - x_i + F, \quad i = 1, \dots, n,$$

where F is a forcing constant and the indices are cyclic so that $x_{-1} = x_{n-1}$, $x_0 = x_n$, and $x_{n+1} = x_1$.